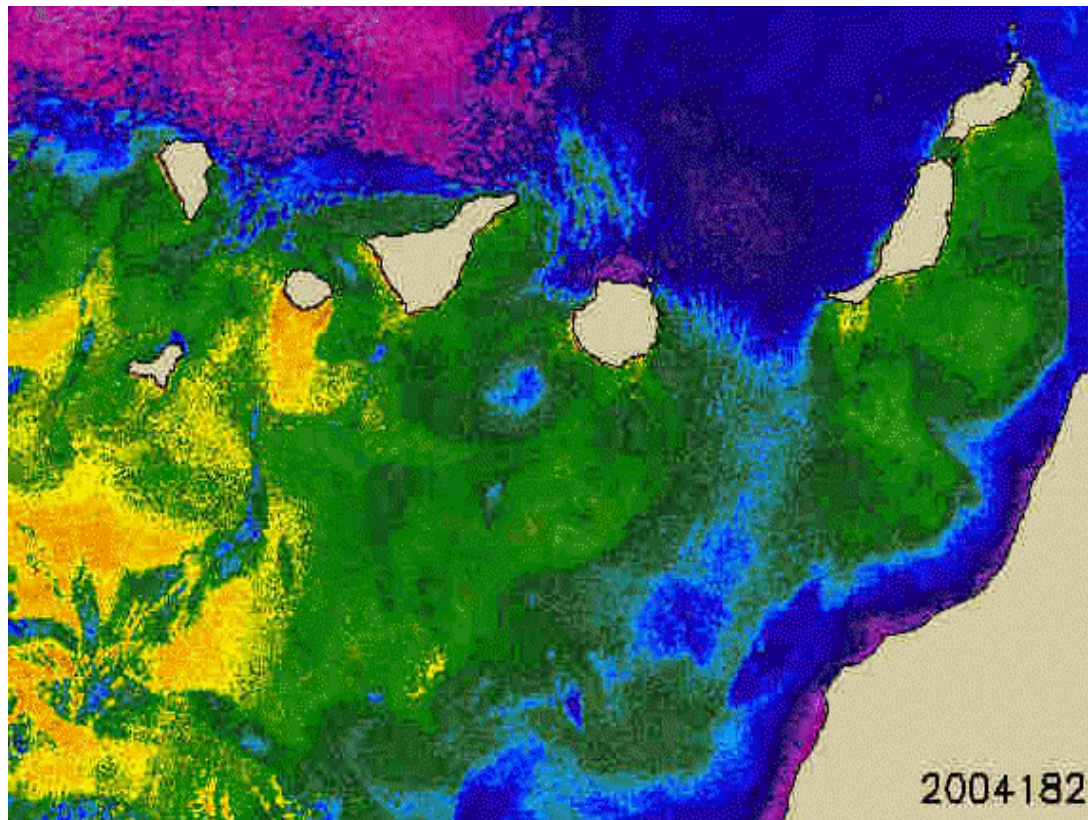




SEASnet

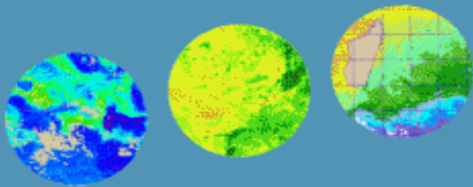
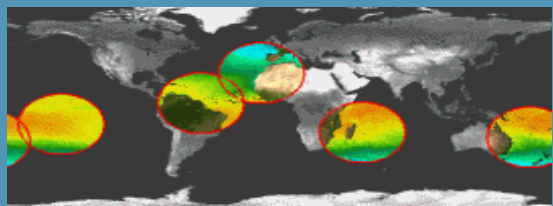
www.seasnet.org



Dr. Antonio G RAMOS *Assistant Prof* **ULPGC + UB/RU**
antonio.ramos@ulpgc.es

Div. Robotic and Computational Oceanography
University Inst. Intelligence Systems & Numeric Applications



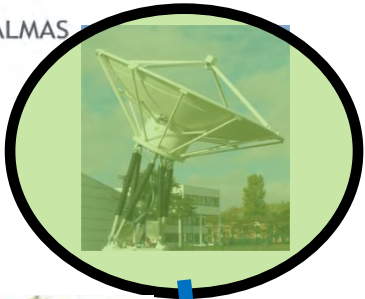


SEASnet

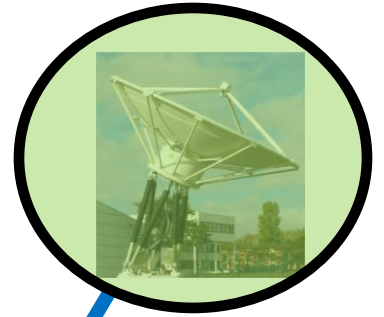
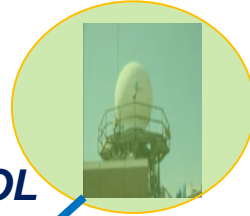
Le réseau de stations de réception de l'IRD et ses partenaires

 UNIVERSIDAD DE LAS PALMAS DE GRAN CANARIA

French Guyane, 05



RU COOL



French Polynesia, 04

Réunion, 91

Réunion I, 11

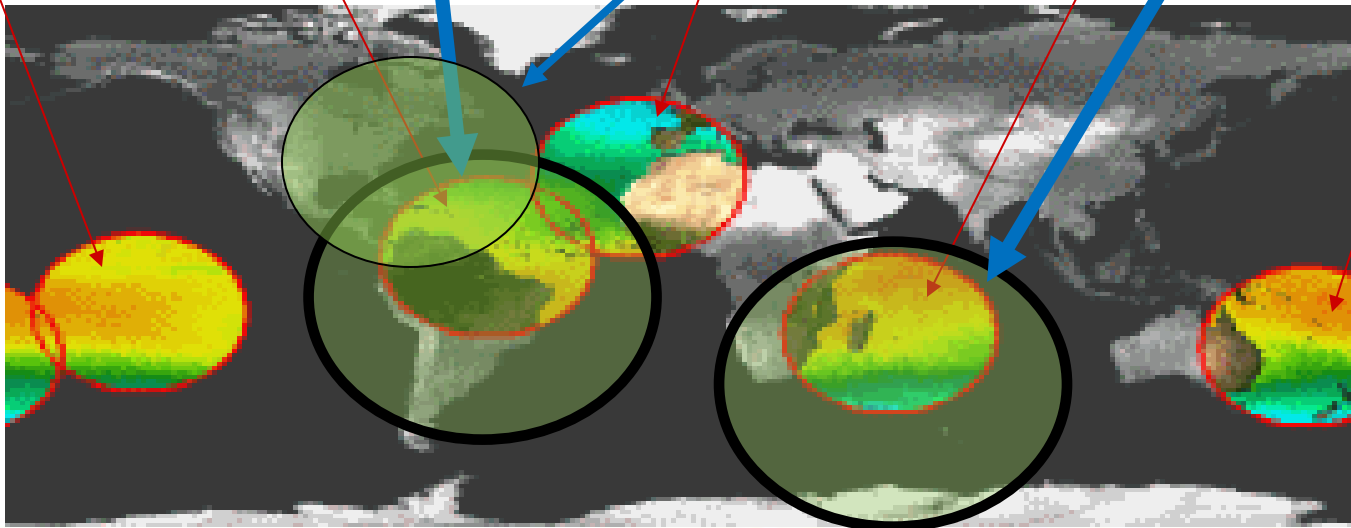
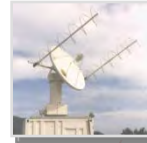
New Caledonia, 97



French Guyane, 98



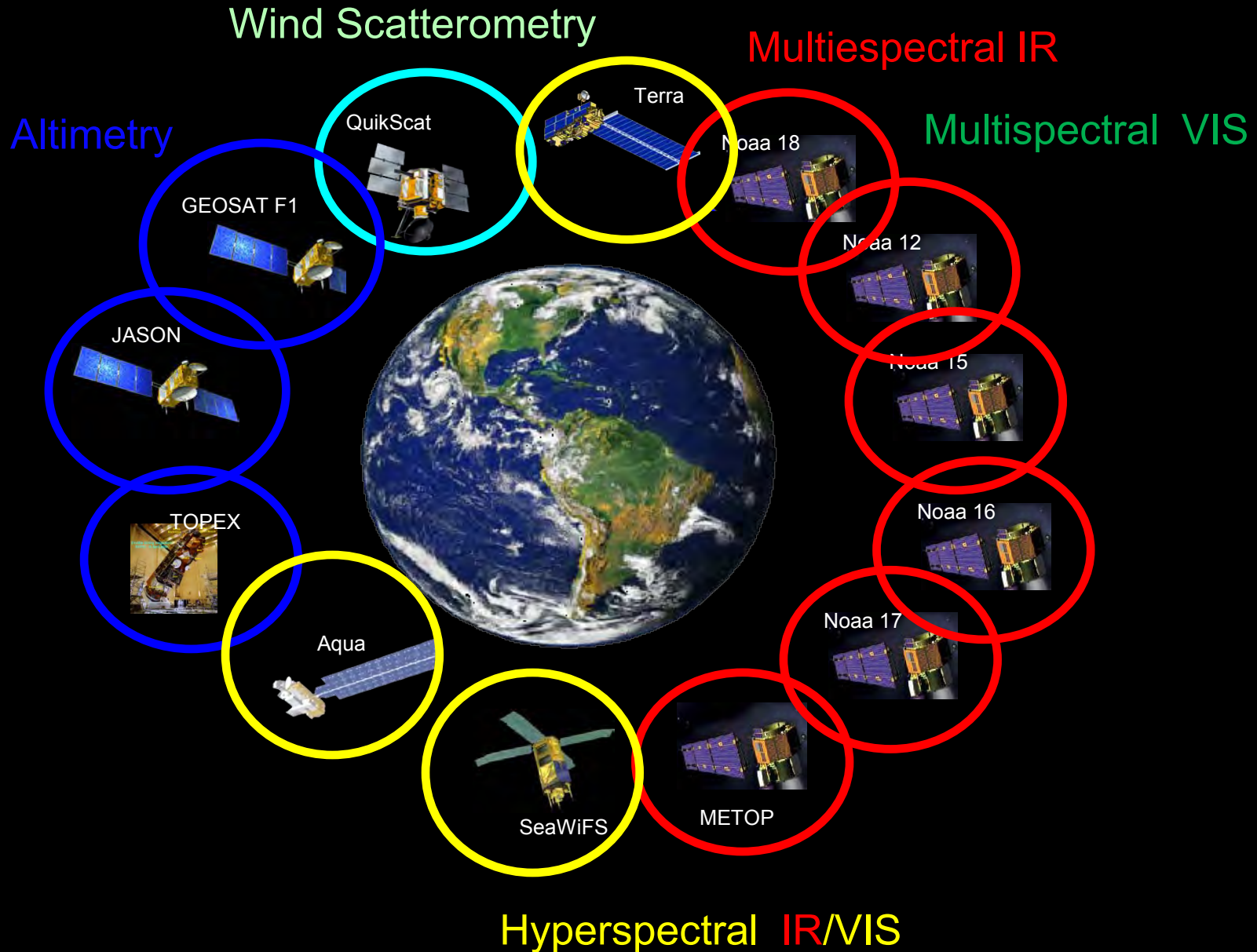
Canarias, 96

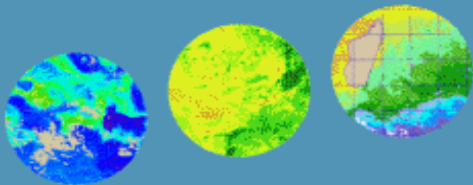
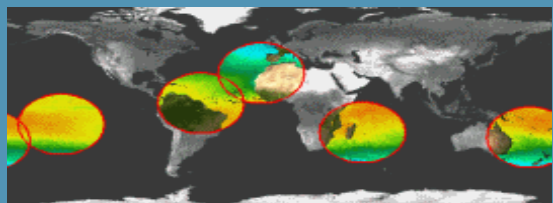


CAMPUS DE EXCELENCIA INTERNACIONAL DE ÁMBITO REGIONAL



Parque Científico Tecnológico
Universidad de Las Palmas de Gran Canaria

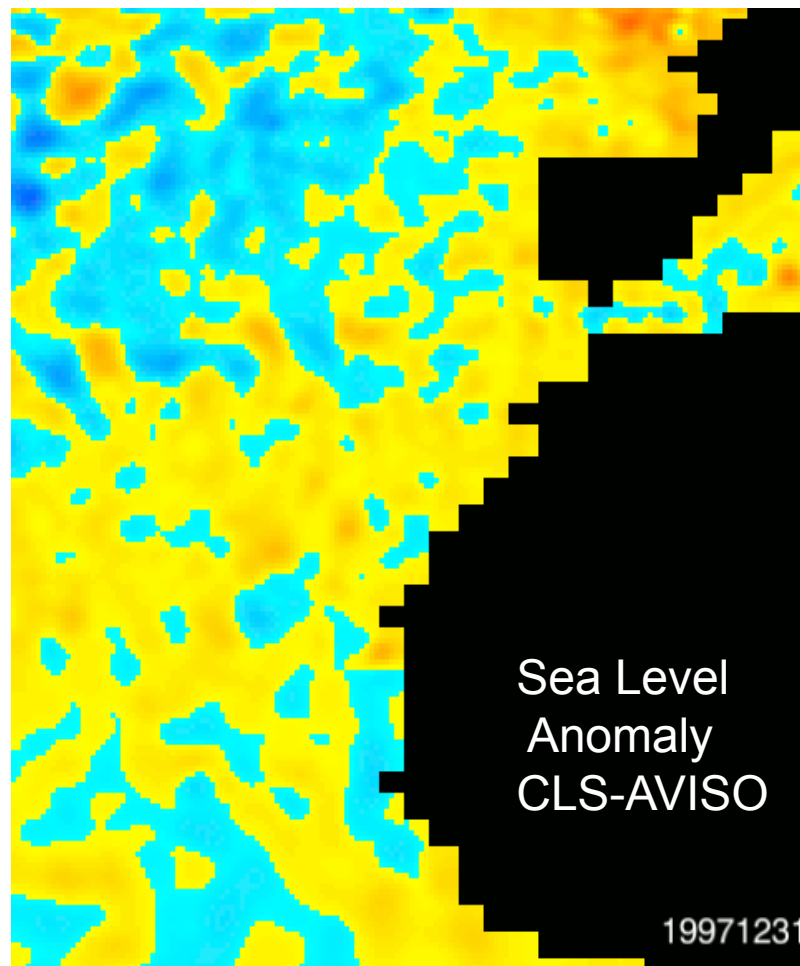
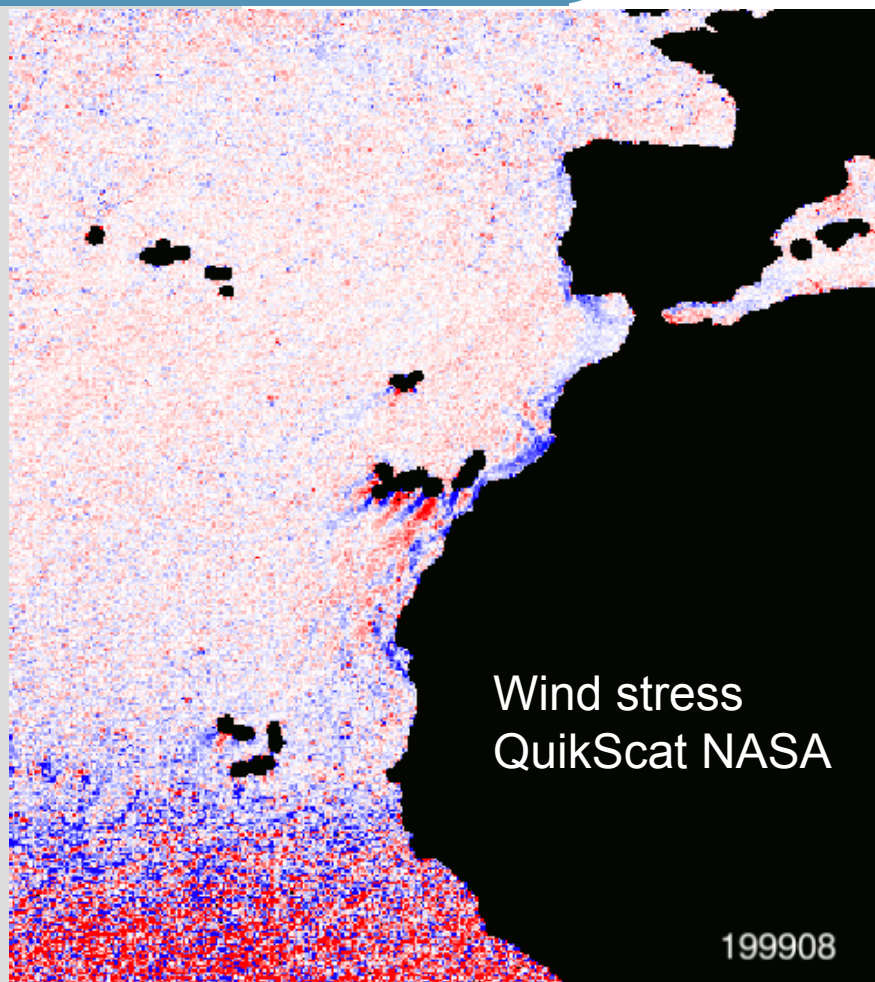


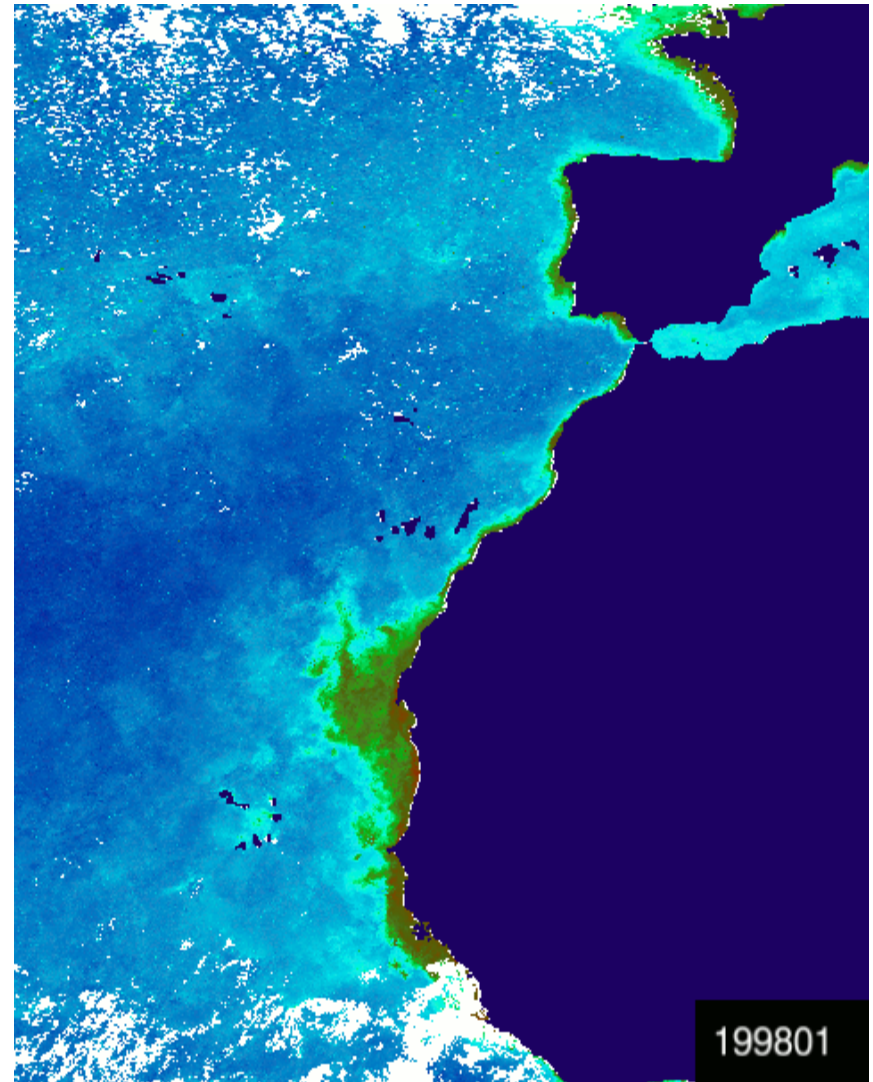


SEASnet

Réseau de stations de réception et d'exploitation de données des satellites d'observation de la Terre

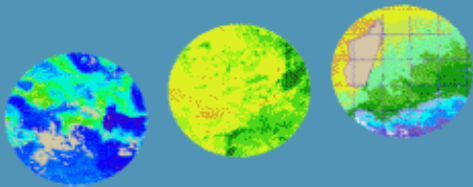
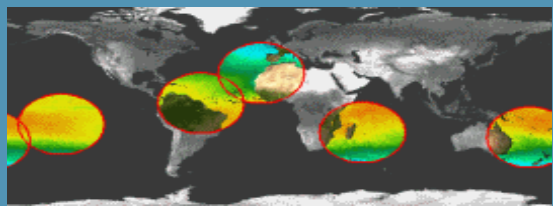
Diffusion de données





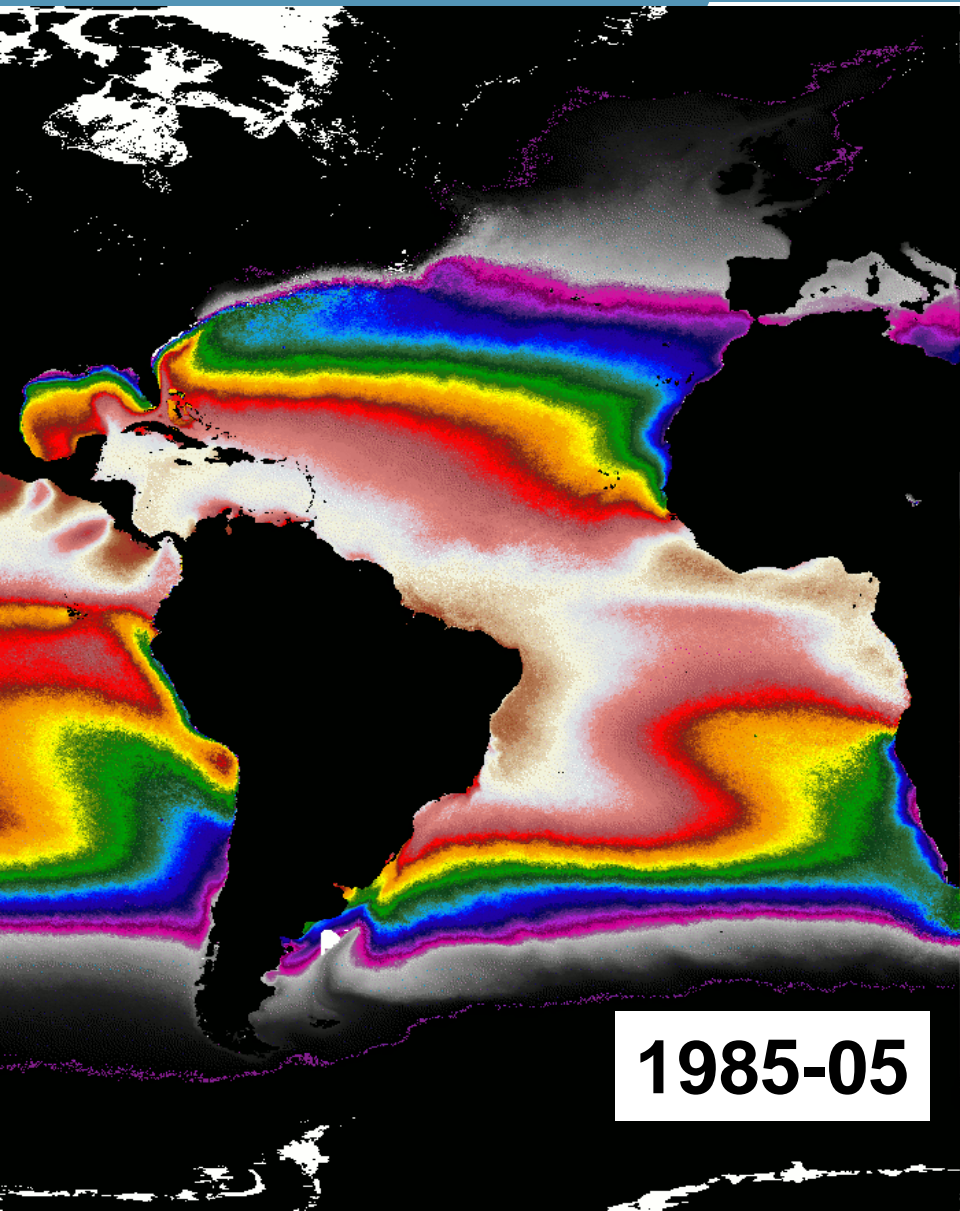
SST

Primary Production

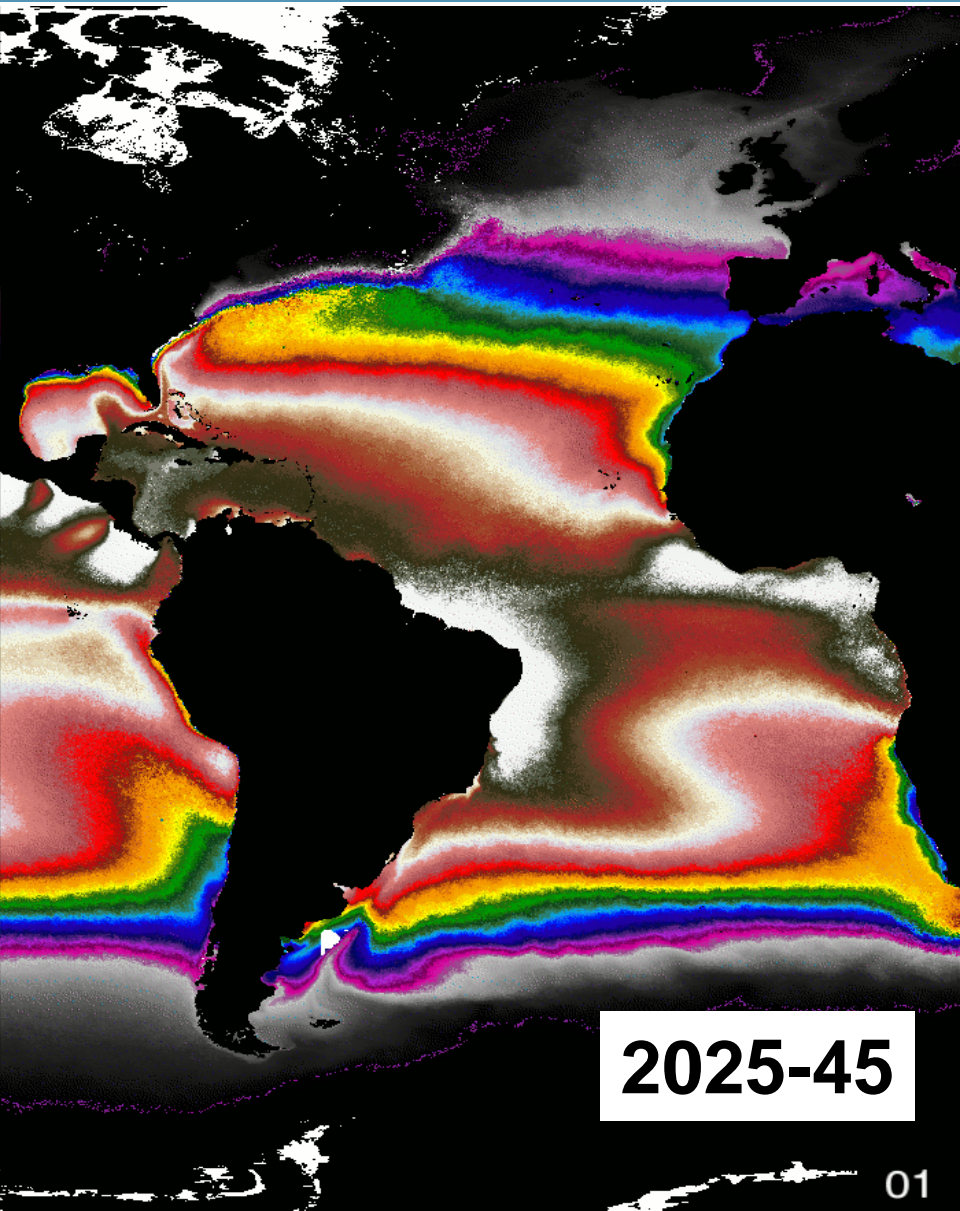


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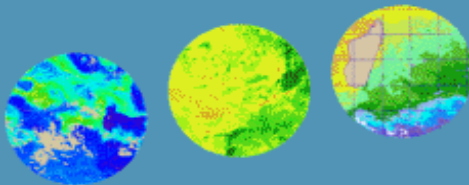
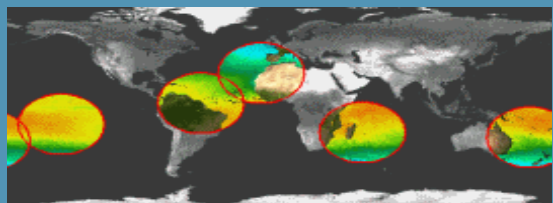
Réseau de stations de réception et
d'exploitation de données des satellites
d'observation de la Terre



1985-05



2025-45

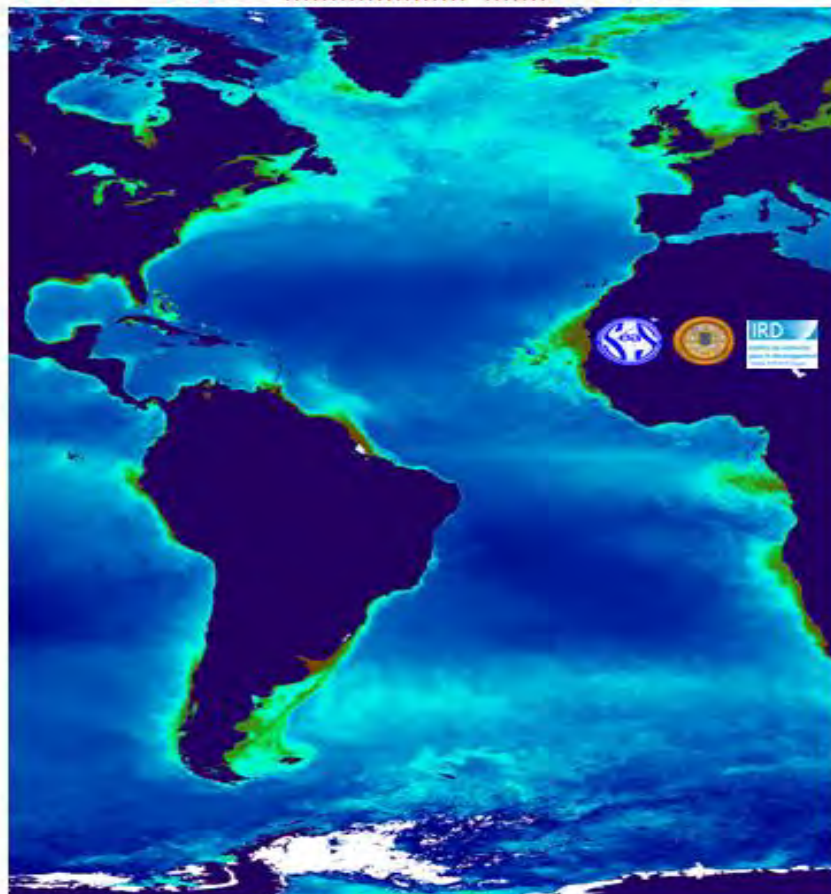


SEASnet

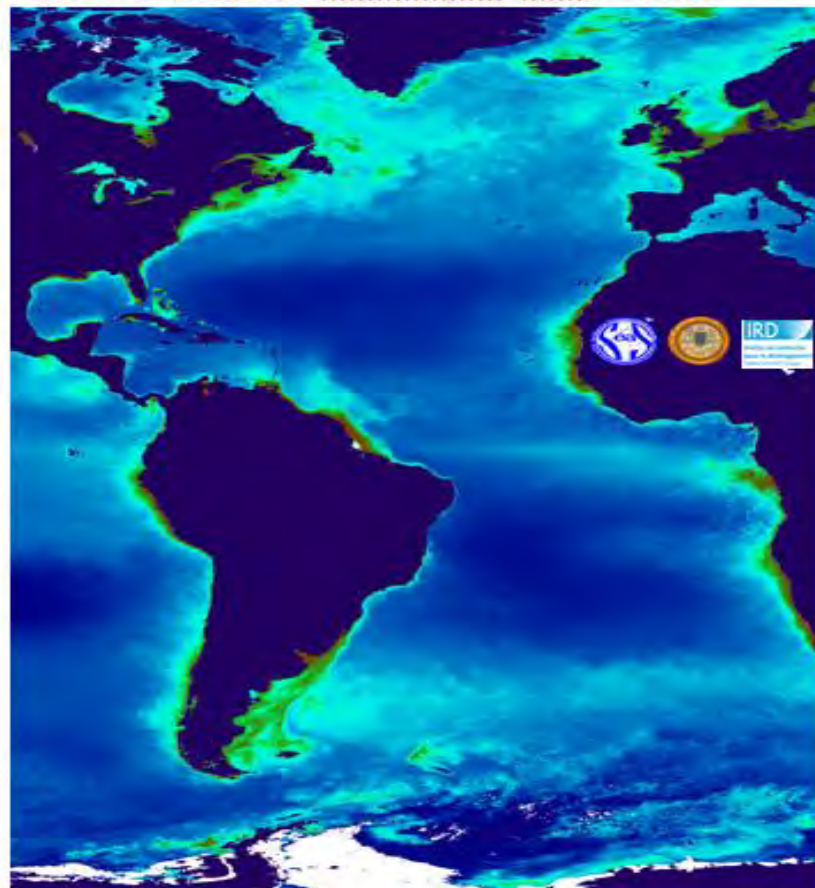
Réseau de stations de réception et d'exploitation de données des satellites d'observation de la Terre

Diffusion de données

1998. Satellite SeaWiFS/Orb-view2



2006. Satellite SeaWiFS/Orb-view2



SeaWiFS Ocean color Project
1998-2008

FLEET SITMA/ULPGC *Min. Economy & Competitiveness*

1 AUV G-500 500m
1 ASV SITMA



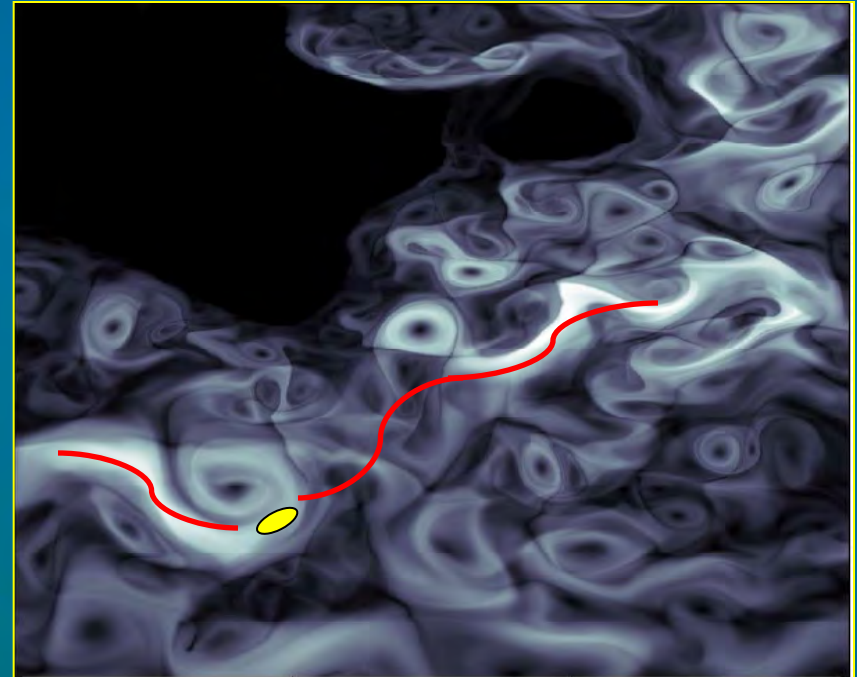
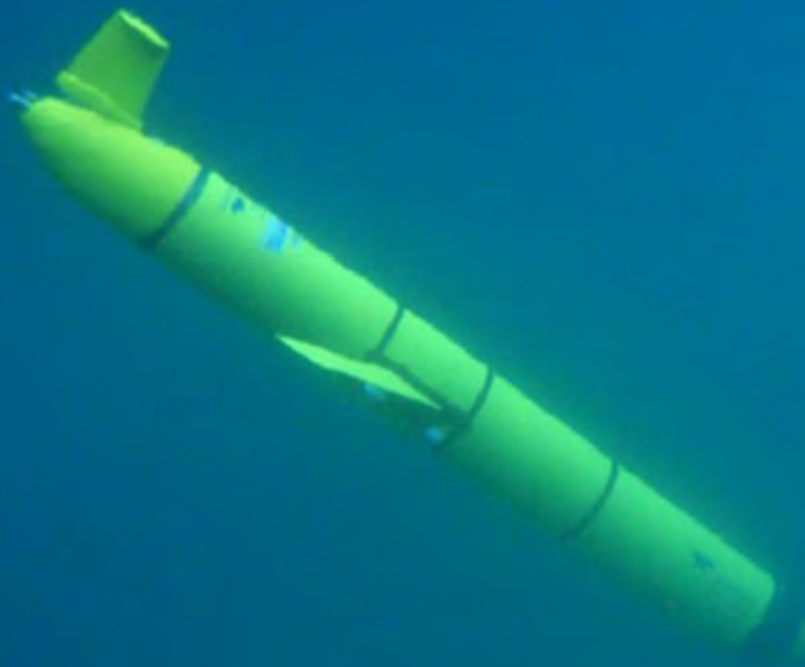
2 Glider G2 TWR

**CTD + Fluorometry + DVL +
Turbidometer + O2 + MR
turbulence**



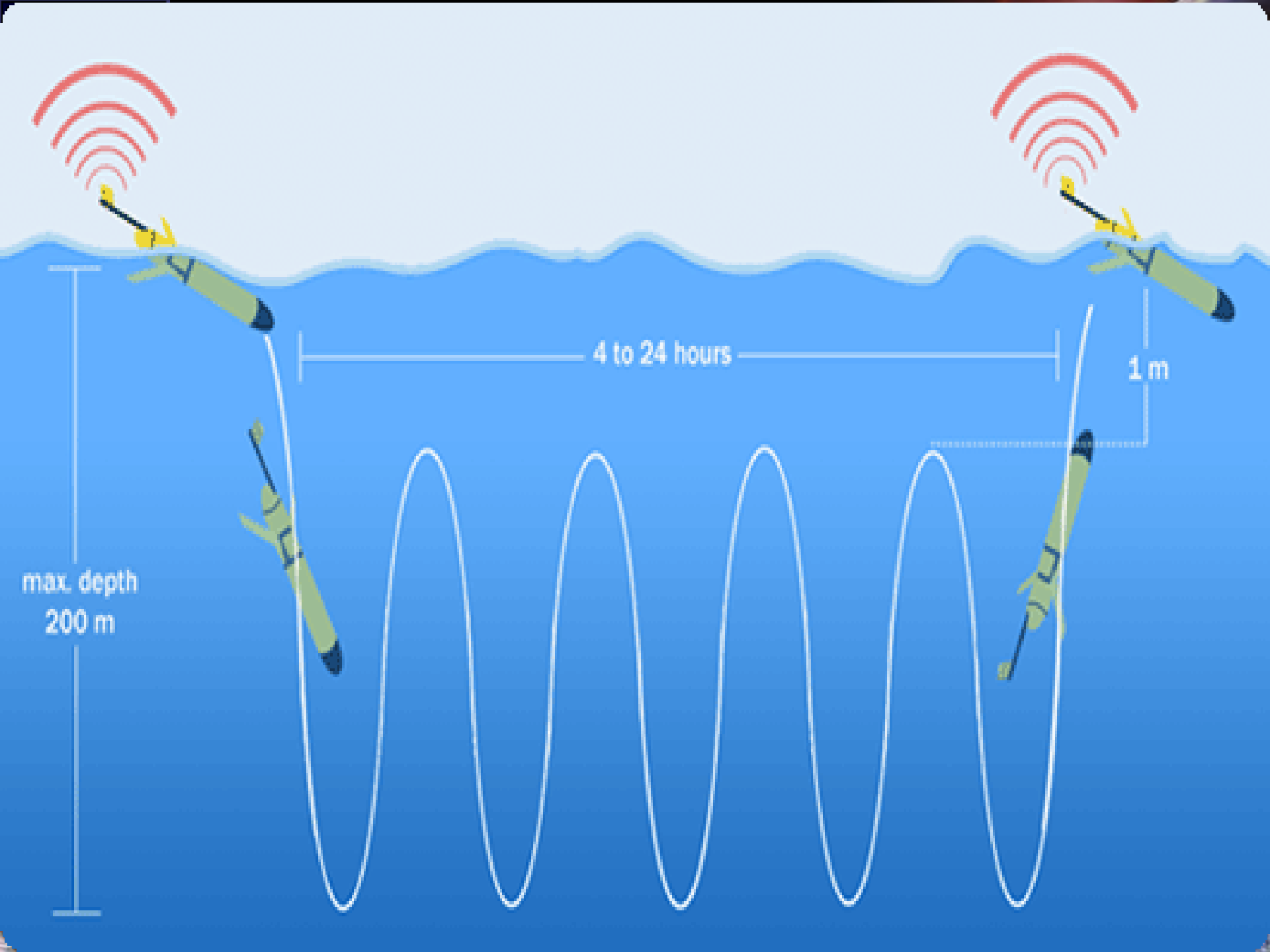
Lagrangian path planning for the first Autonomous Underwater Vehicles in transoceanic missions: The new boundaries of operational oceanography.

A.G. RAMOS⁽¹⁾, V.J GARCÍA-GARRIDO⁽²⁾, S.GLENN⁽³⁾, J.KOHUT⁽³⁾, O.SCHOFIELD⁽³⁾, D.K. ARAGON⁽³⁾, N. STRANDSKOV⁽³⁾, A.M. MANCHO⁽²⁾, S. WIGGINS⁽²⁾, J.COCA⁽¹⁾. **SITMA-ULPGC, ICMAT, RUTGERS.**



SILBO, NW Atlantic, June 2016

photo credit: *Ben Allsup*, Teledyne Webb Research





- > 2008
- 10 missions
- > 50 months/sea
- > 45,000 km

-  **RU-17 Slocum. Across the Pond. (May – Oct 08)**
-  **RU-27 Slocum. Atlantic Crossing. (Apr – Dec 09)**
-  **Silbo Slocum. Challenger 1 (Apr11–Aug13)**
-  **RU-29 Slocum. Challenger 1 (Jan13 –March16)**

The Scarlet Knight's Trans-Atlantic Challenge

- A ROBOT'S EXPLORATION OF THE UNKNOWN OCEAN -



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Scarlet Knight RU-27 challenge

Science and History and Magic . . .

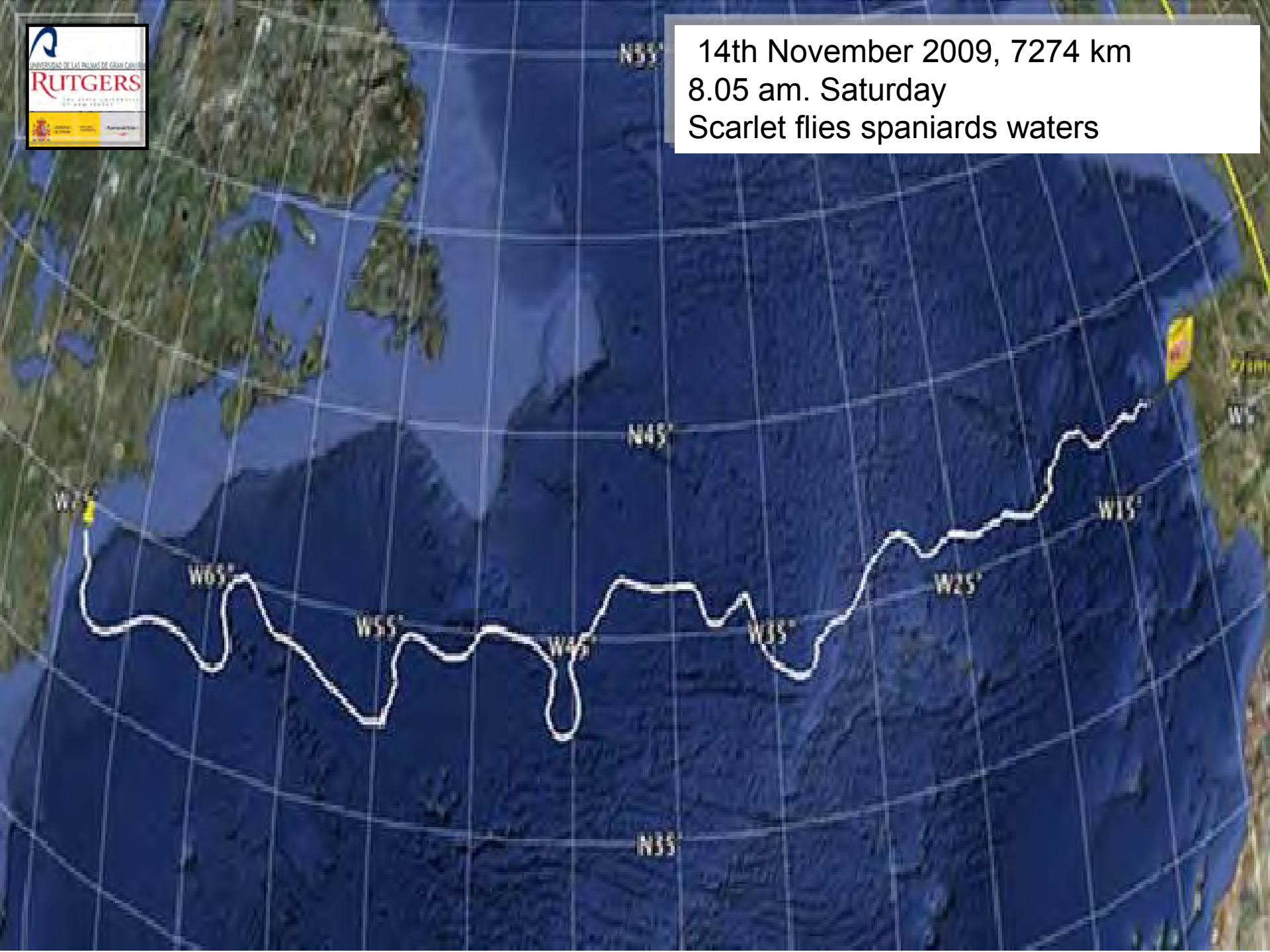


".... She was at sea for 221 days. She was alone, often in dangerous places, and usually out of touch. Her predecessor had disappeared in October 2008 on a similar trip,, probably killed by a shark..."

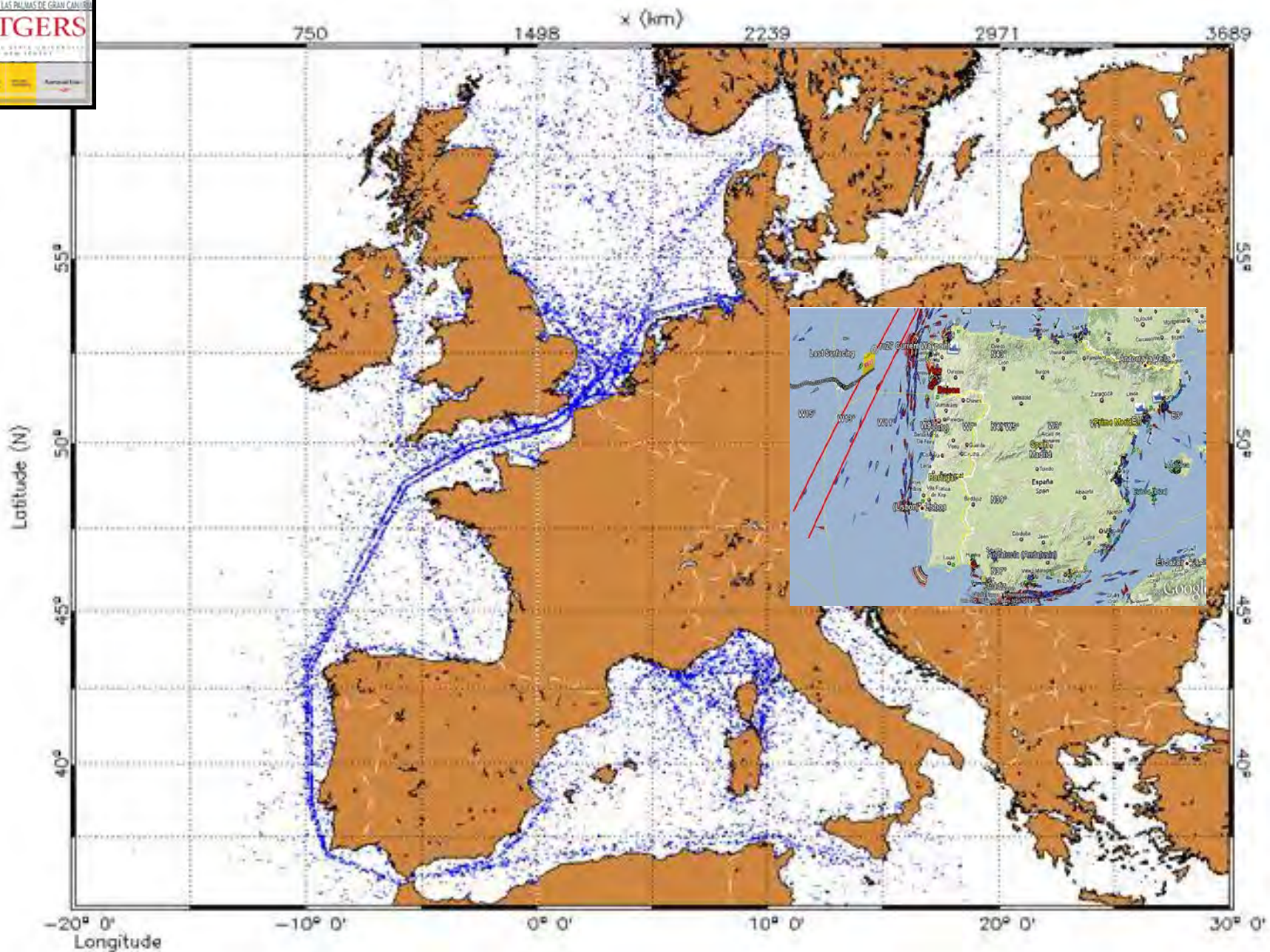
The Washington Post

Dec 2009

14th November 2009, 7274 km
8.05 am. Saturday
Scarlet flies spaniards waters

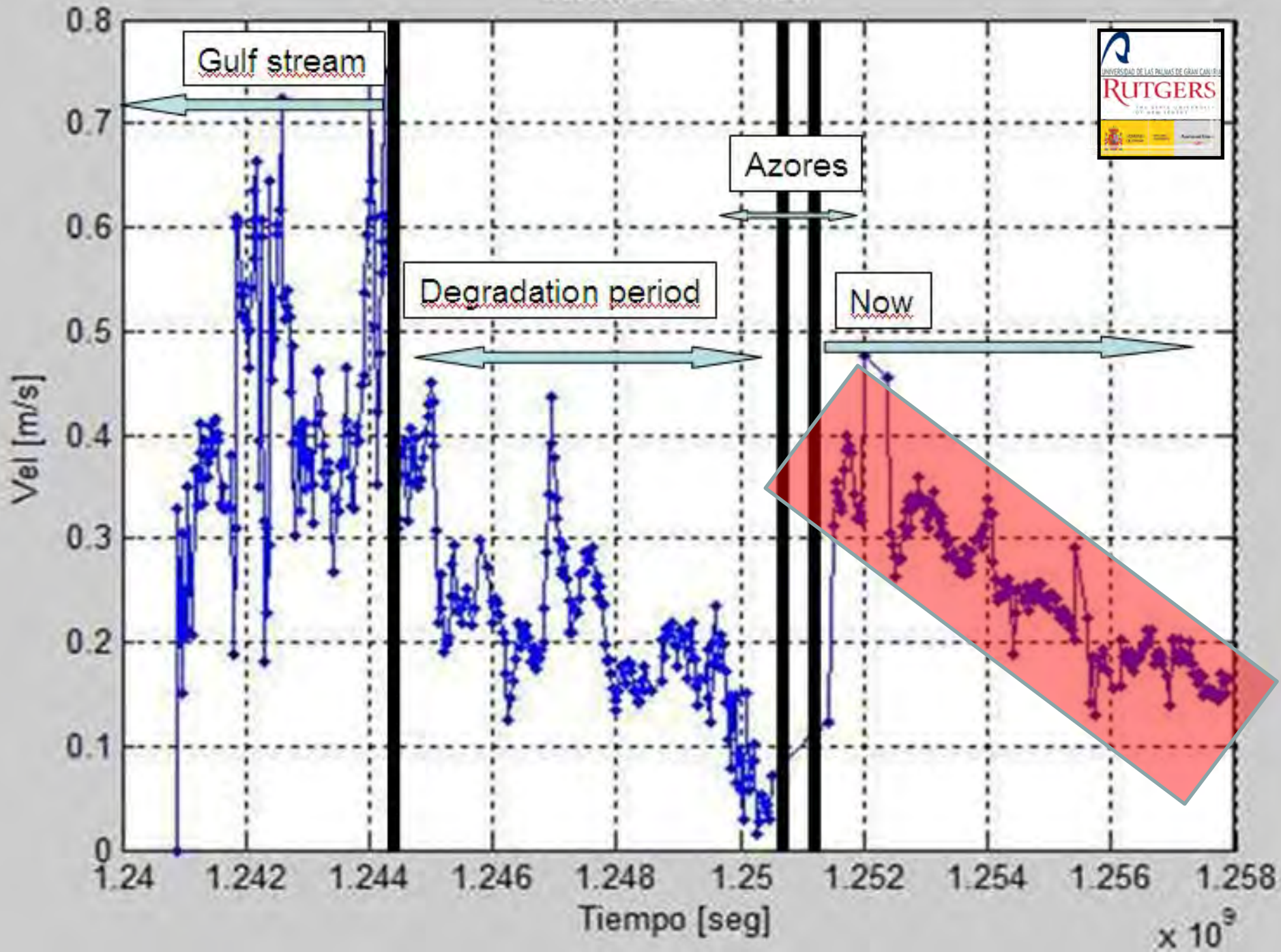


Ship detection over Europe using ENVISAT ASAR Wide Swath products



▲ 33417 targets

Velocidades Glider



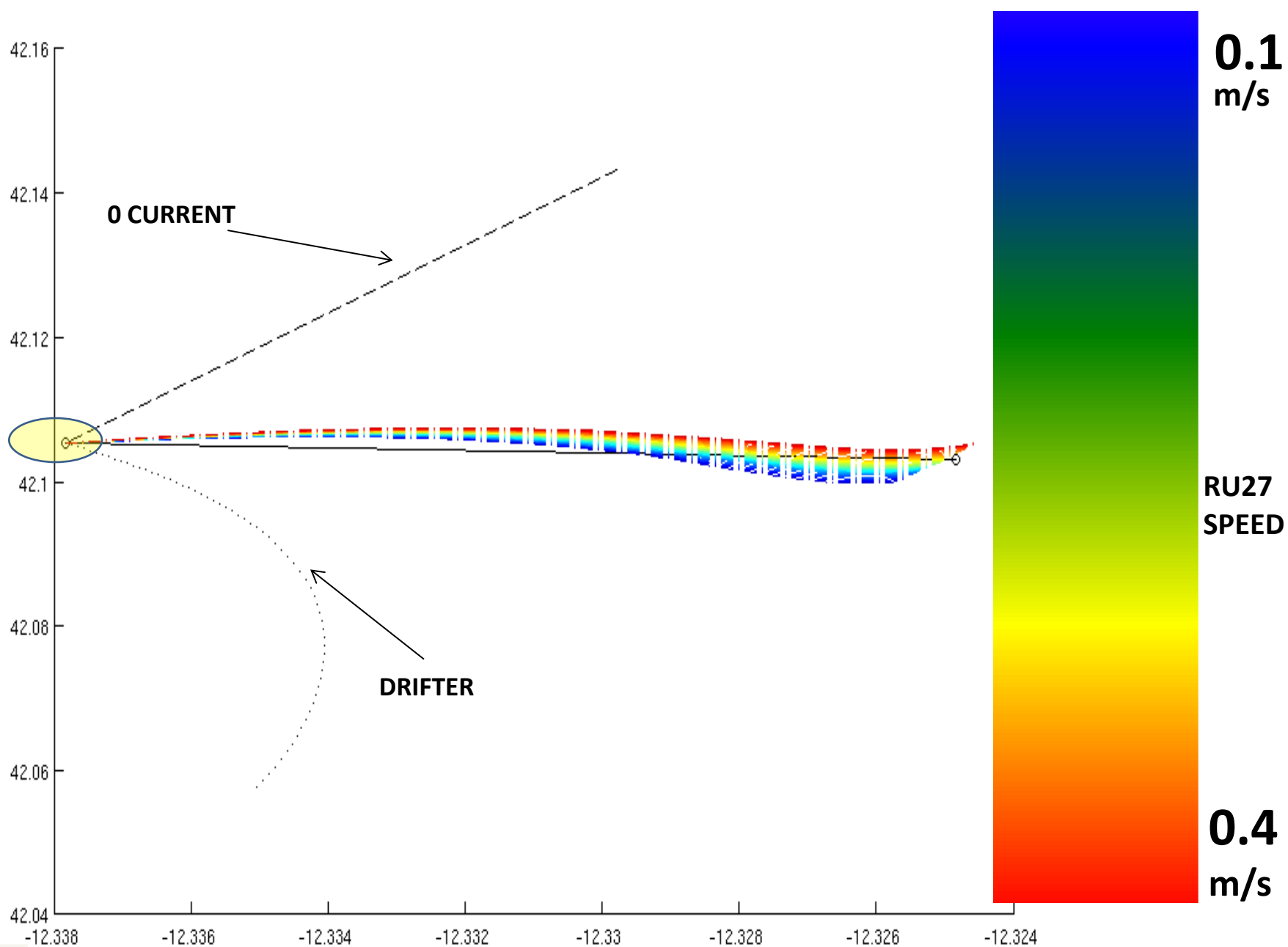


FIGURE 3. PINZON HEADING ERROR DIAGNOSTIC.

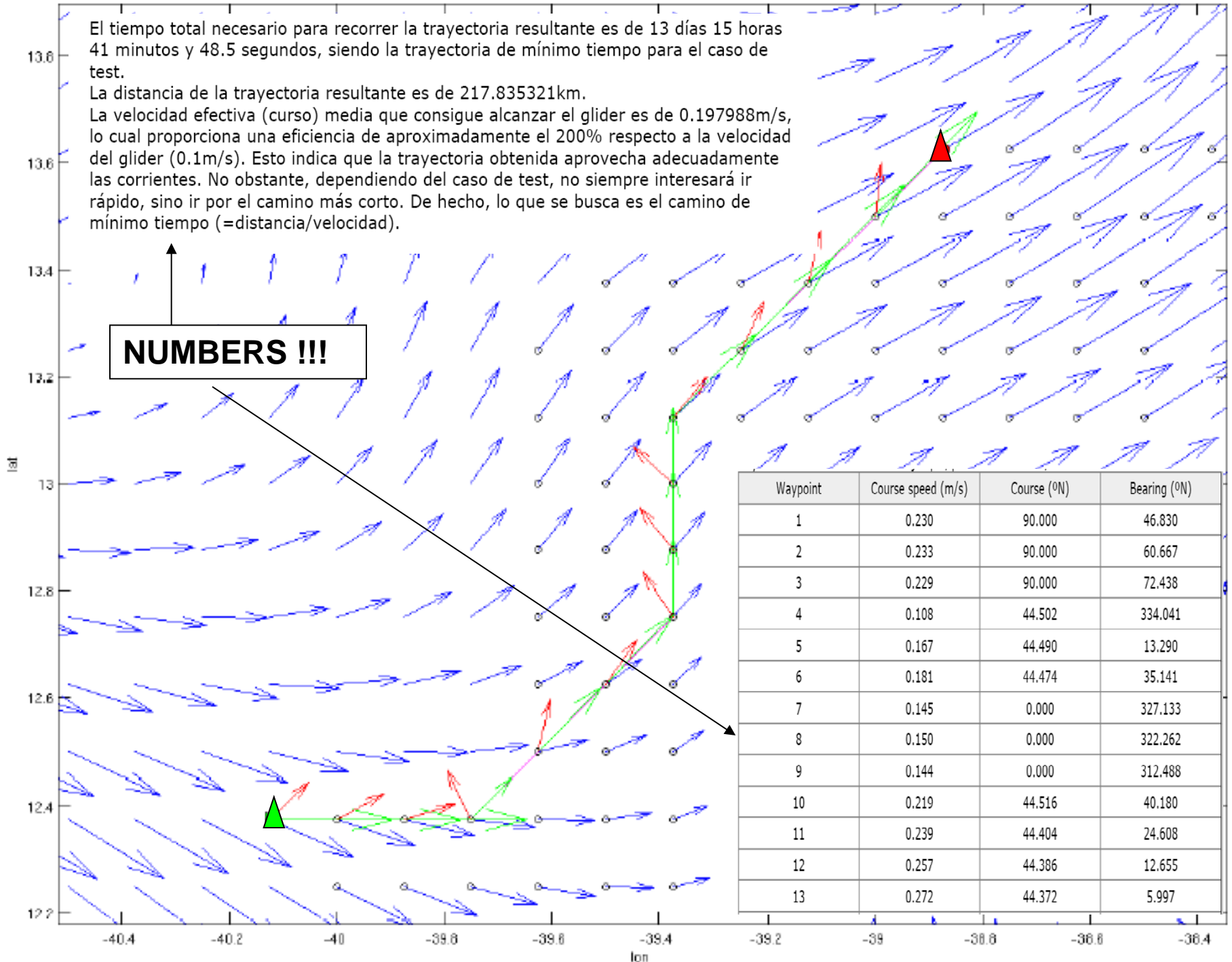


El tiempo total necesario para recorrer la trayectoria resultante es de 13 días 15 horas 41 minutos y 48.5 segundos, siendo la trayectoria de mínimo tiempo para el caso de test.

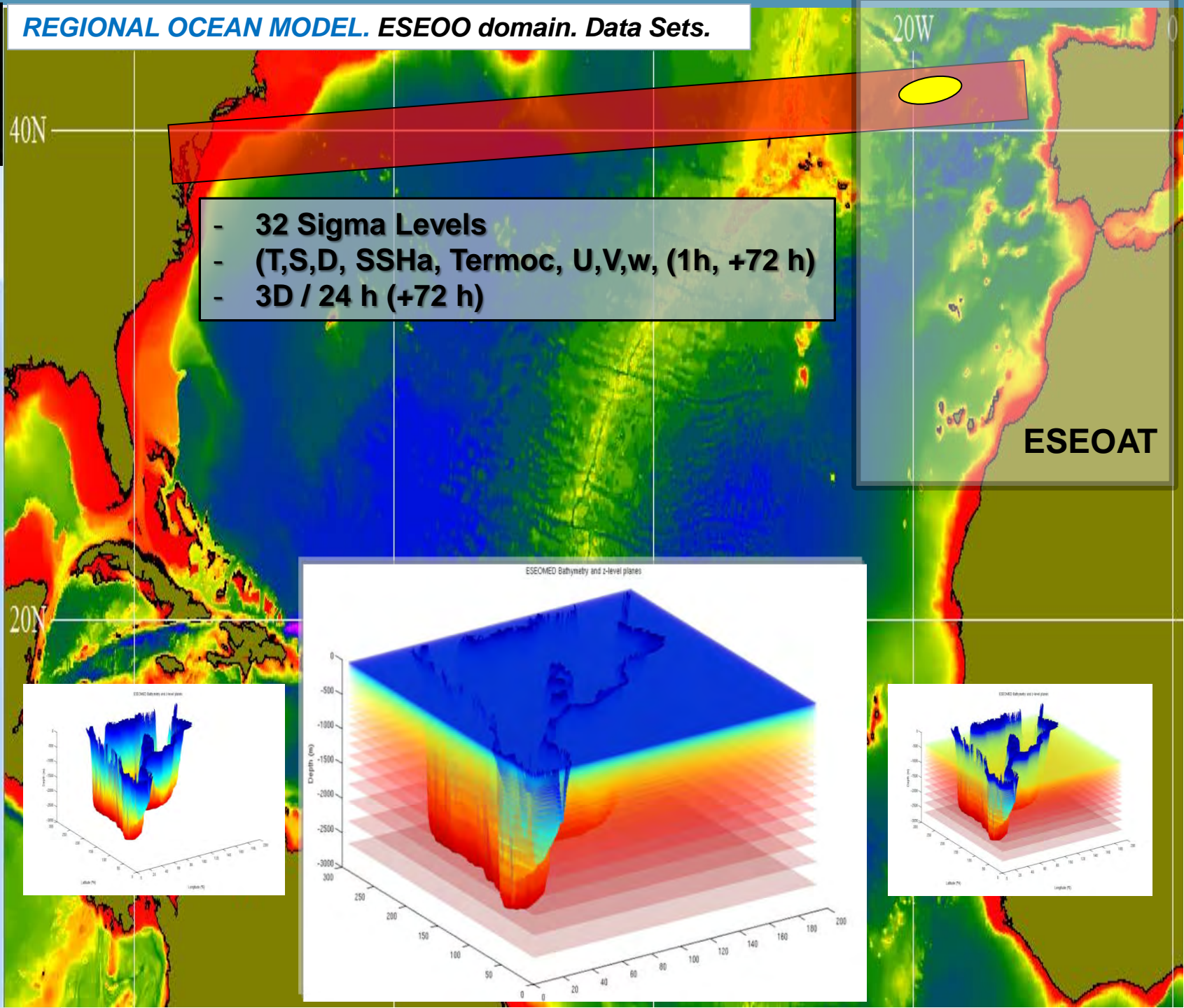
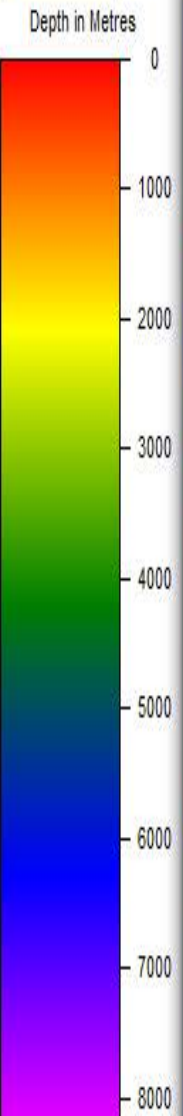
La distancia de la trayectoria resultante es de 217.835321km.

La velocidad efectiva (curso) media que consigue alcanzar el glider es de 0.197988m/s, lo cual proporciona una eficiencia de aproximadamente el 200% respecto a la velocidad del glider (0.1m/s). Esto indica que la trayectoria obtenida aprovecha adecuadamente las corrientes. No obstante, dependiendo del caso de test, no siempre interesará ir rápido, sino ir por el camino más corto. De hecho, lo que se busca es el camino de mínimo tiempo (=distancia/velocidad).

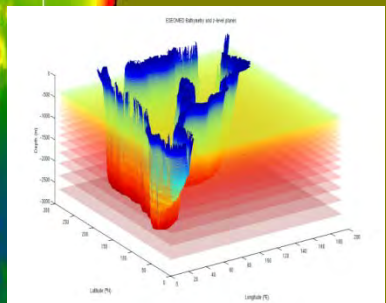
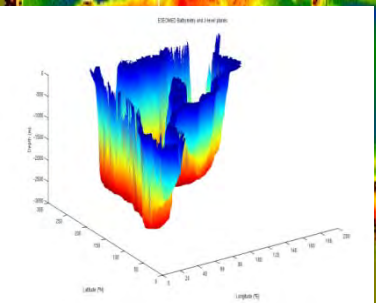
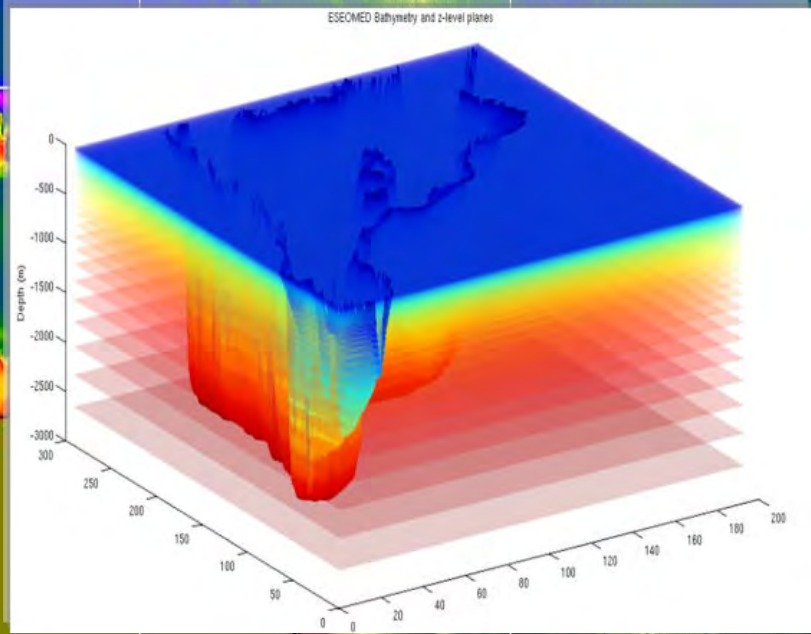
NUMBERS !!!

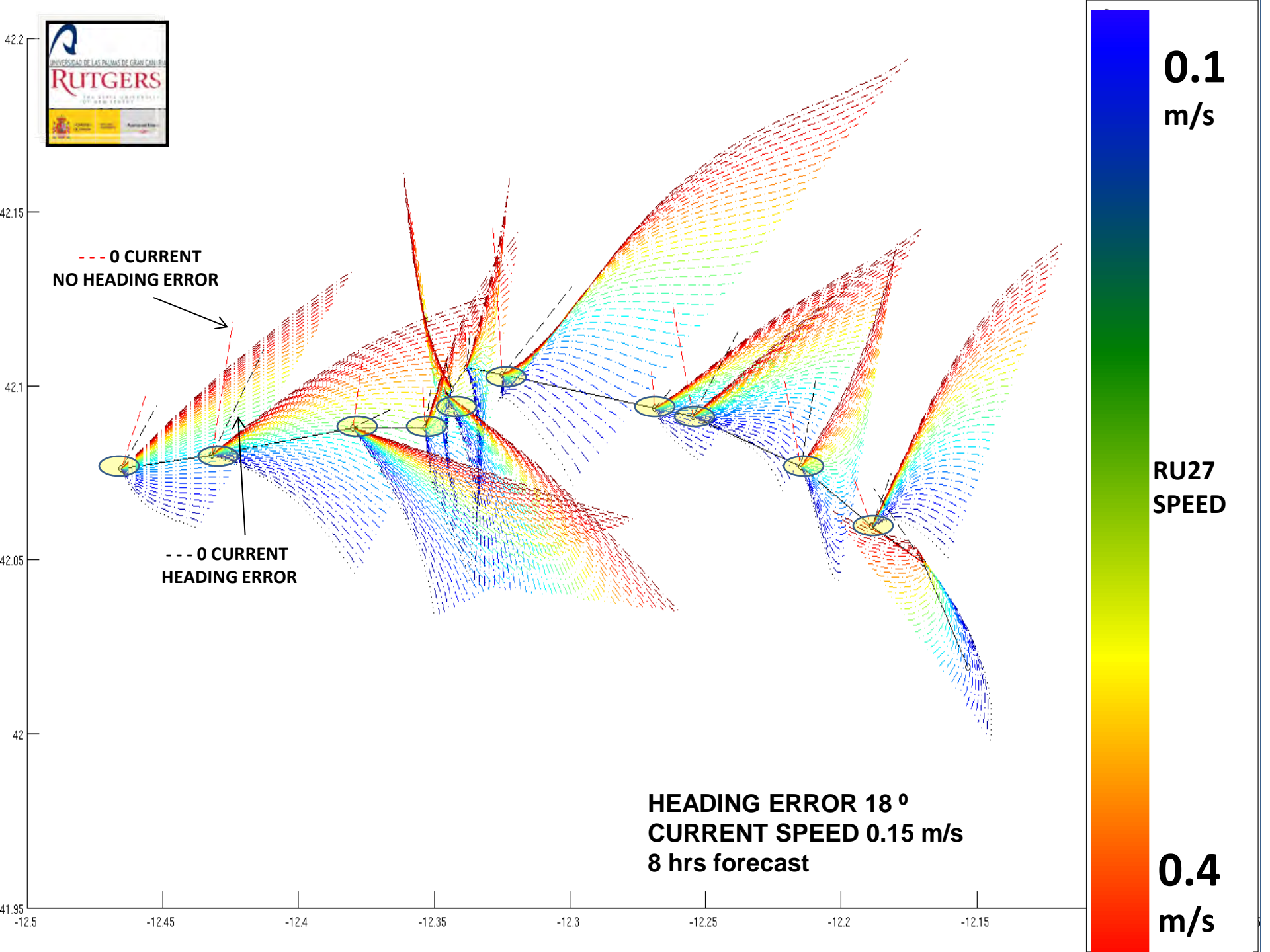


Waypoint	Course speed (m/s)	Course (°N)	Bearing (°N)
1	0.230	90.000	46.830
2	0.233	90.000	60.667
3	0.229	90.000	72.438
4	0.108	44.502	334.041
5	0.167	44.490	13.290
6	0.181	44.474	35.141
7	0.145	0.000	327.133
8	0.150	0.000	322.262
9	0.144	0.000	312.488
10	0.219	44.516	40.180
11	0.239	44.404	24.608
12	0.257	44.386	12.655
13	0.272	44.372	5.997



- **32 Sigma Levels**
- **(T,S,D, SSHa, Termoc, U,V,w, (1h, +72 h)**
- **3D / 24 h (+72 h)**





--- 0 CURRENT
NO HEADING ERROR

--- 0 CURRENT
HEADING ERROR

HEADING ERROR 18°
CURRENT SPEED 0.15 m/s
8 hrs forecast

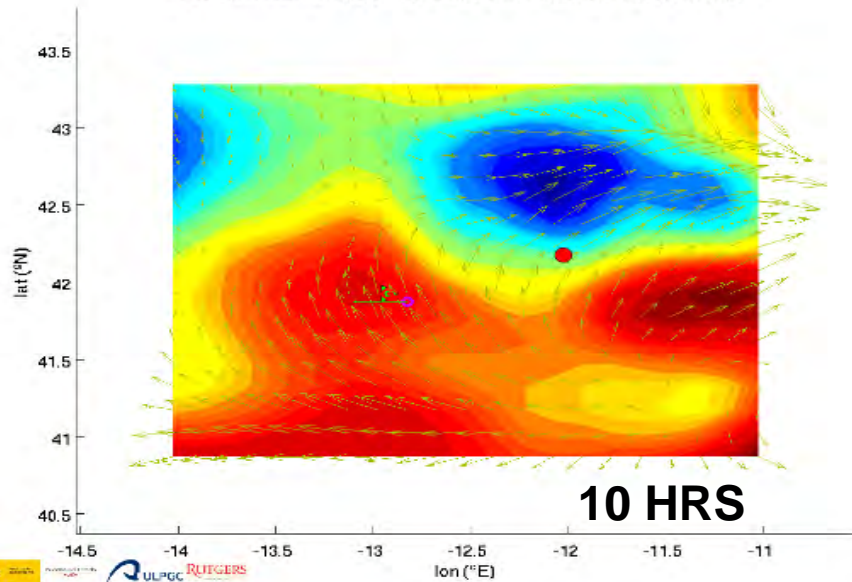
0.1
m/s

RU27
SPEED

0.4
m/s

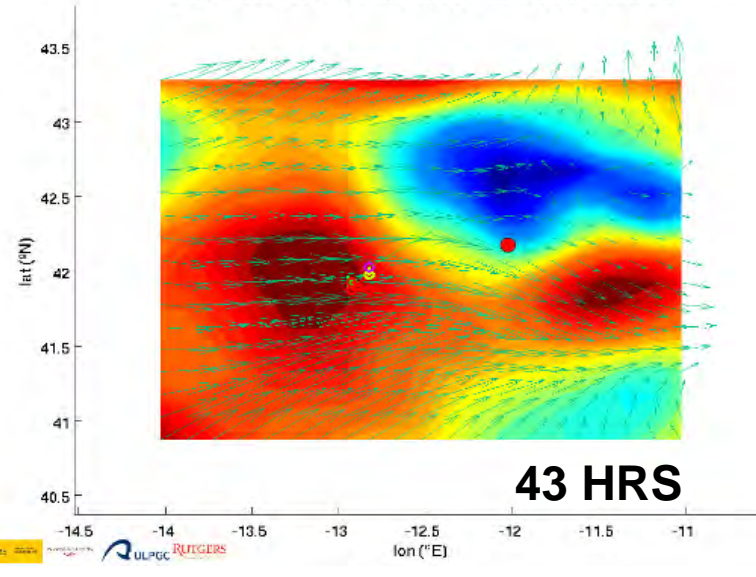
VIDEO

Path plan 20091124 (AN) - Glider speed = 0.150m/s, t = 0d 18:00:00.000



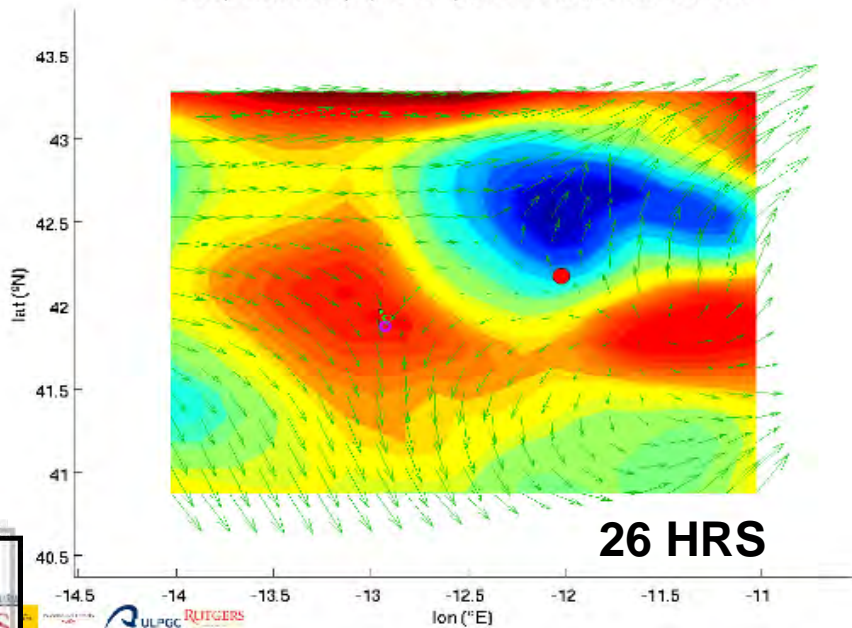
10 HRS

Path plan 20091124 (P1) - Glider speed = 0.150m/s, t = 1d 19:00:00.000



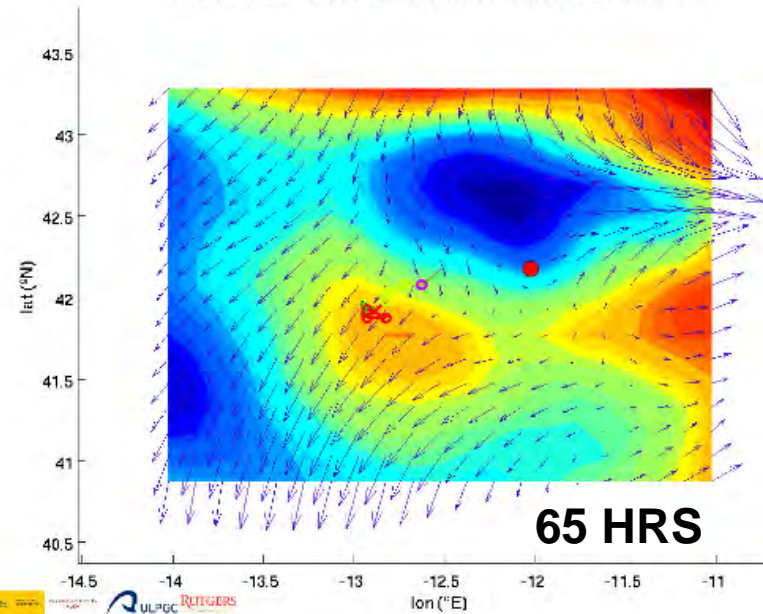
43 HRS

Path plan 20091124 (P1) - Glider speed = 0.150m/s, t = 1d 07:00:00.000



26 HRS

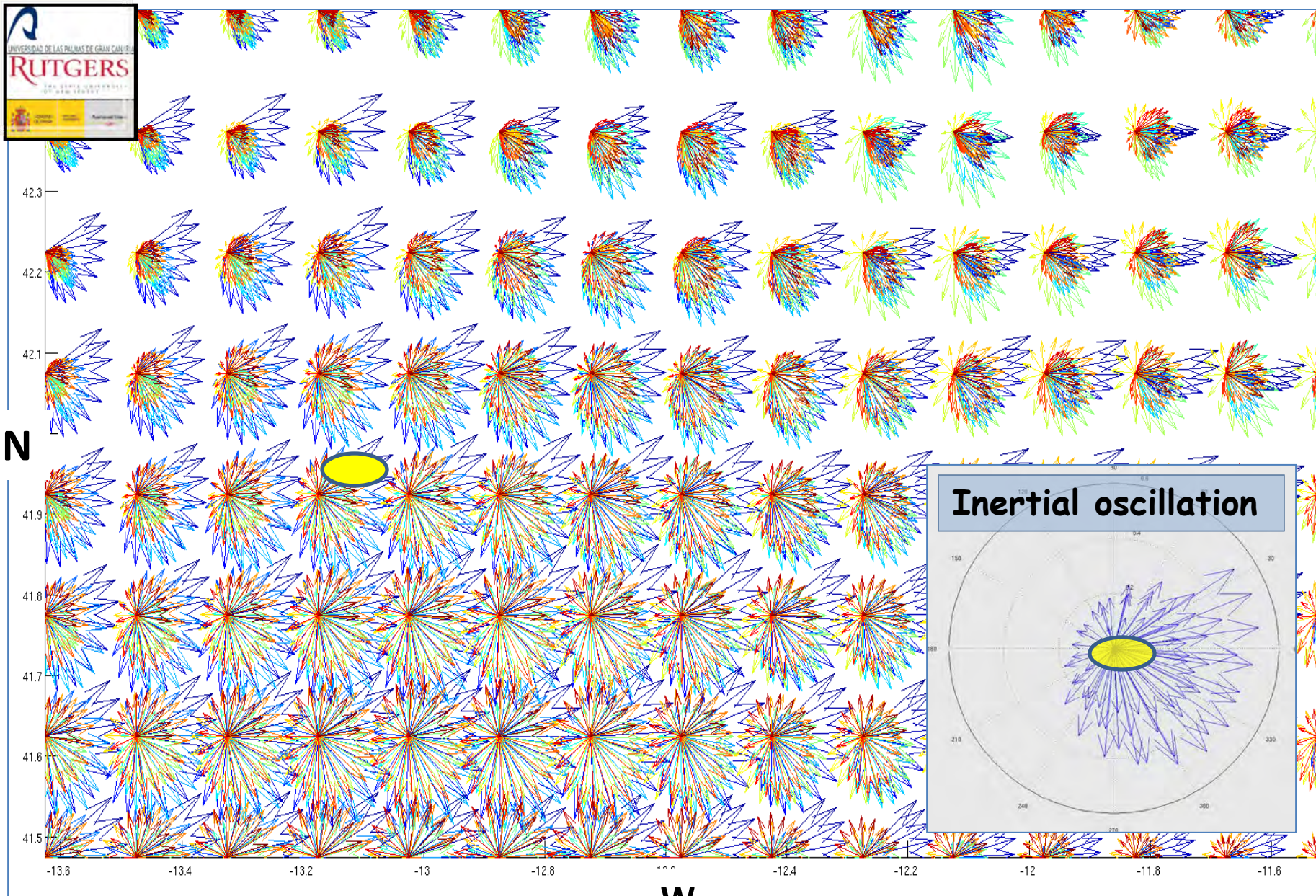
Path plan 20091124 (P2) - Glider speed = 0.150m/s, t = 2d 21:00:00.000



65 HRS

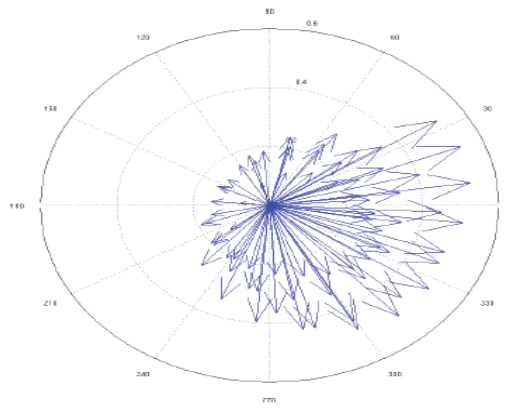
ESEOO SSHa. 24-27 NOV 2009



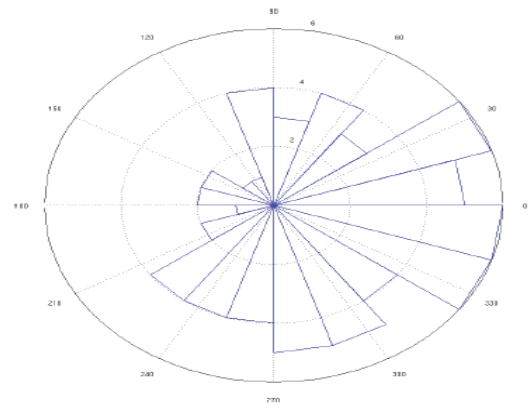


21 -23 Nov 2009. CURRENT FIELD USING HOURLY DATA FROM *ESEO* ON THE RIGHT THE COMPASS PLOT AT THE NE OF RU27 POSITION. (the 3 days in different colors)= (42N, 13W).

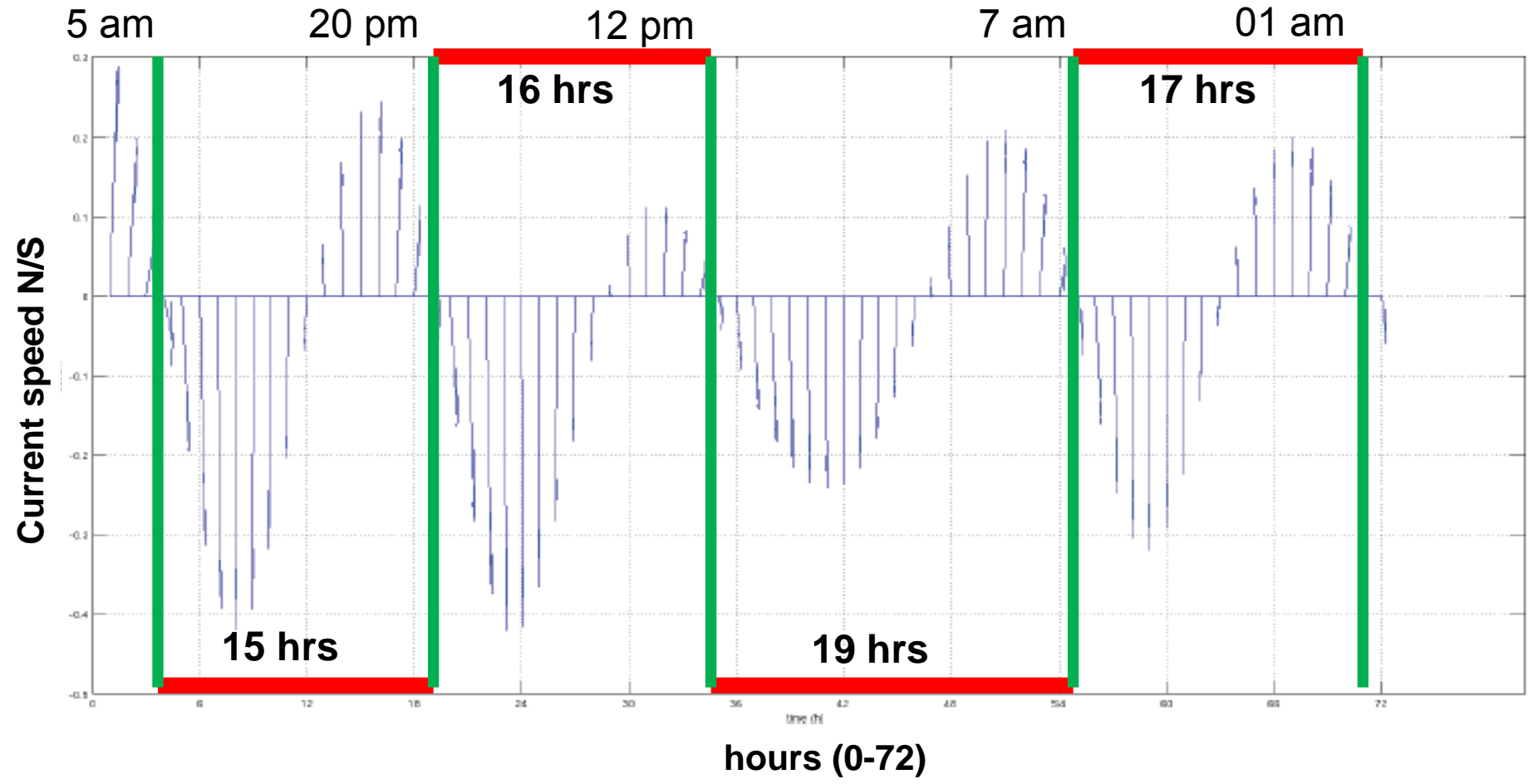
RU27
24-26 NOV 09
ESEOAT



(c) Compass plot



(d) Rose plot



VIDEO

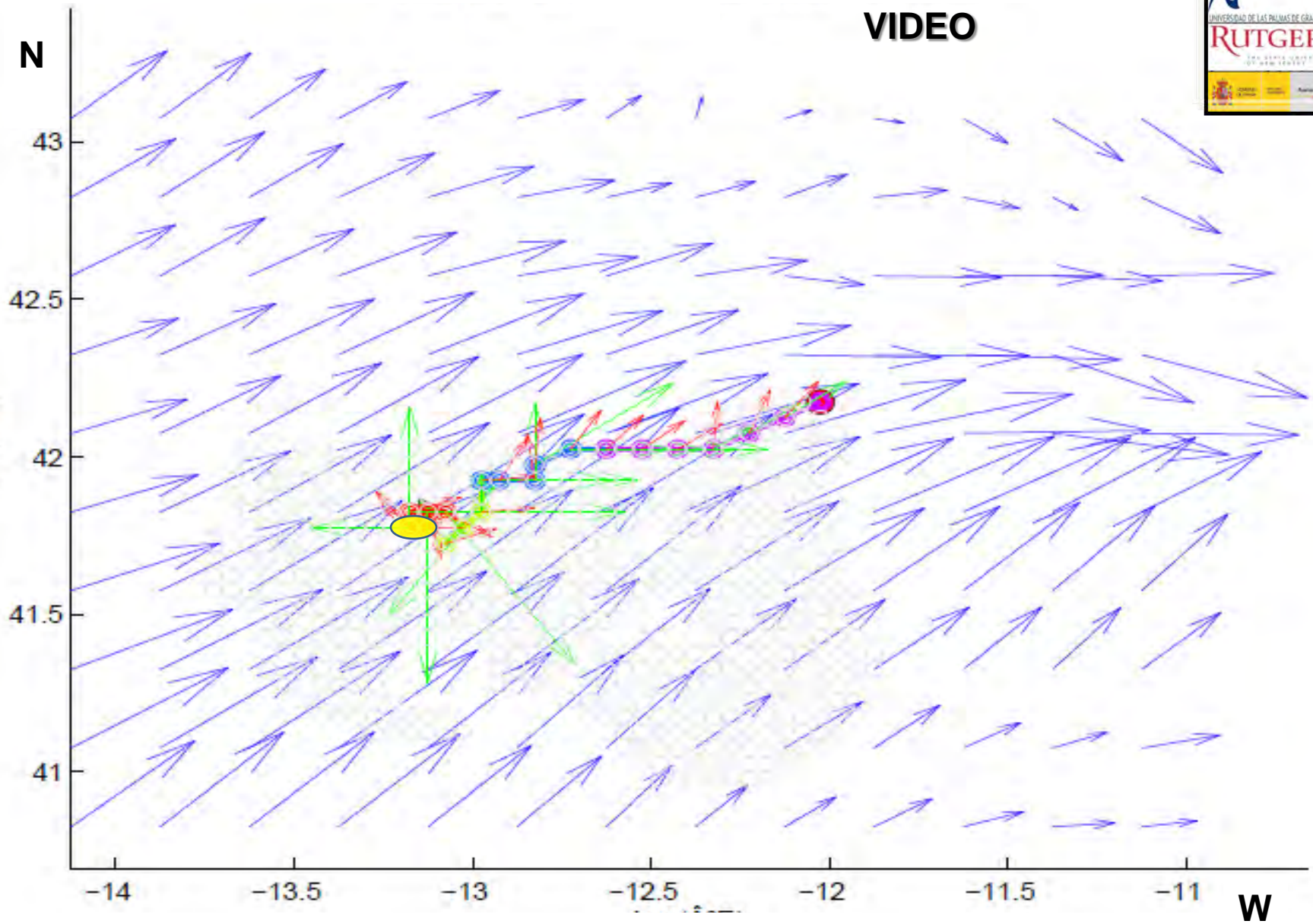


FIGURE 7. PINZON PATH PLAN ON 24 NOV 09 TO LEAVETHE INERTIAL OSCILLATION.

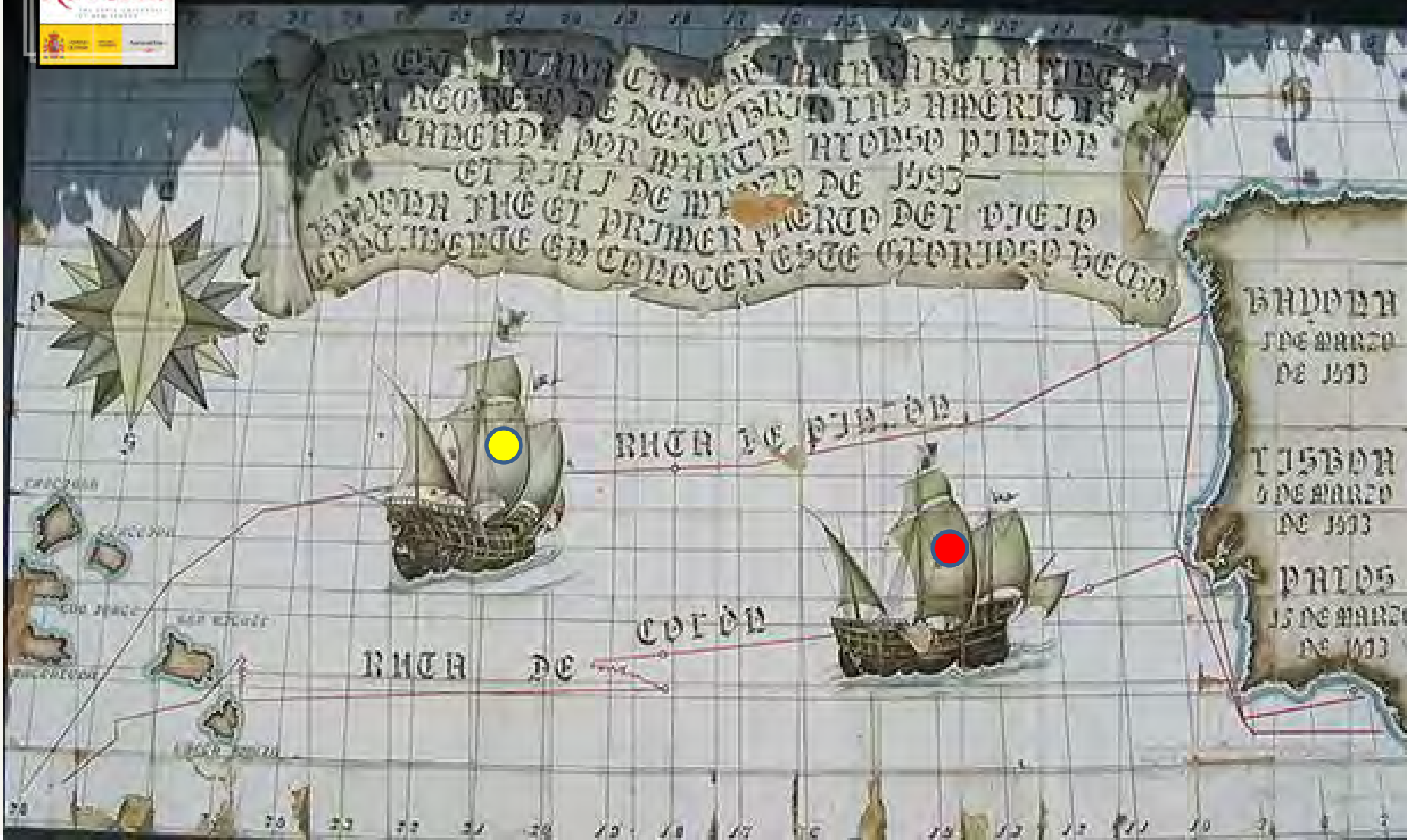
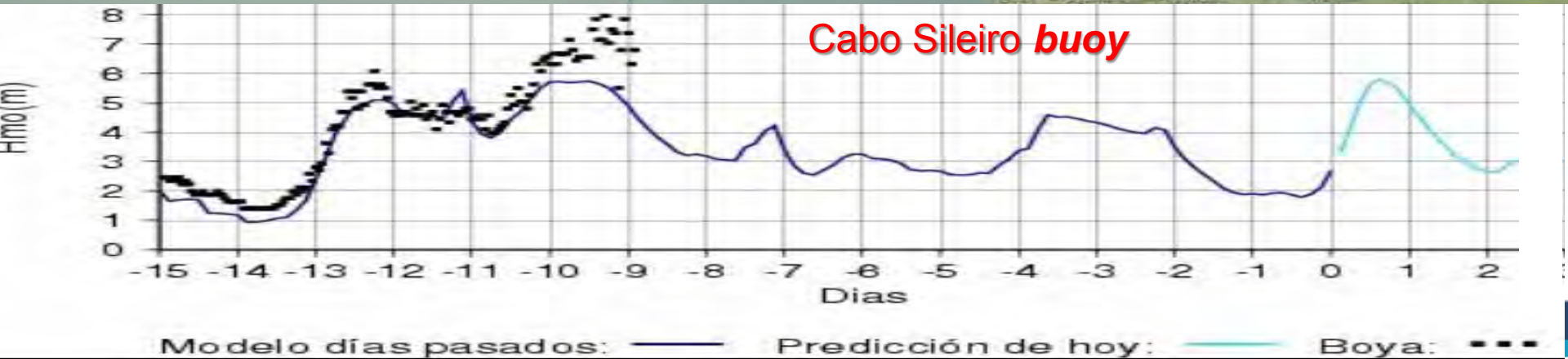


FIGURE 1. LA PINTA OF PINZON (●) AND LA NIÑA OF COLUMBUS (●) FROM MID FEBRUARY TO MID MARCH OF 1493. PICTURE EXPOSED ON THE BAIONA TOWN.



4th December 2009. 9.05 am, **Costa da Morte, NW Spain**

221 days, 7409 km

11000 yos 8000 CTD casts, 1000 sat coms

Energía = $\frac{1}{2}$ litter of gas



first contact 3 by RU COOL

(left to right) Juan Pedrosa, Enrique Fanjul, Scott Glenn & Antonio Ramos, conduct a visual inspection of The Scarlet Knight to ensure all is safe for the divers to conduct a complete video survey of the vehicle.

Taken on December 7, 2009
135 views, 0 comments



Barco: *"The bear is in the igloo..."*
Centro de Control: BZ



4th December 2009 9.45 am
Costa da Morte, SPAIN

- » [Hopewell Valley News: Yellow submarine surfaces at nearby school - 01/21/10](#)
- » [Rutgers Magazine: Fantastic Voyage - 01/18/10](#)
- » [The Princeton Packet: Yellow submarine surfaces in Montgomery classroom - 01/19/10](#)
- » [Star-Ledger: Students get their hands on Rutgers' yellow submarine - 01/15/10](#)
- » [Star-Ledger: Students get up close with Rutgers' yellow submarine - 01/15/10](#)
- » [The Times: "Scarlet" glides her way to history - 01/15/10](#)
- » [El Pais: Obama quiere que EE UU lleque al 3% del PIB en ciencia y tecnologia - 12/23/09](#)
- » [The Philadelphia Inquirer: Rutgers glider robot a sleek ocean explorer - 12/21/09](#)
- » [The Washington Post: Deep-sea glider - 12/15/09](#)
- » [Faro De Vigo: Baiona devuelve Obama el submarino norteamericano que exploro el Atlantico- 12/10/09](#)
- » [Atlantico: Baiona reenvia el robot "Piolin" a Obama - 12/10/09](#)
- » [El Pais: La ciencia hace historia en Baiona - 12/10/09](#)
- » [La Region: "Piolin" cumple su mision - 12/10/09](#)
- » [La Voz de Galicia: Baiona recibe el robot prodigioso - 12/10/09](#)
- » [Puertos Informa: Un pequeño planeador submarino atraviesa el Océano Atlántico - 12/09/09](#)
- » [Star-Ledger: Spaniards fete Rutgers research sub - 12/09/09](#)
- » [La Region: Fin de trayecto del primer robot submarino transoceanico - 12/09/09](#)
- » [La Voz de Galicia: Más de 7.000 kilómetros bajo el mar - 12/05/09](#)
- » [Faro De Vigo: El submarino Piolin culminasu travesia de 7.400 kilometros desde EE UU a Galicia - 12/05/09](#)
- » [Faro De Vigo:Piolin cumple su destino - 12/03/09](#)
- » [Daily Targum: Transatlantic glider slides into Spanish waters - 11/30/09](#)
- » [Star-Ledger: Excitements runs deep for Rutgers' glider- 11/28/09](#)

OSTP Blog

Science < Technology < Innovation

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[Voting Now Open for the President's SAVE Award](#) »

An (Underwater) Flight Across the Atlantic

At 3 a.m. this morning, students and scientists from Rutgers University led a successful mission to recapture a small underwater robotic glider off the coast of Spain. The glider, dubbed The Scarlet Knight, is the first underwater robot to cross the Atlantic Ocean. With leadership from the National Oceanic and Atmospheric Administration (NOAA) and help from a number of international partners, students from the university's Coastal Ocean Observation Lab piloted The Scarlet Knight glider during its eight-month voyage.



a single patent into different languages. The plan awaits debate in the European parliament.

Biotech boost: The European life-sciences sector was perked up by its first large initial public offering for almost two years, after Belgian biotech firm Movetis raised €85 million (US\$128 million) on its 3 December debut. Backed by venture-capital investment, Movetis has European approval to market a constipation drug, prucalopride (Resolor).

NUMBER CRUNCH

221

The number of days unmanned underwater glider Scarlet Knight took to cross the Atlantic Ocean, gathering water data. It is the first craft of its kind to make the crossing.

Source: Rutgers, the State University of New Jersey

quit the agency on 2 December. Clive Spash (pictured below), an ecological economist at the Commonwealth Scientific and Industrial Research Organization in Canberra, said he had "had enough" after his paper was accepted by the journal *New Political Economy* earlier this year, withdrawn by the acting chief of his division, and then approved again on condition that parts were reworded. See go.nature.com/OoYXwX for more.



THE WEEK AHEAD

9-11 DECEMBER
 New Zealand hosts the Antarctic Treaty Meeting of Experts, which will recommend ways to manage ship-borne tourism to Antarctica.
go.nature.com/dUJGwl

10 DECEMBER
 This year's Nobel science laureates receive their awards in Stockholm, Sweden.
go.nature.com/PUJasn



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Science & Technology

First-Ever Trans-Atlantic Crossing by Unmanned Glider Advances Ocean Observation

Jennie Lyons and Deanna Eastman, National Ocean Service

January 4, 2009 — It took 221 days and international coordination, but a 7-foot-long, 135-pound Slocum deep-sea glider opened up a new world of ocean technology in December when it successfully crossed the Atlantic Ocean — a 7,300-mile-journey from the New Jersey coast to a famed Spanish harbor.



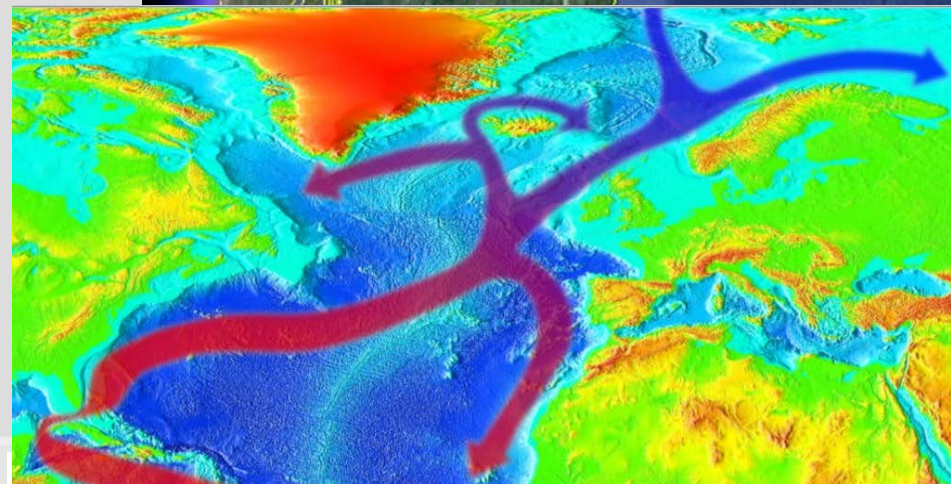
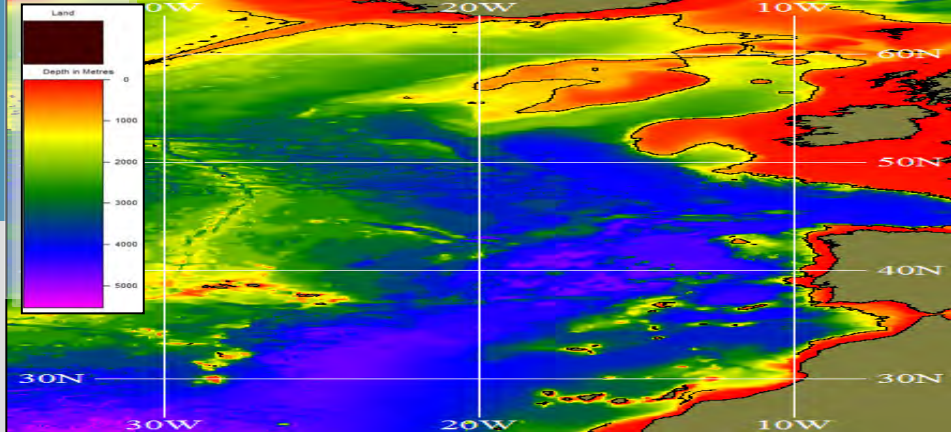


Museo Casa de la Navegación de Baiona, Vigo-SPAIN

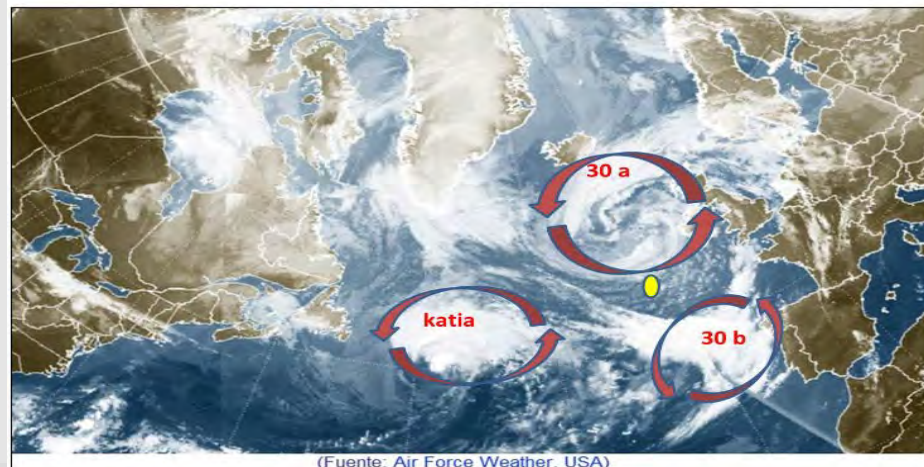


- > 2008
- 10 missions
- > 50 months/sea
- > 45,000 km

-  **RU-17 Slocum. Across the Pond. (May – Oct 08)**
-  **RU-27 Slocum. Atlantic Crossing. (Apr – Dec 09)**
-  **Silbo Slocum. Challenger 1 (Apr11–Aug13)**
-  **RU-29 Slocum. Challenger 1 (Jan13 –March16)**



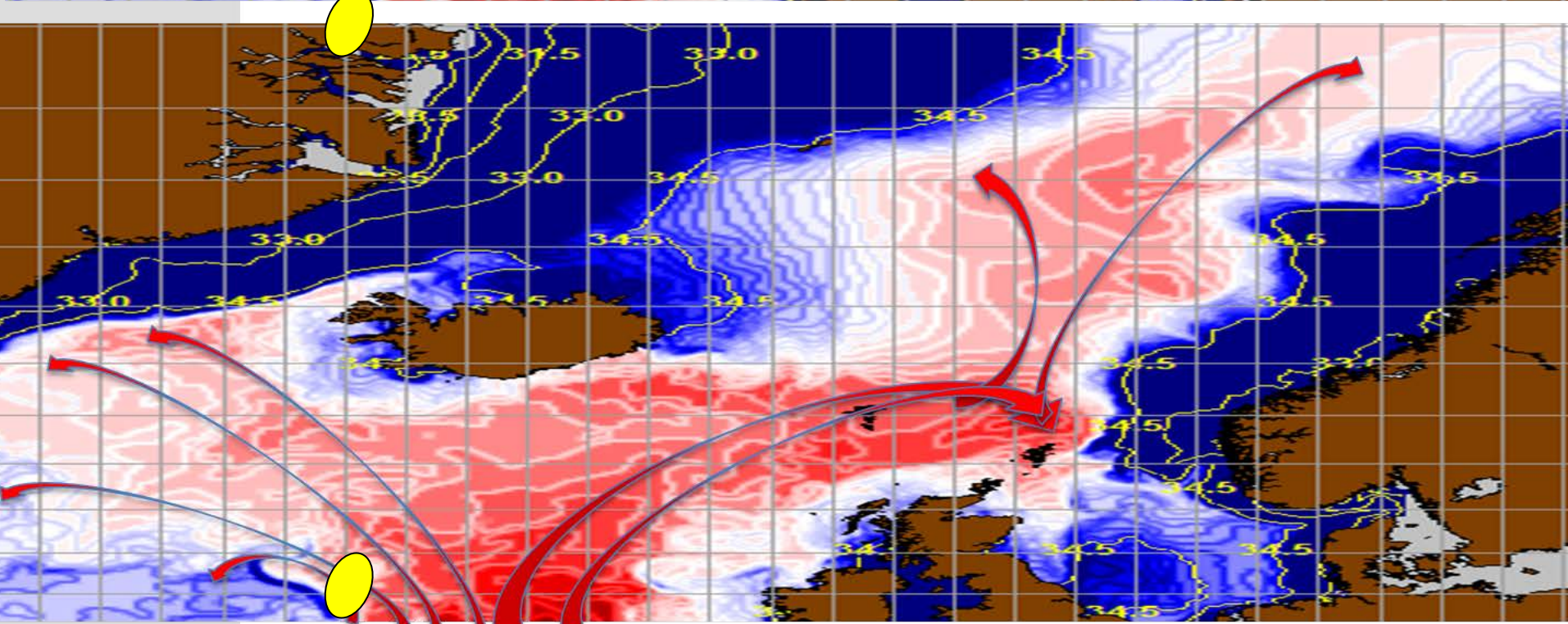
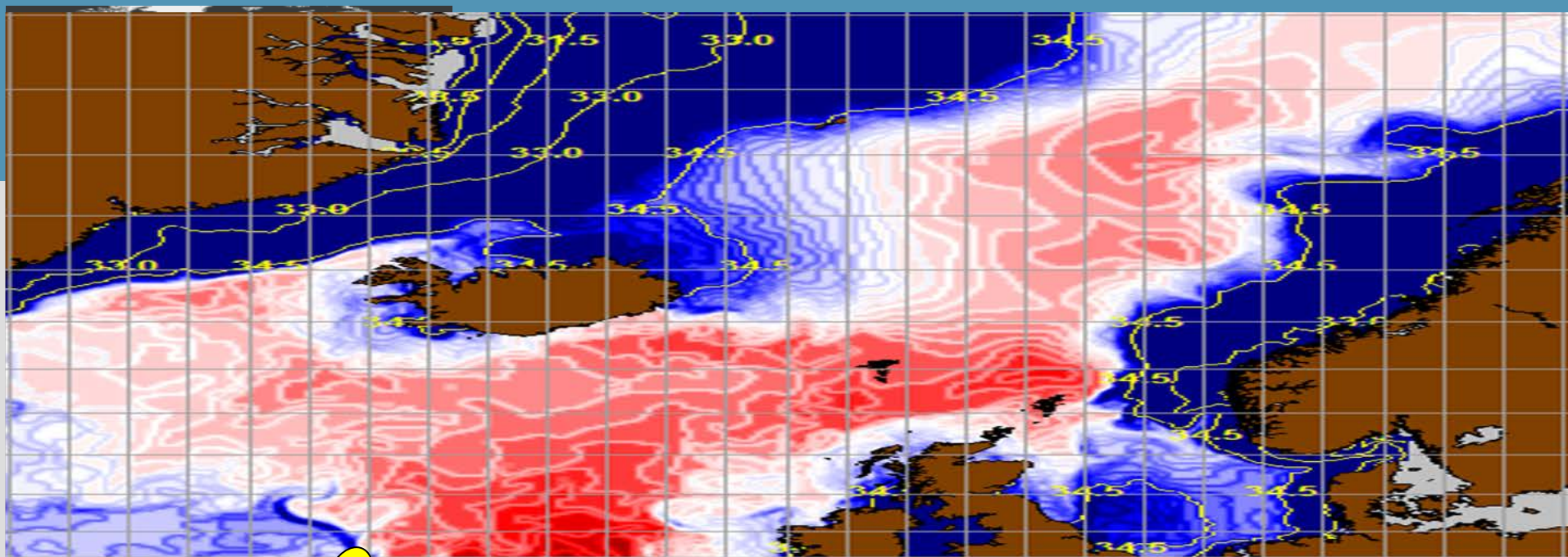
The Perfect Storm

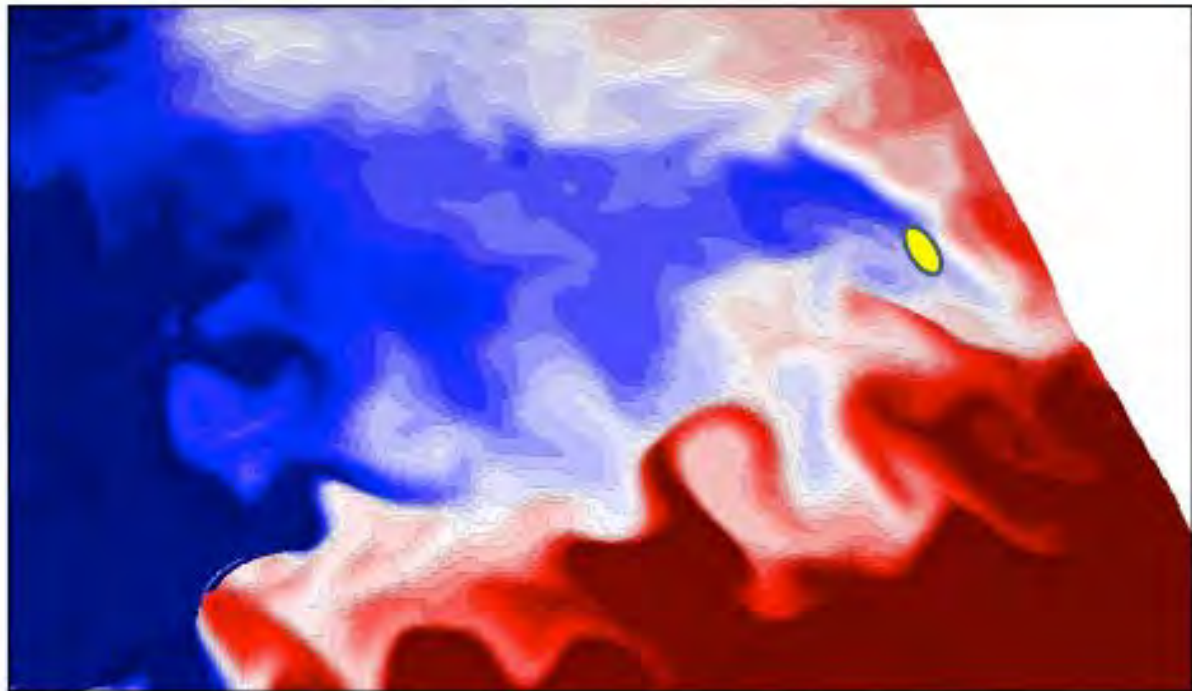
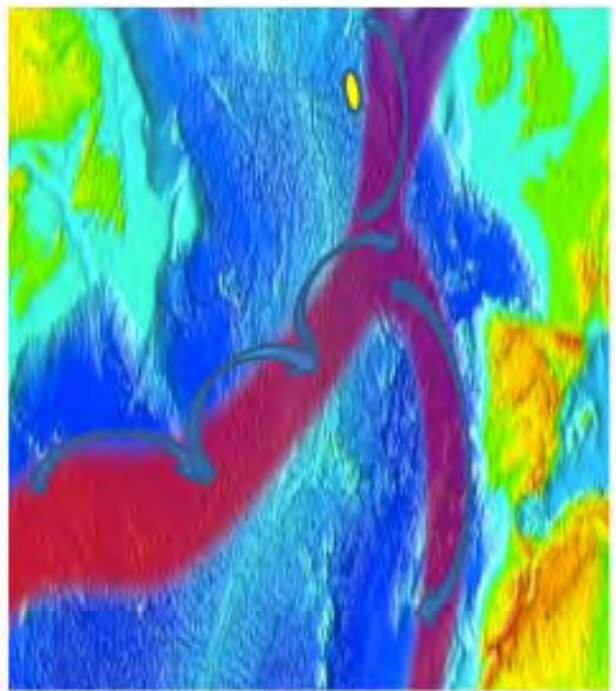
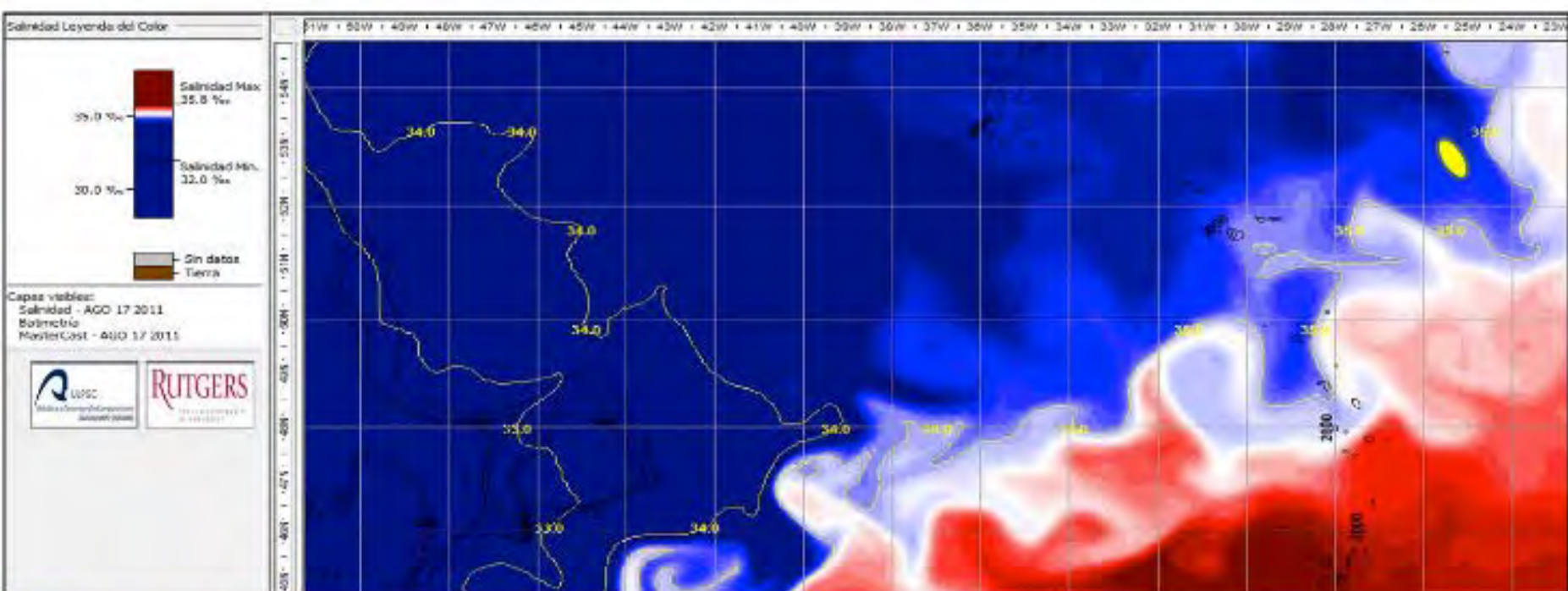


(Fuente: Air Force Weather, USA)

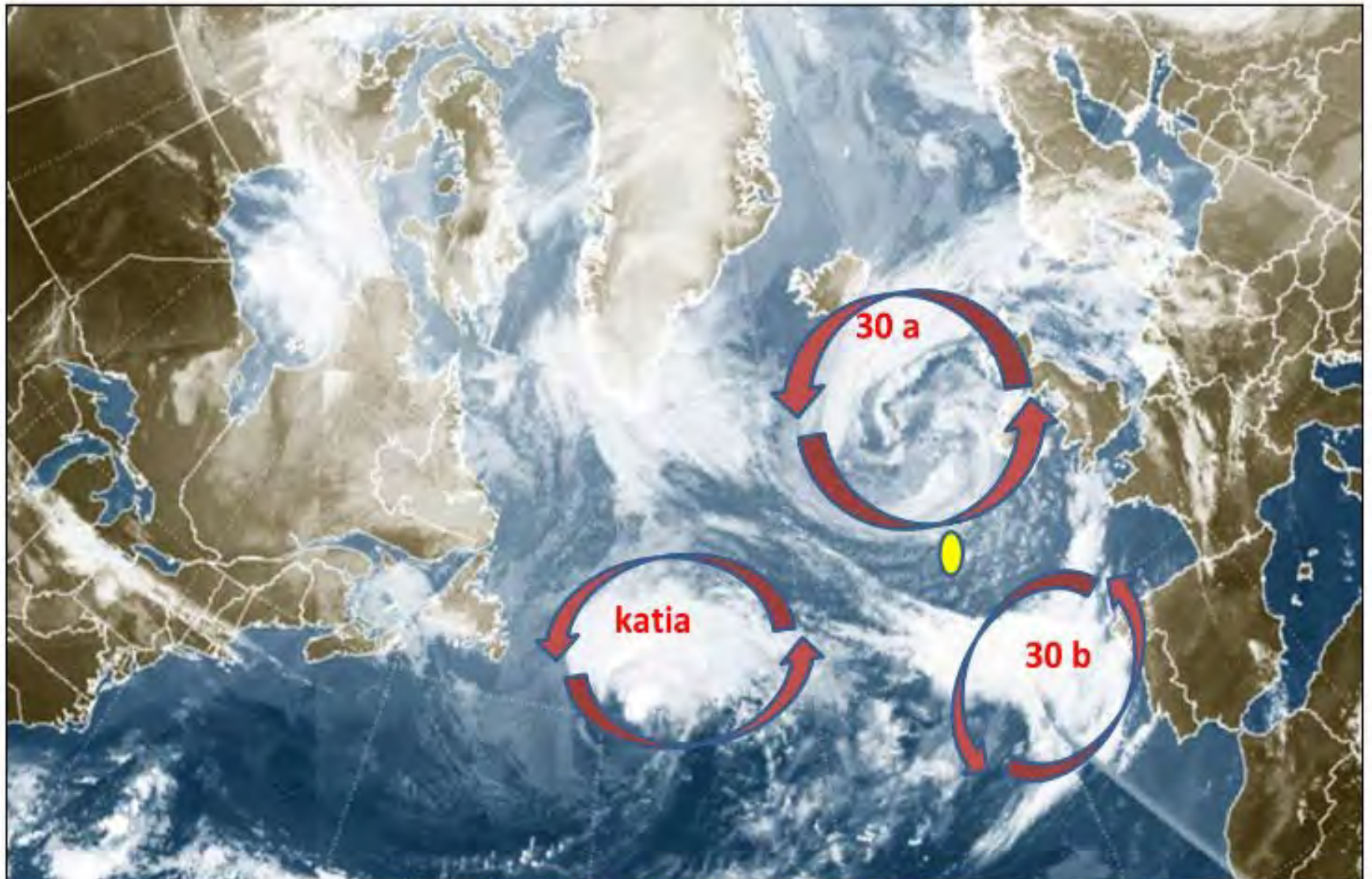


2.- Silbo,s job

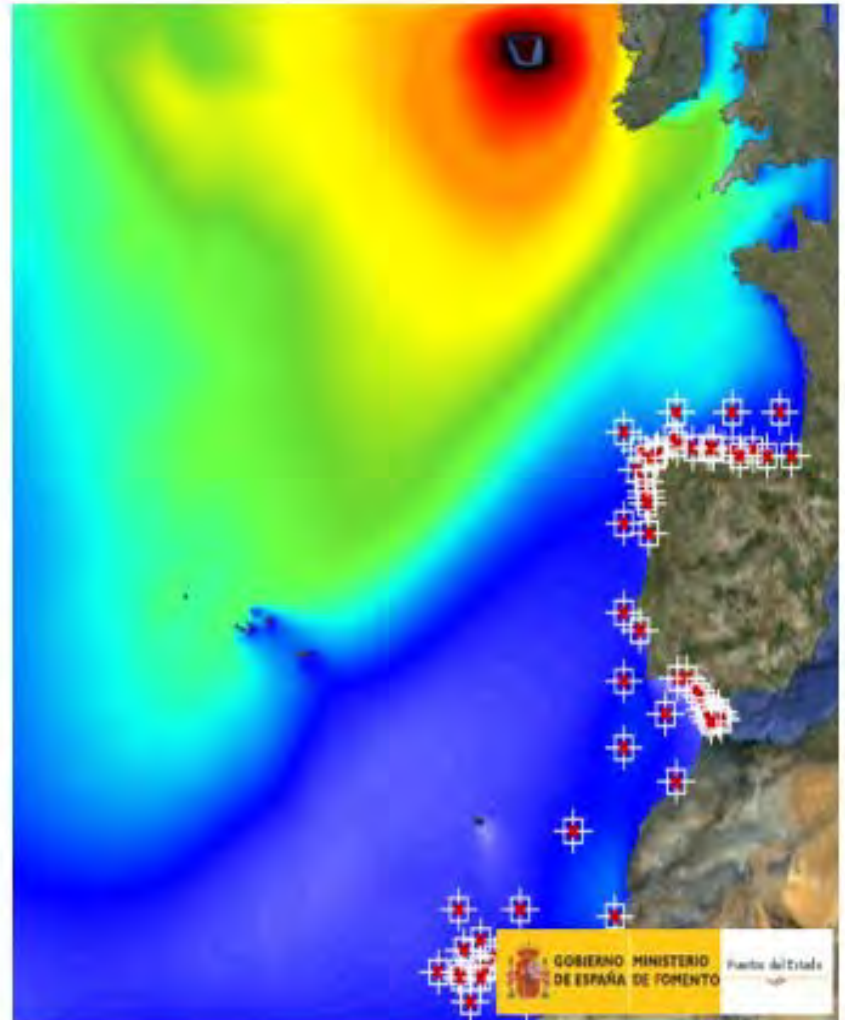
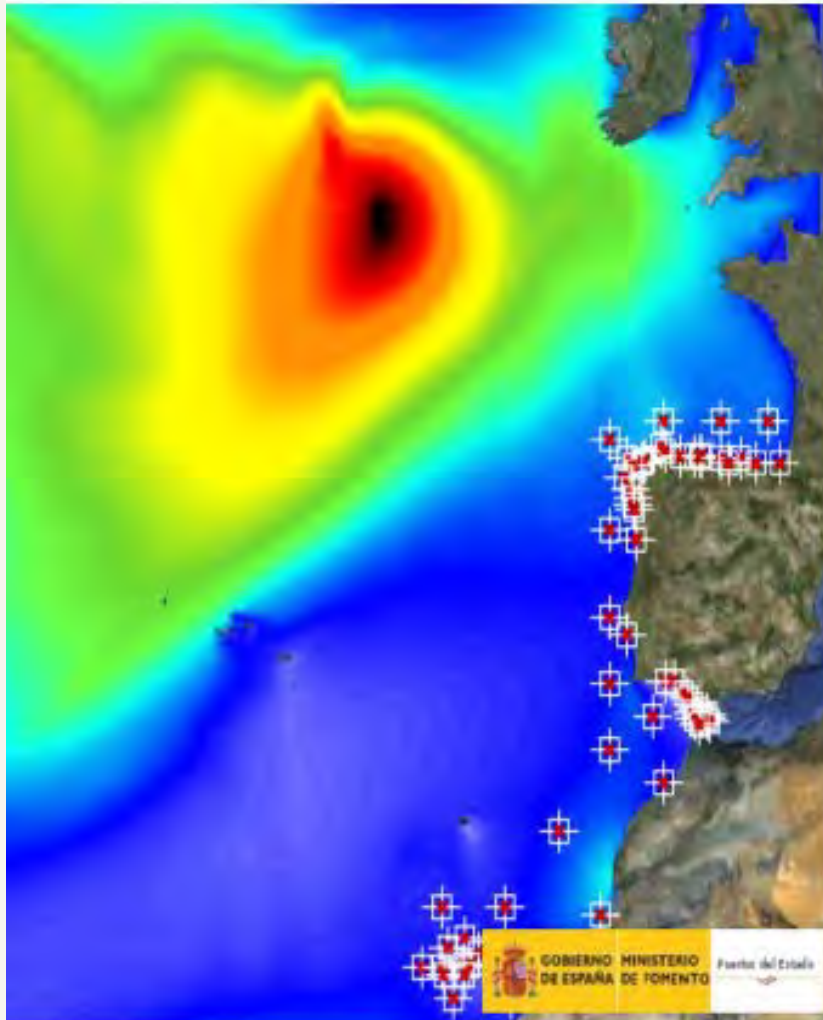
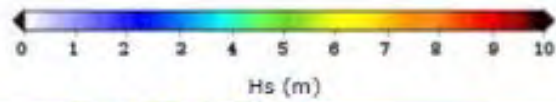




11 SEPTEMBER 11 00.00 am
The Perfect Storm

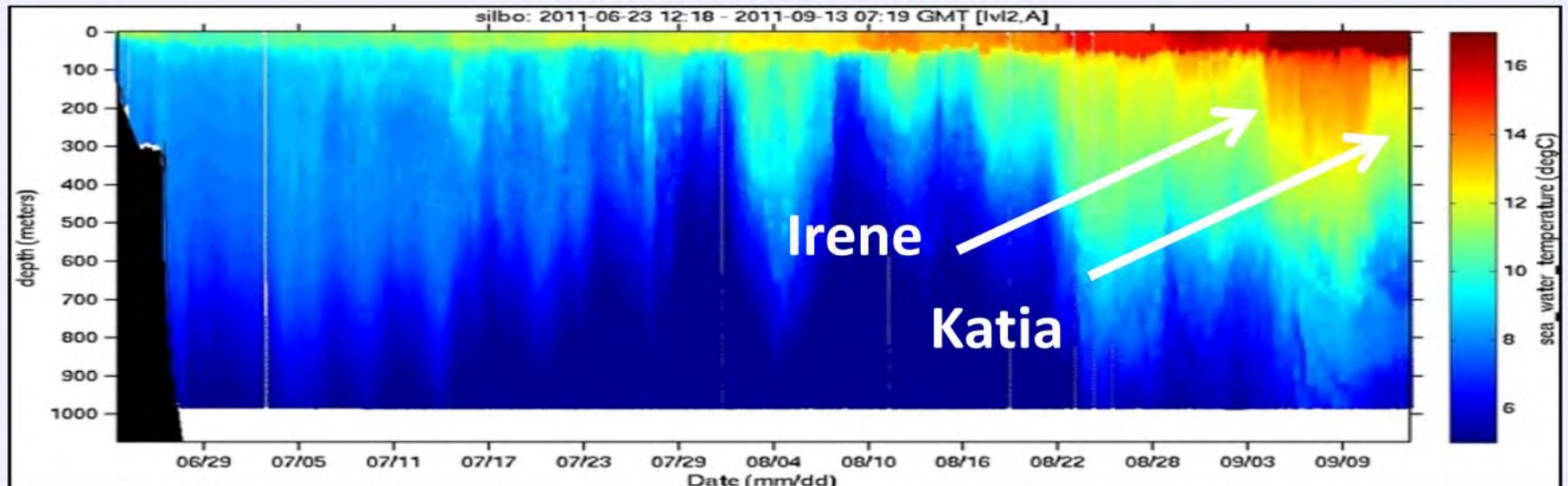


(Fuente: Air Force Weather, USA)

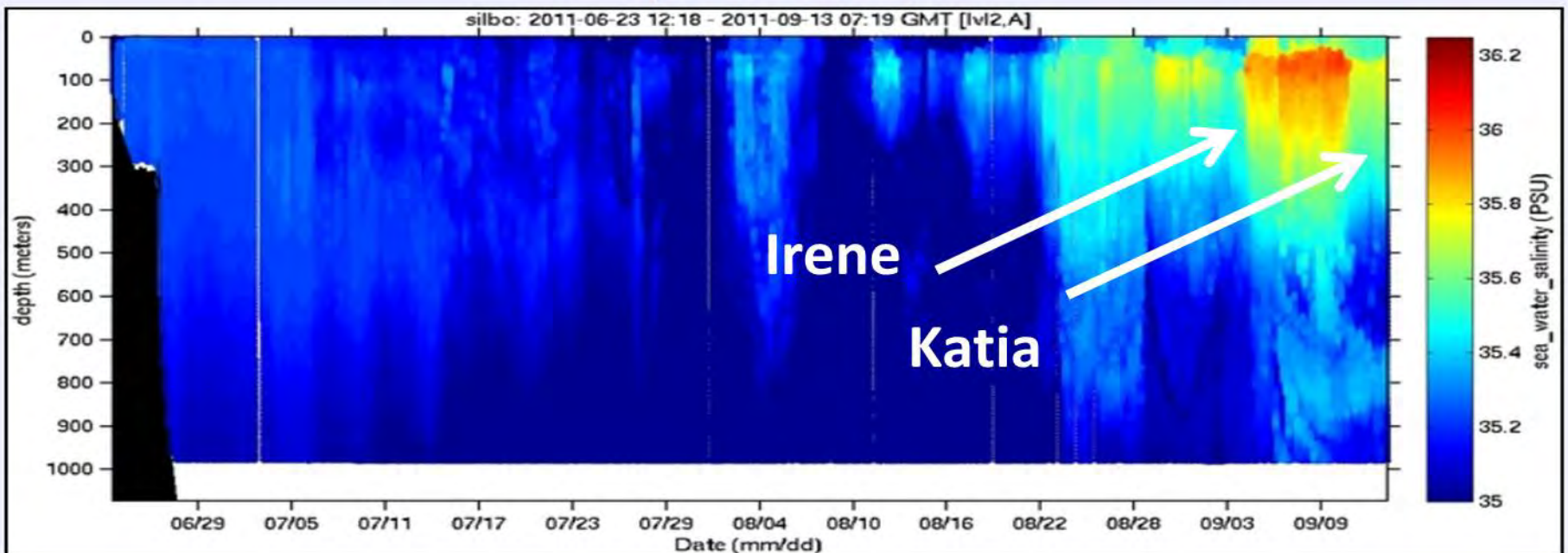


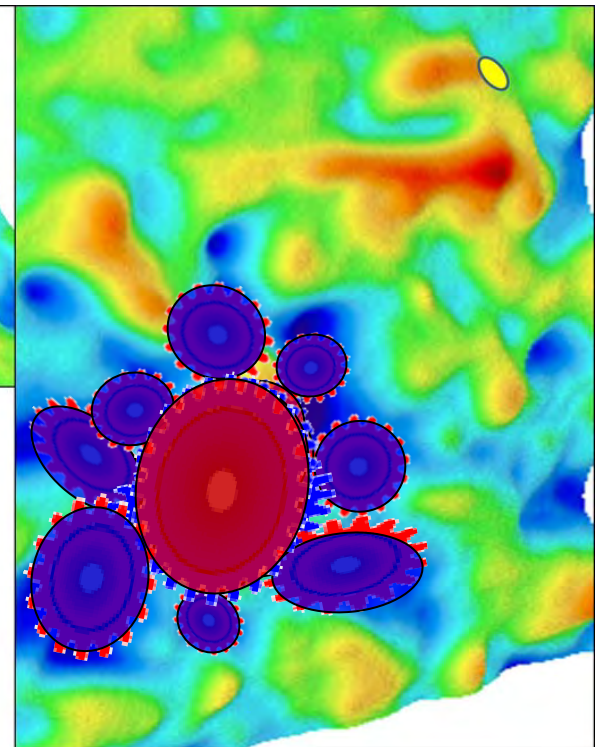
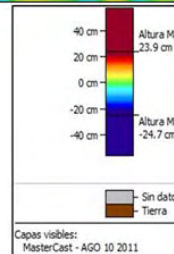
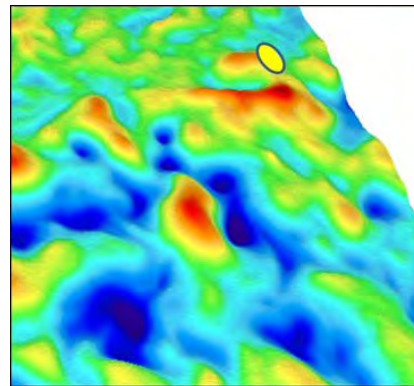
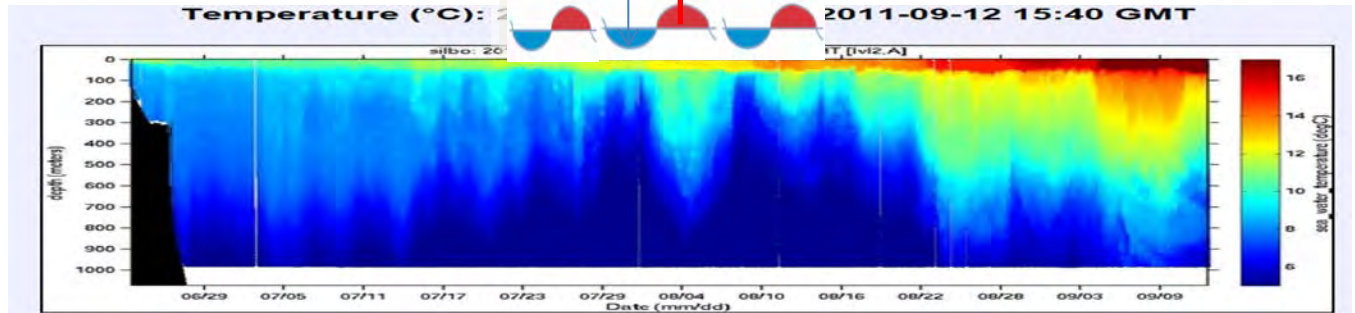
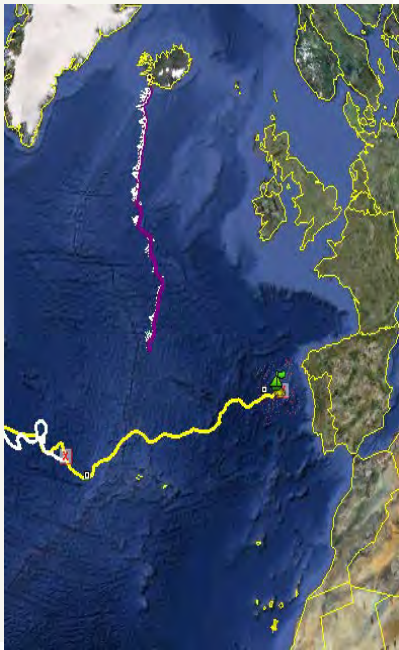
12 September 06.00 am

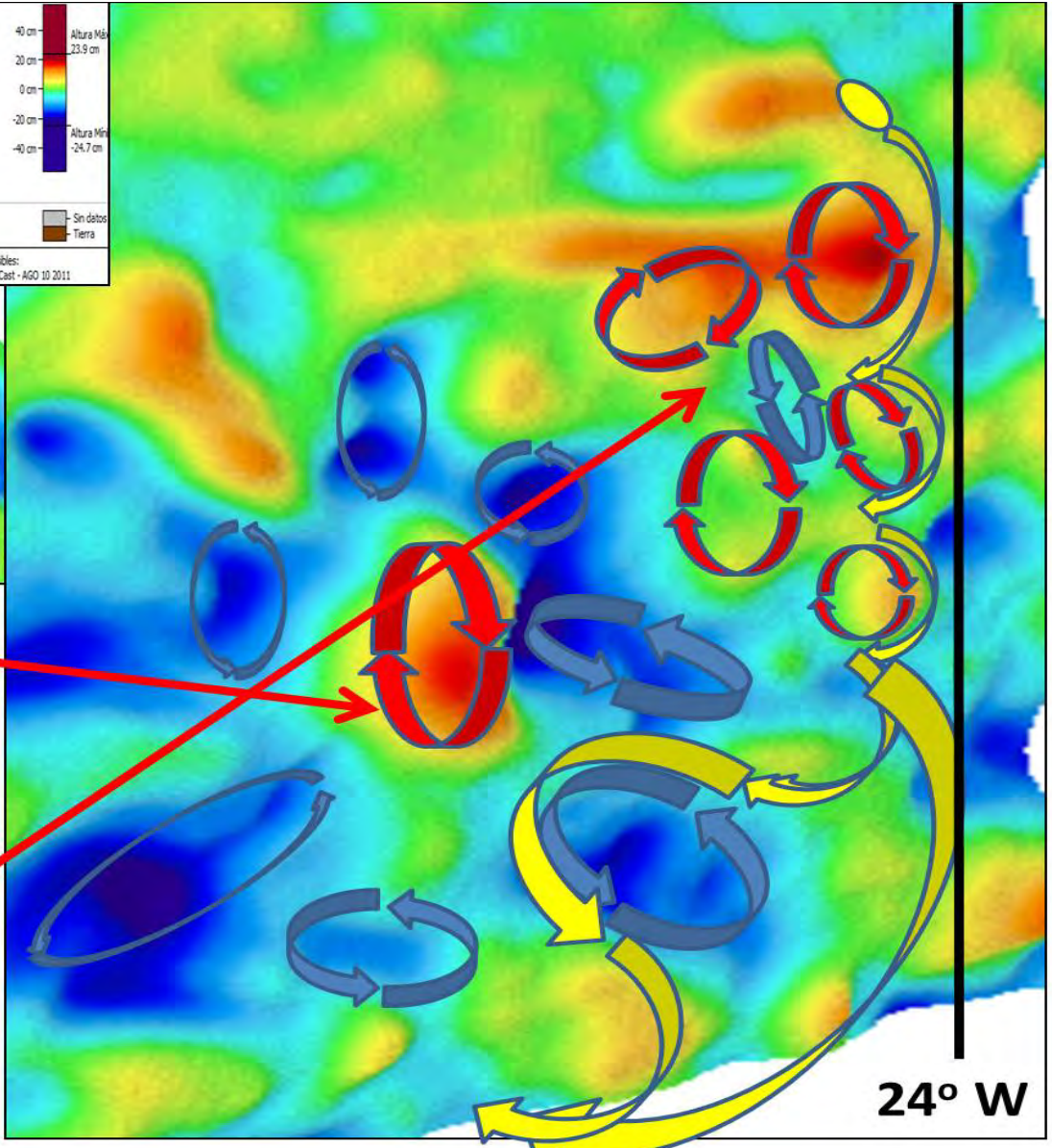
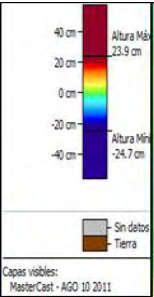
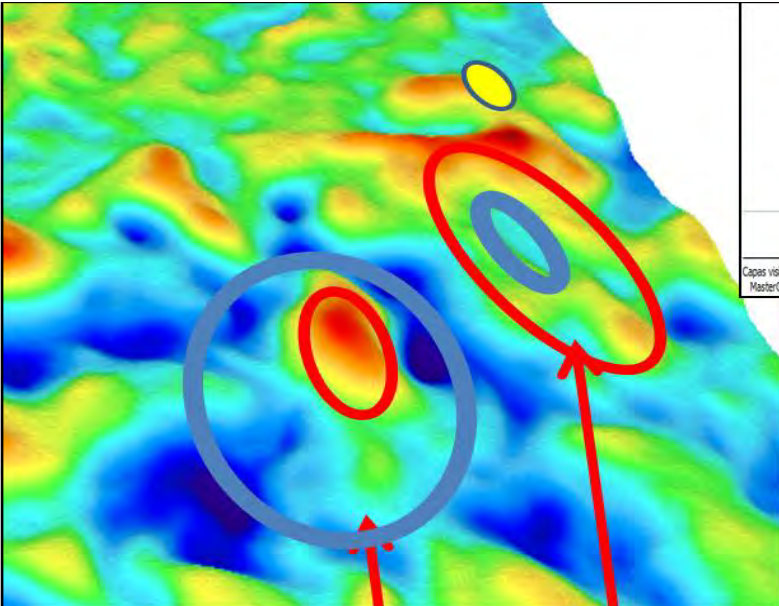
Temperature (°C): 2011-06-23 12:18 - 2011-09-13 07:19 GMT (Time Series)



Salinity (PSU): 2011-06-23 12:18 - 2011-09-13 07:19 GMT (Time Series)



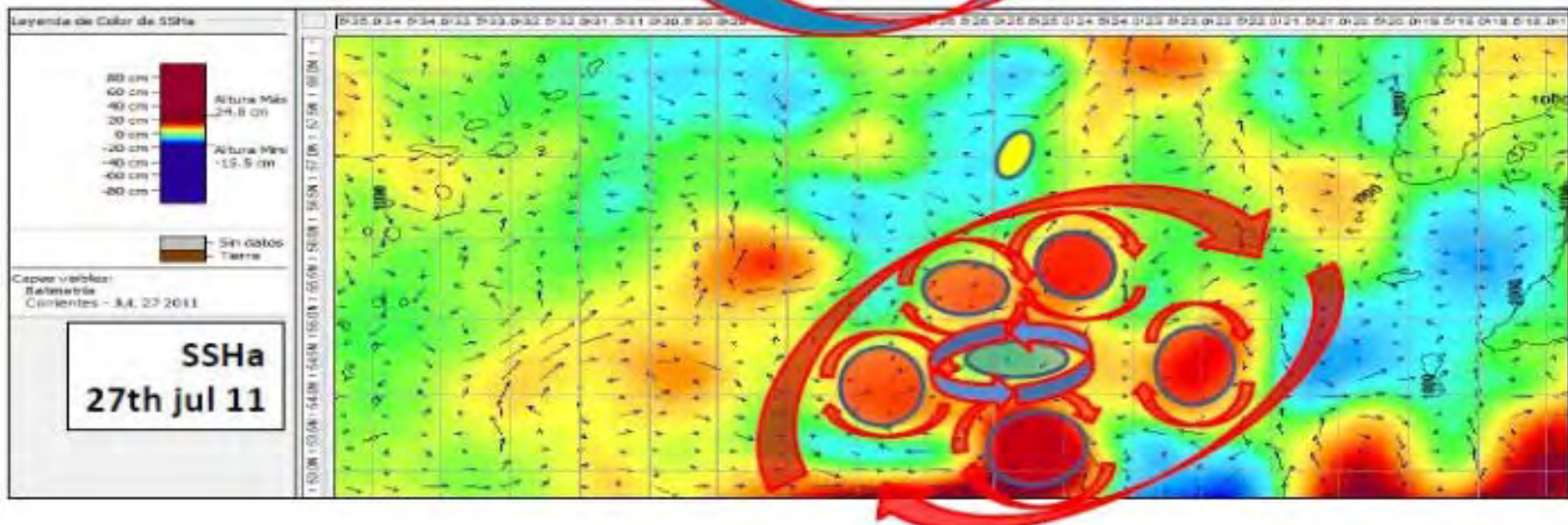
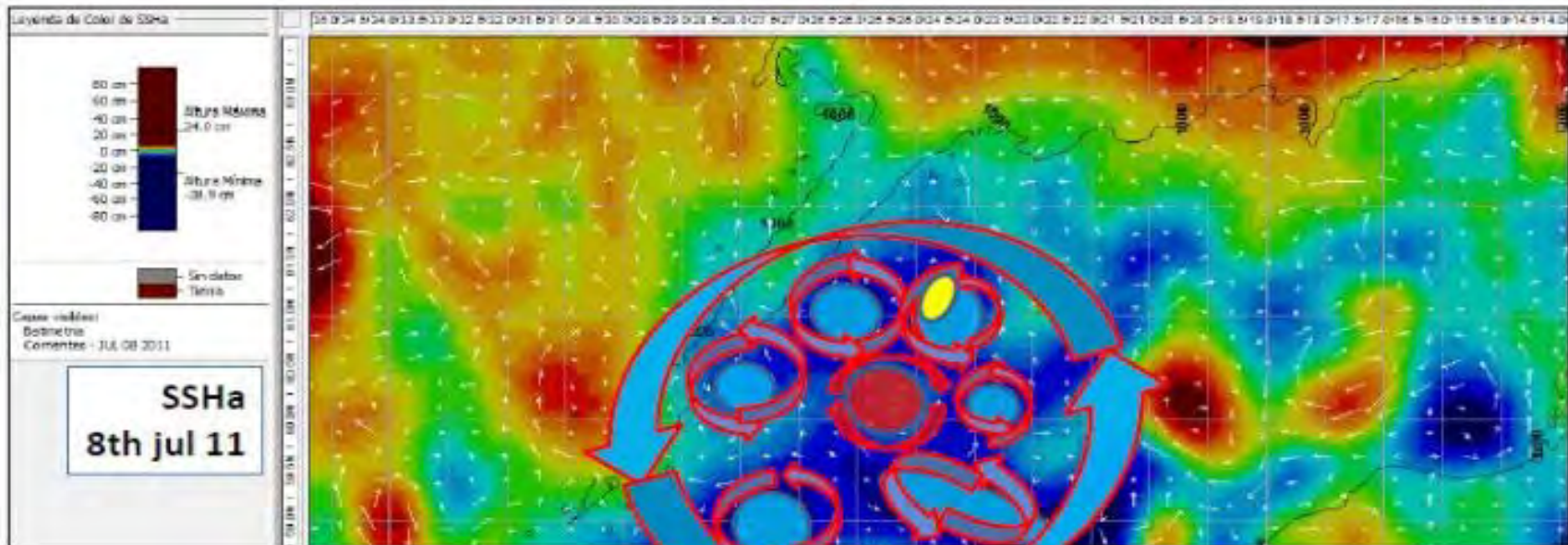


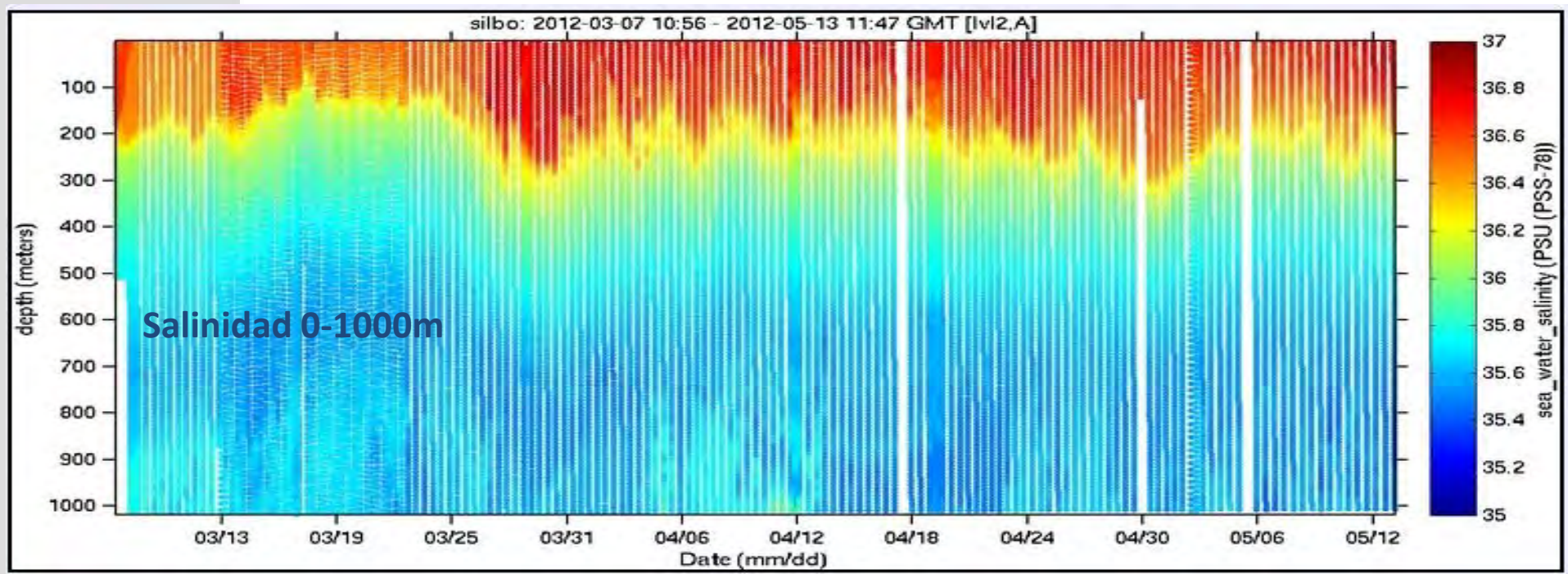
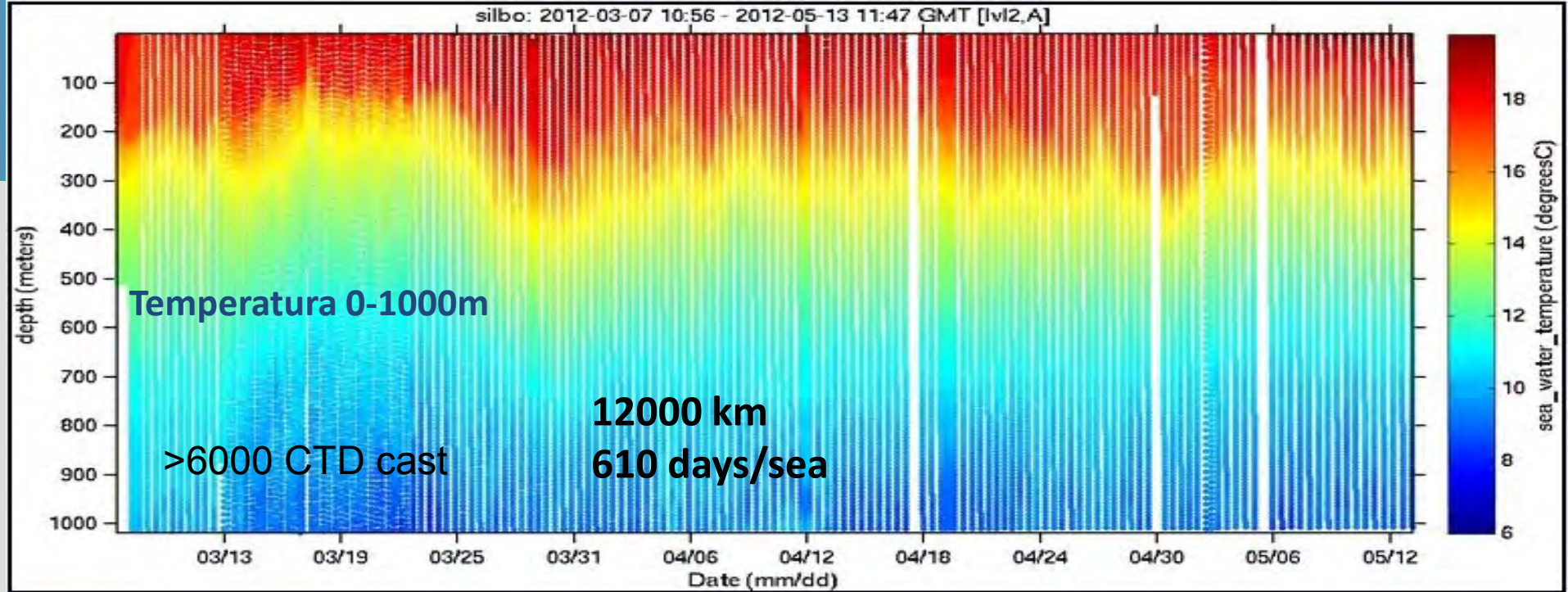


**Cold planets
&
warm sun**

**Warm planets
&
Cold sun**

24° W





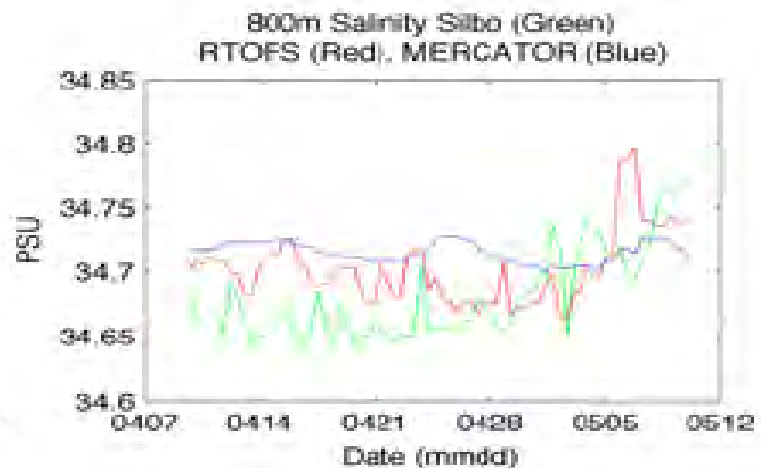
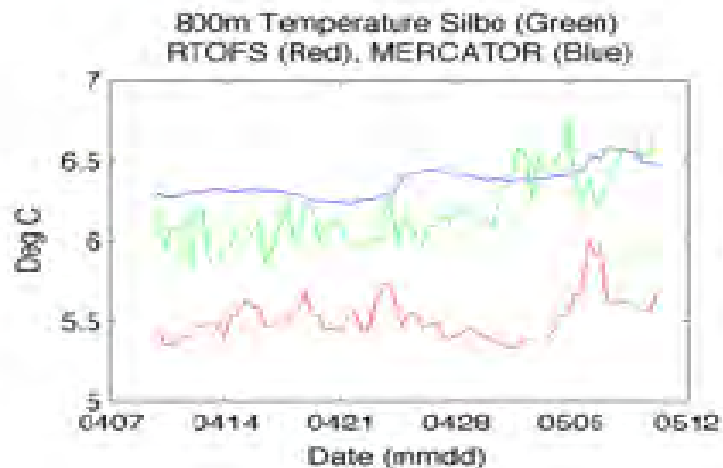
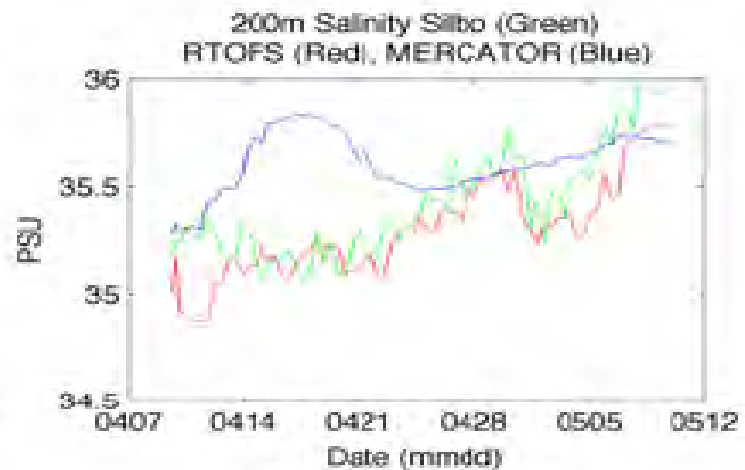
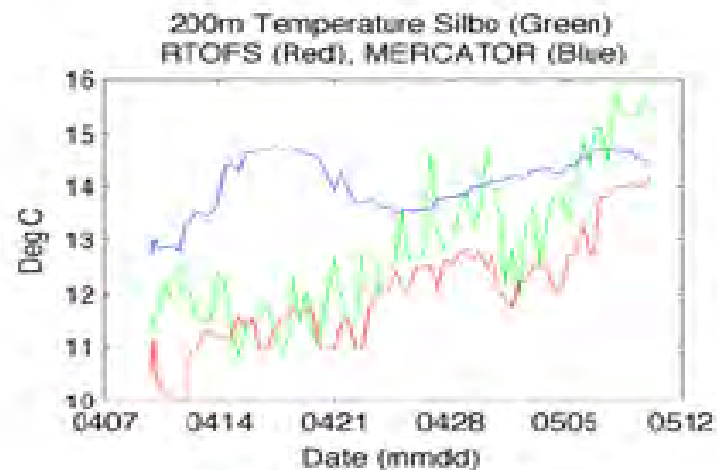


Figure 7: Comparisons of Silbo (green) with RTOFS (red) and MyOcean (blue) model data of temperature at 200m (top left), 800m (bottom left) and salinity at 200m (top right) and 800m (bottom right).

CHALLENGER 1 MISSION

RU-29 (“Challenger”): : 17400km 760 days

1st Circumnavigation Jan 2013 – Mar 2016

Cape Town (Sudáfrica) – Isla Ascensión (UK) - Brasil



The bear is in the igloo

Cape of Good hope . R/V Algoa 31 March 2016



9/11/2013
8/2013 5/2014

Last Surfacing
Deployment Location

0.25403739 m/s

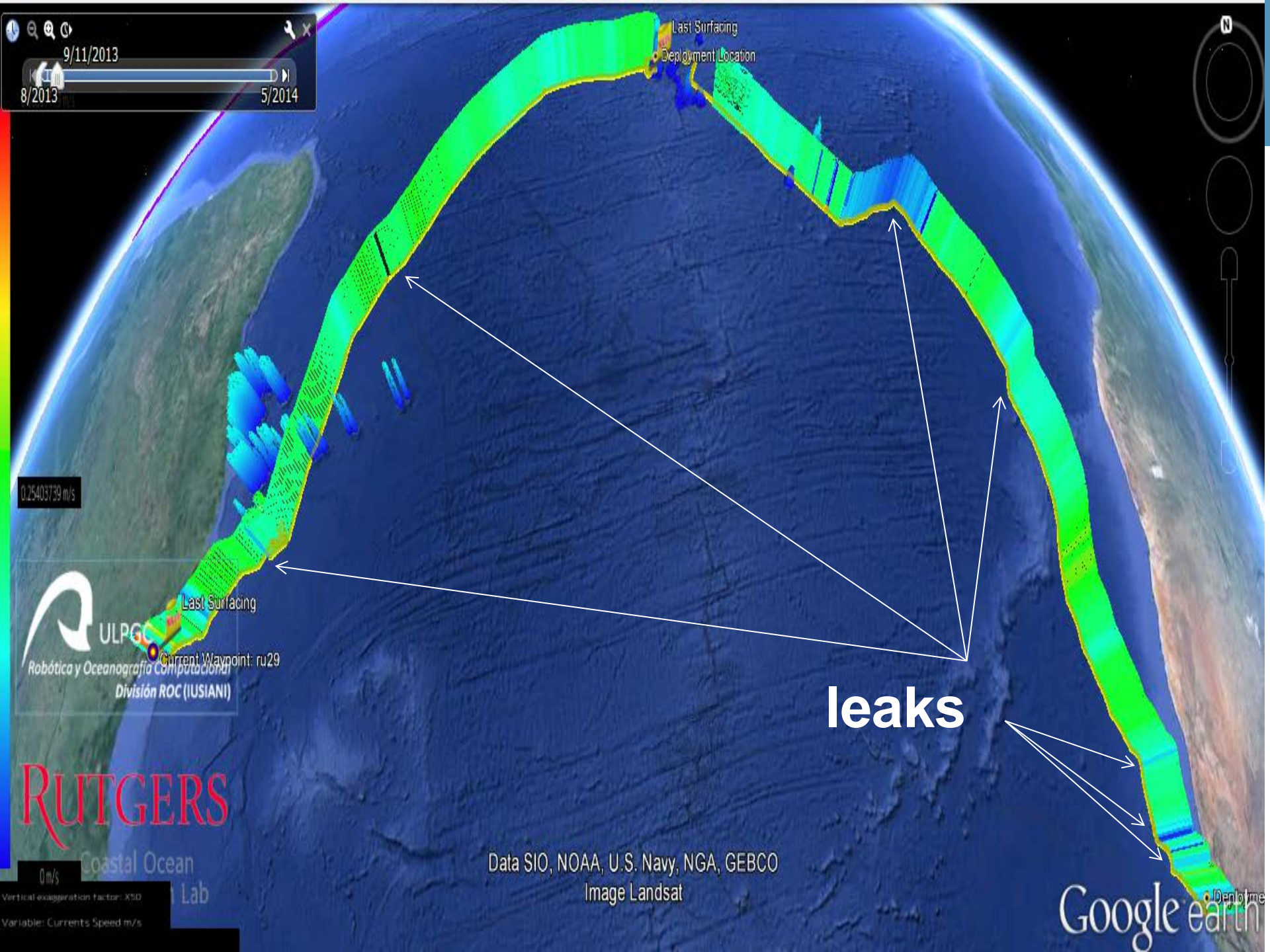
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División ROC (IUSIANI)

RUTGERS
Coastal Ocean
Lab

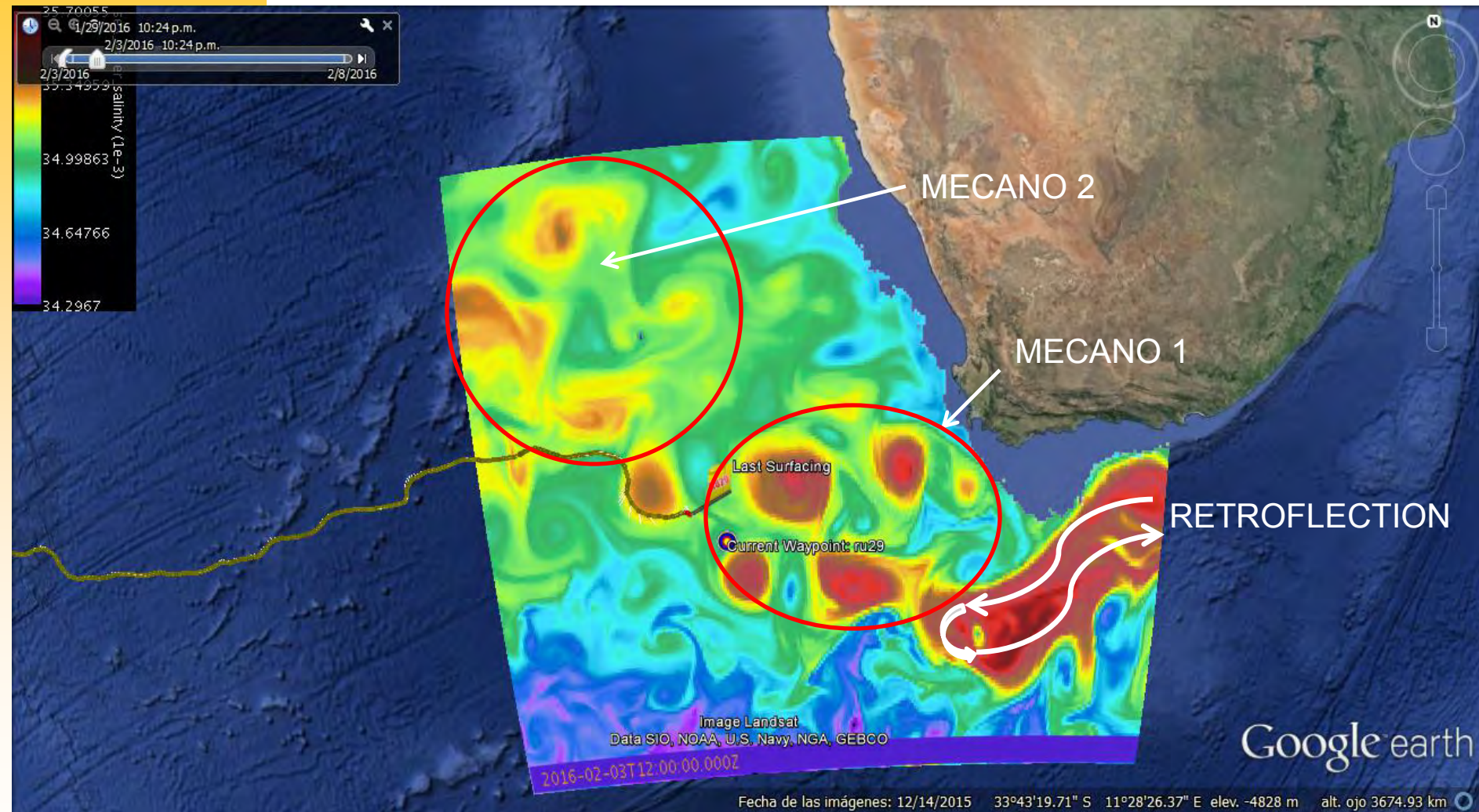
Data SIO, NOAA, U.S. Navy, NGA, GEBCO
Image Landsat

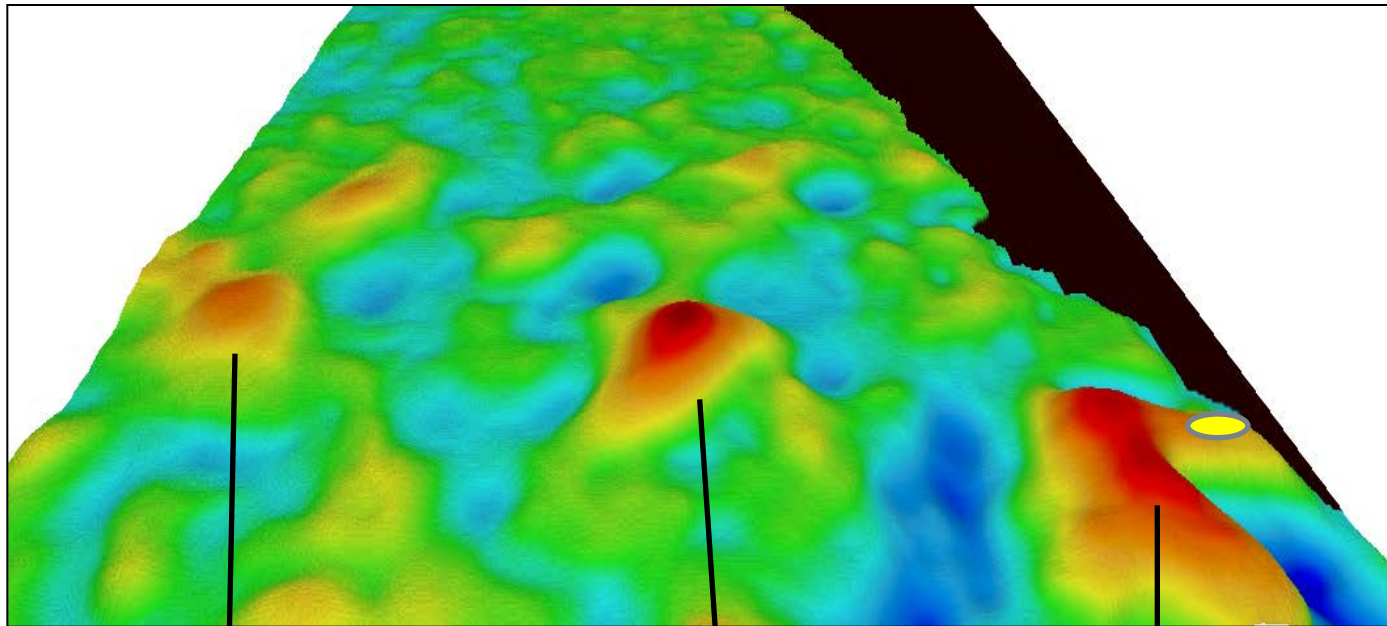
leaks

Google earth

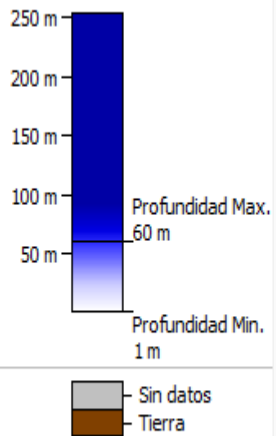


SALINITY FIELD 260m depth. 8th February 2016

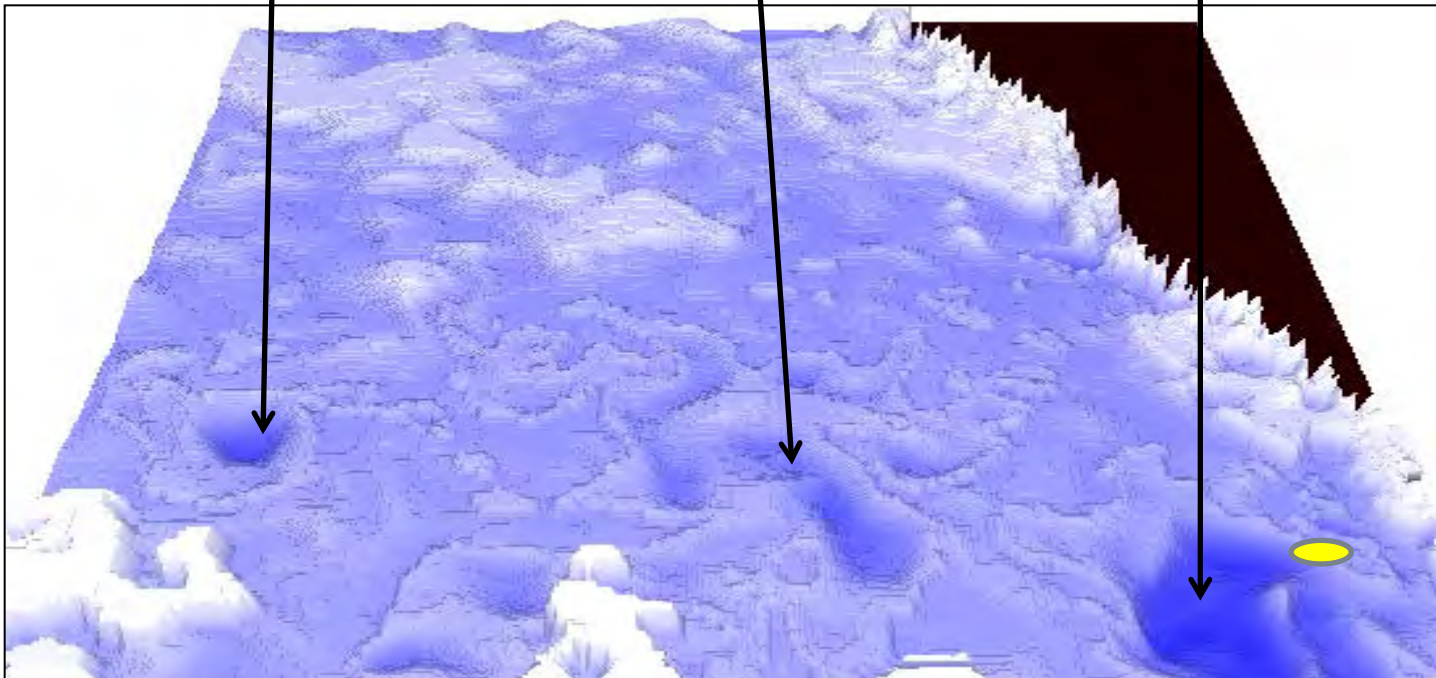


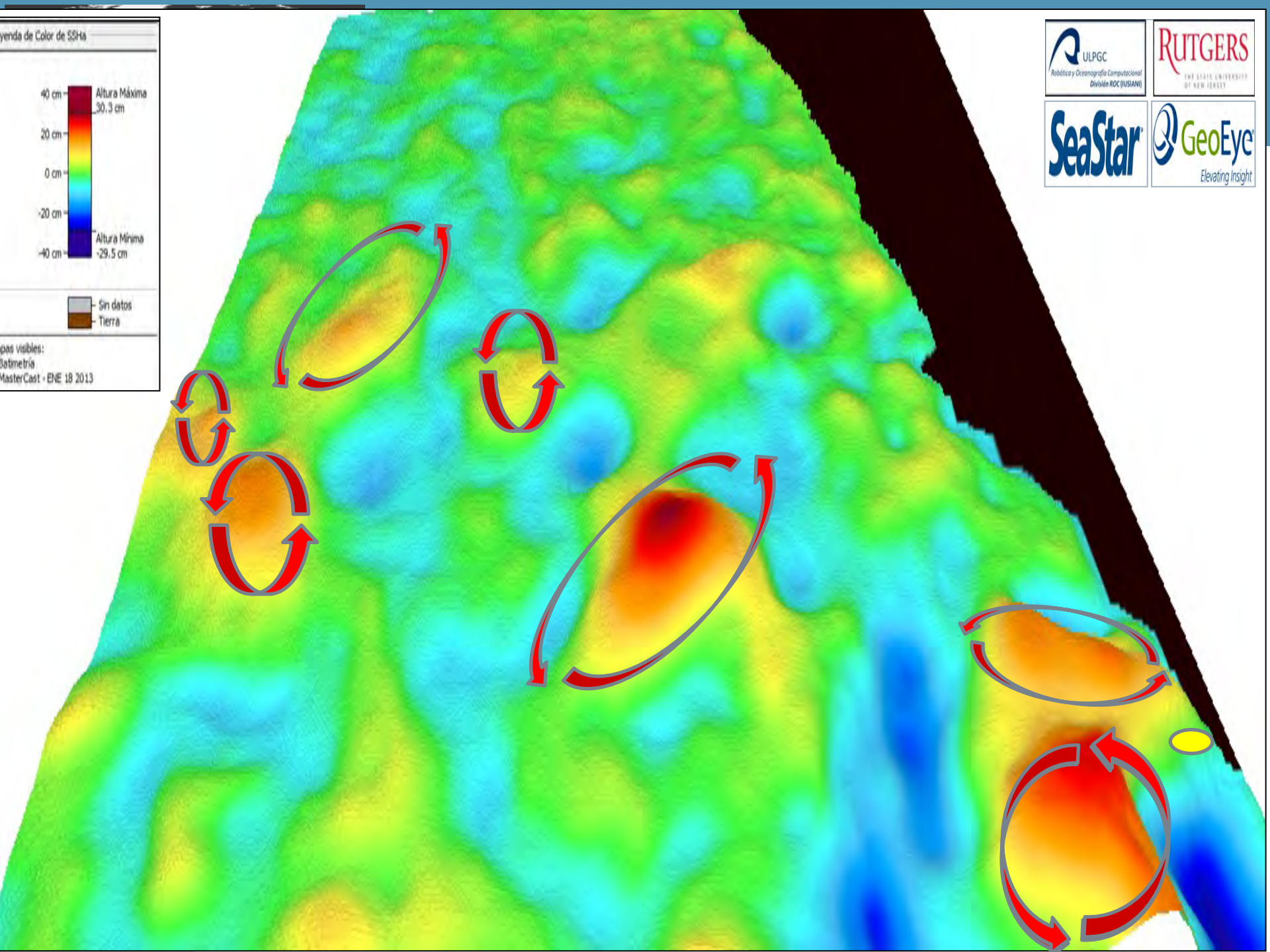
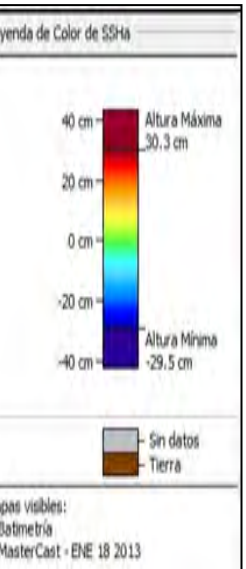


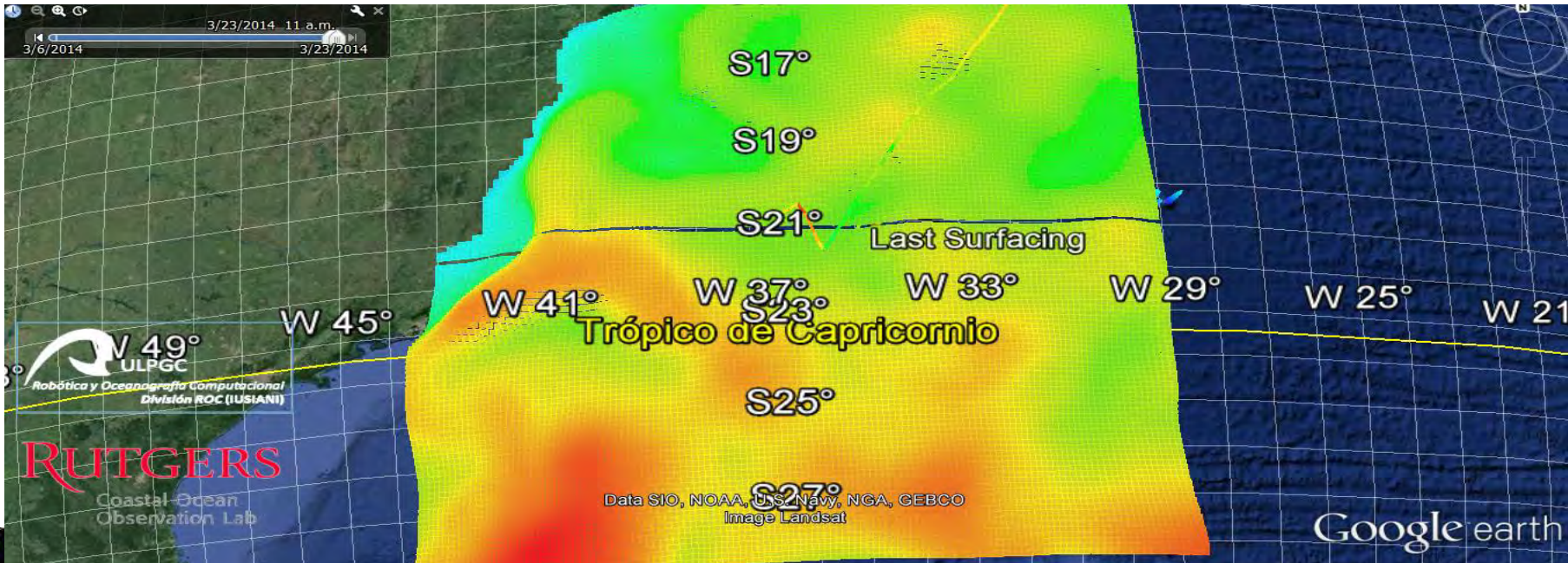
Leyenda de Profundidad de Termoclina



Capas visibles:
 Vista 3-D - ----
 Corrientes - ENE 21 2013
 MasterCast - ENE 21 2013





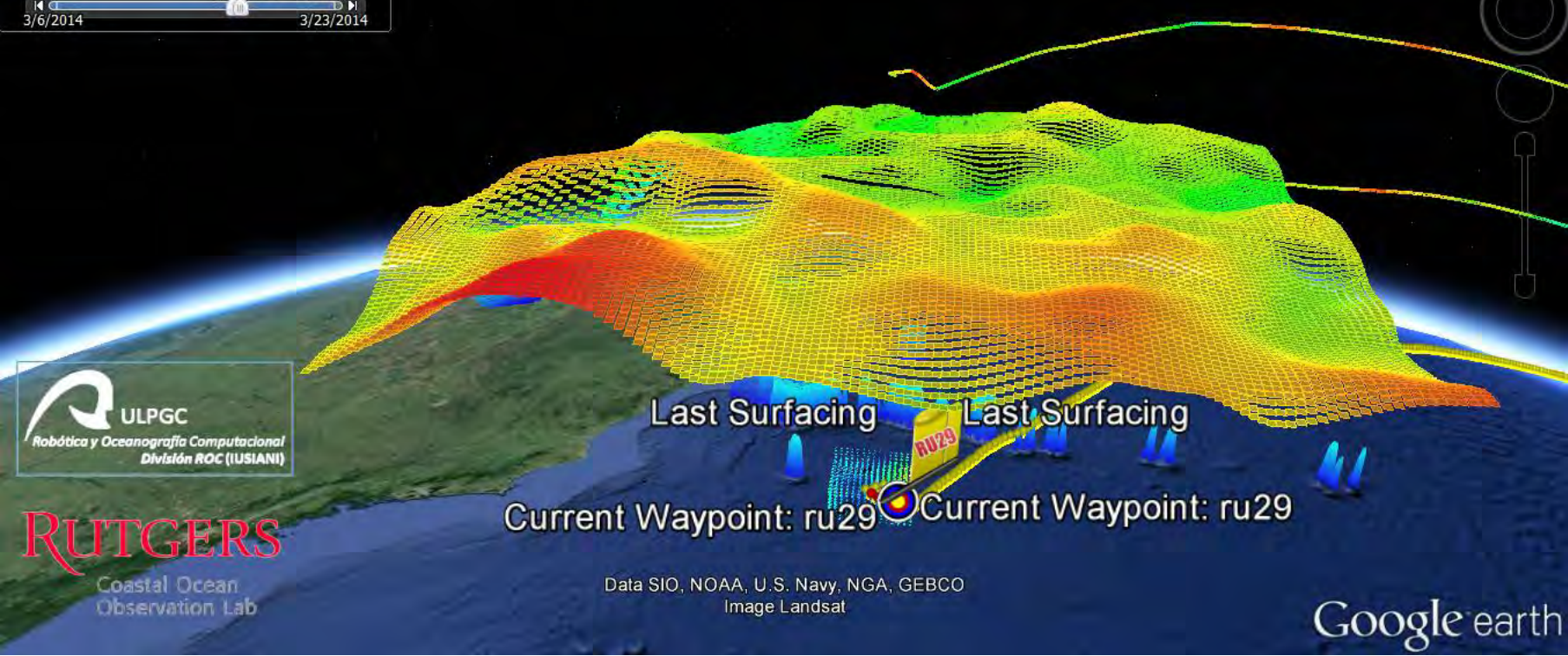


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Coastal Ocean
Observation Lab

Google earth

3/6/2014 3/23/2014



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Coastal Ocean
Observation Lab

Data SIO, NOAA, U.S. Navy, NGA, GEBCO
Image Landsat

Google earth

0.47389143 m/s

0.23725090 m/s
0.473891 m/s @ 2015-10-29 21:48:57, -35.833332°, -16.5°, -10m

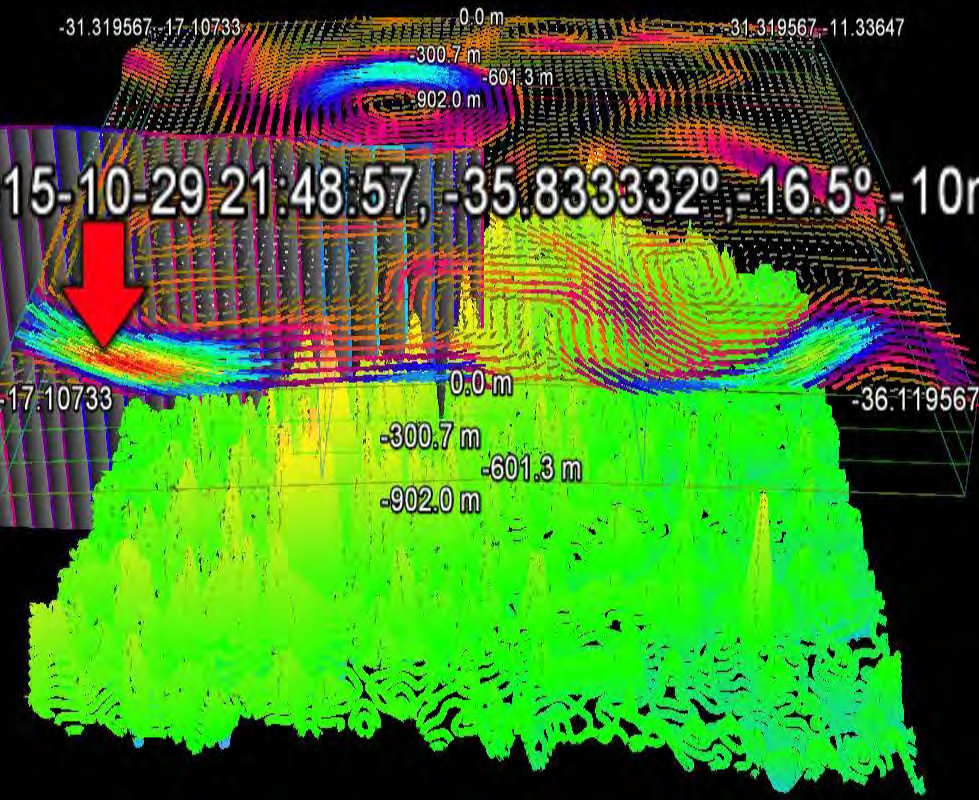
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División ROC (IUSIANI)

RUTGERS
Coastal Ocean
Observation Lab

0.00061037 m/s

Vertical exaggeration factor: X50
Variable: Currents speed

Data from: 2015-10-28 12:00:00 To: 2015-10-30 11:59:48 UTC

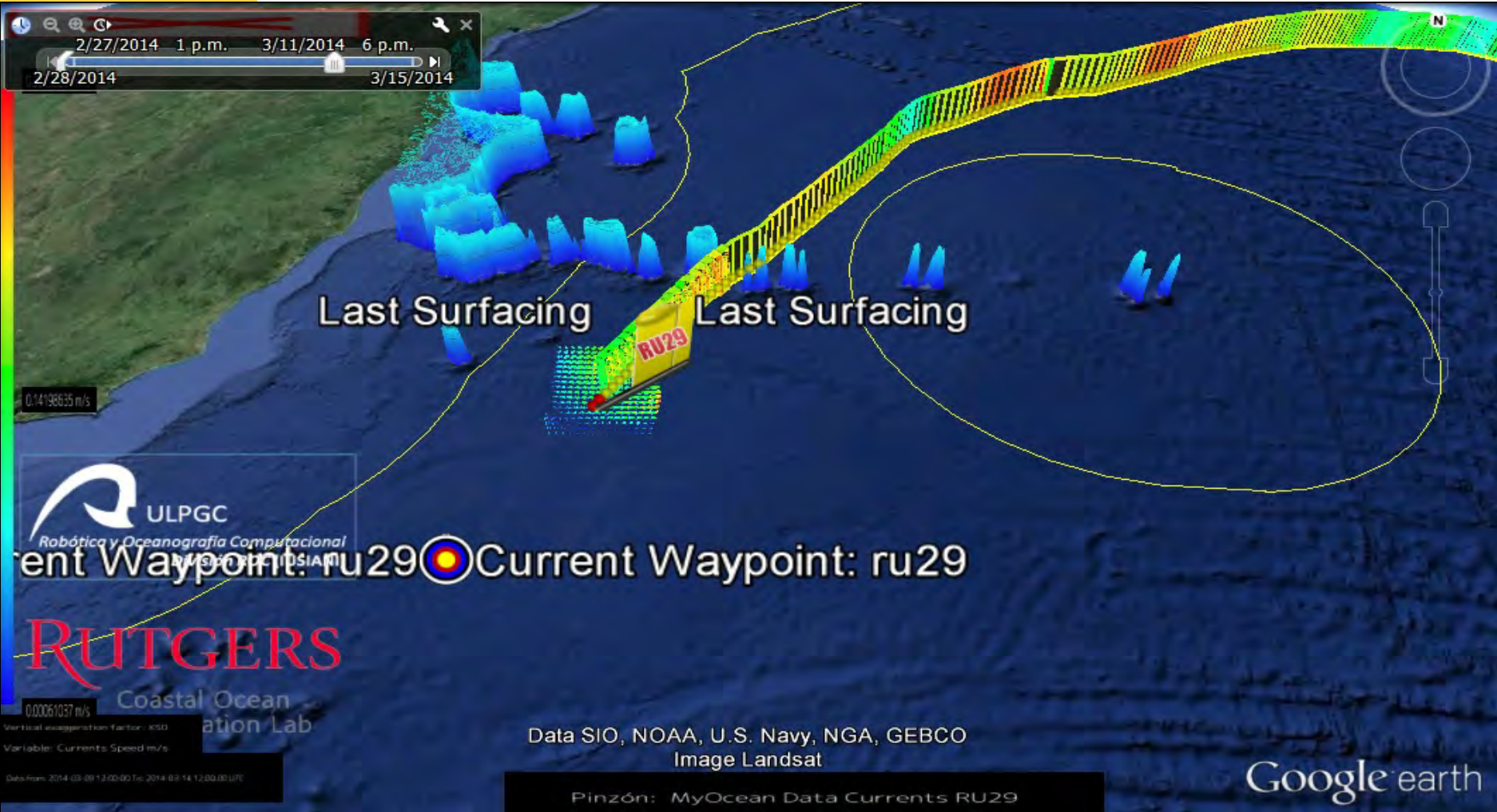


Data SIO, NOAA, U.S. Navy, NGA, GEBCO
Data IODE, Columbia, NSF, NOAA

RU29 Currents

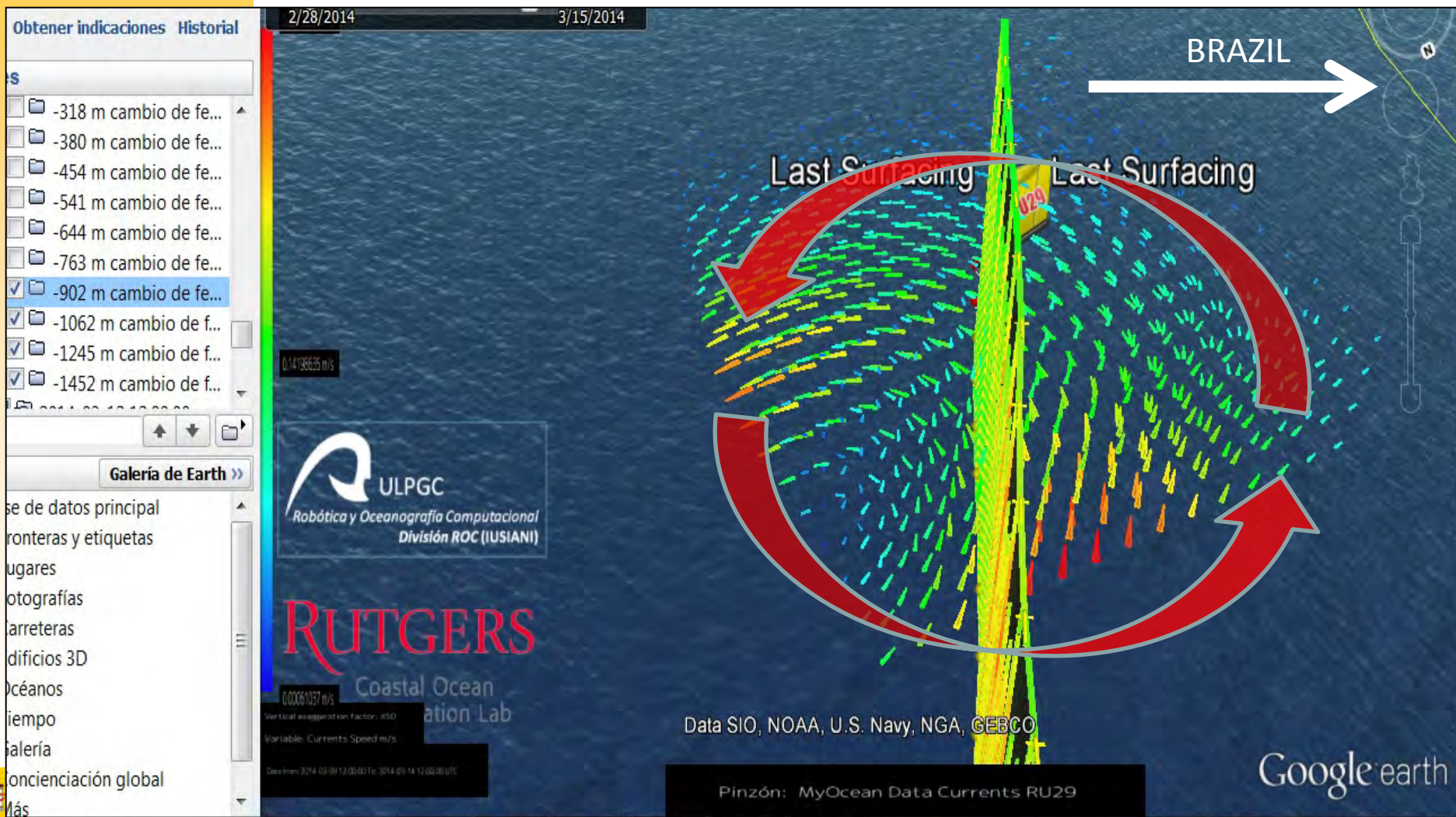
Google earth

AFTER MORDOR....



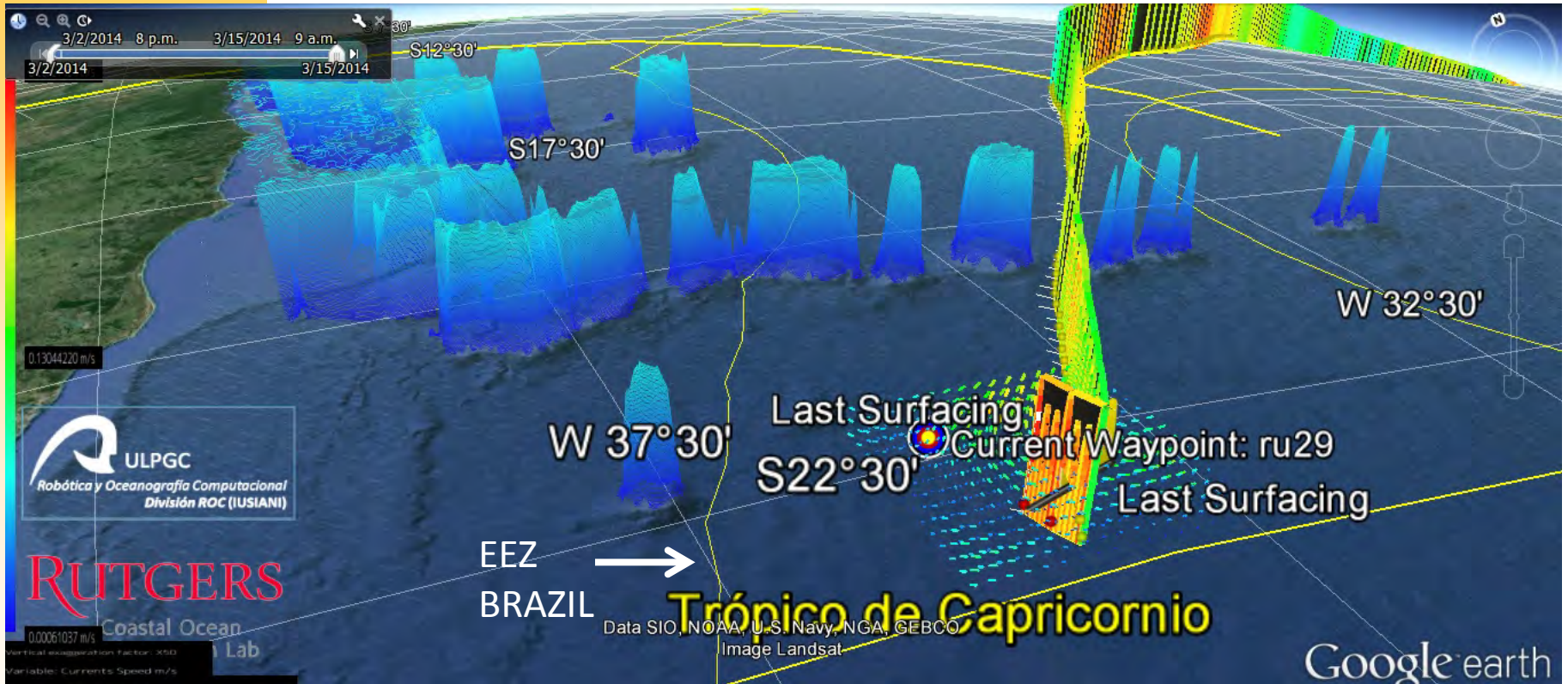
MYOCEAN (800m-1000m) 11 mar 2014

(800m-1000m), 0.3 m/s

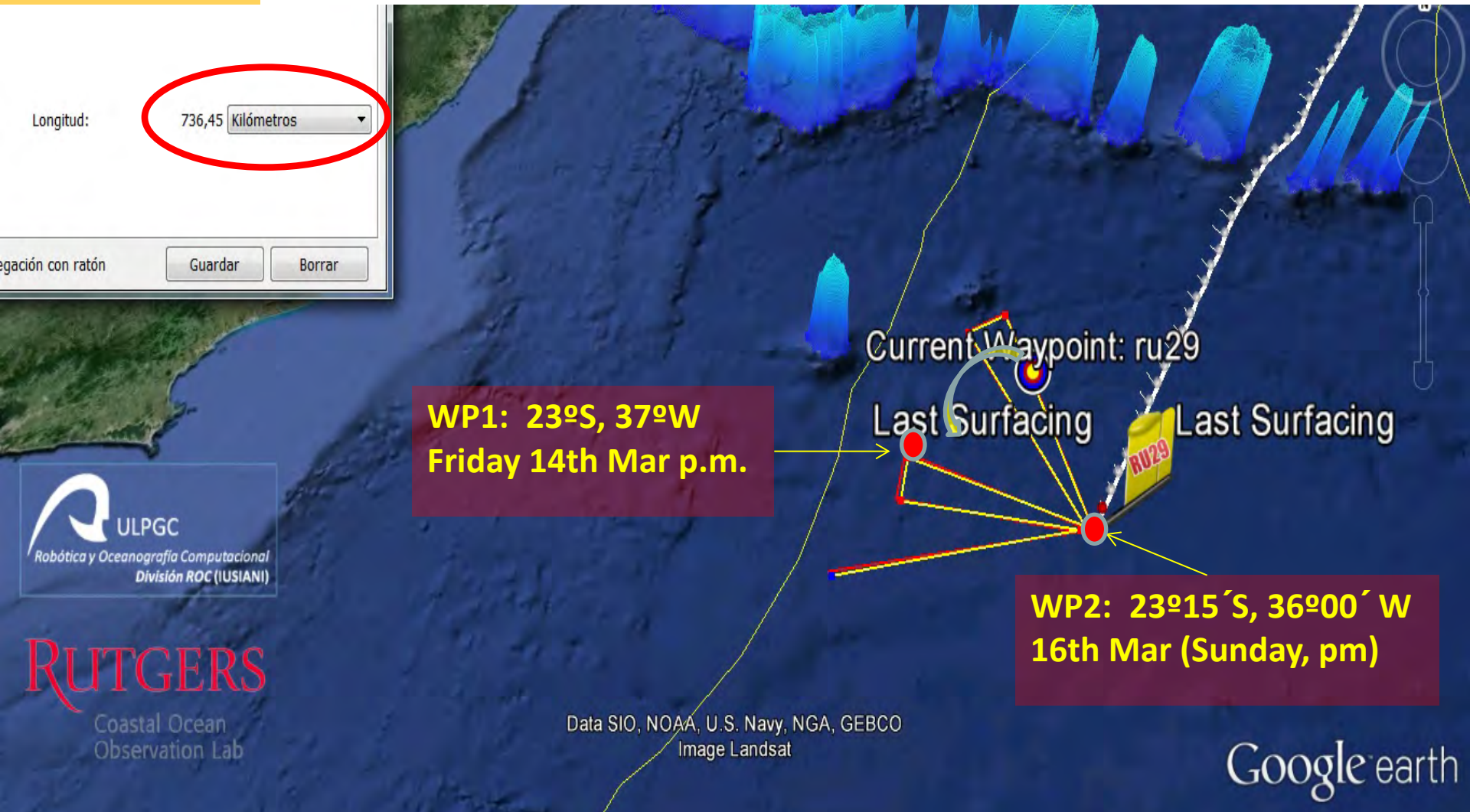


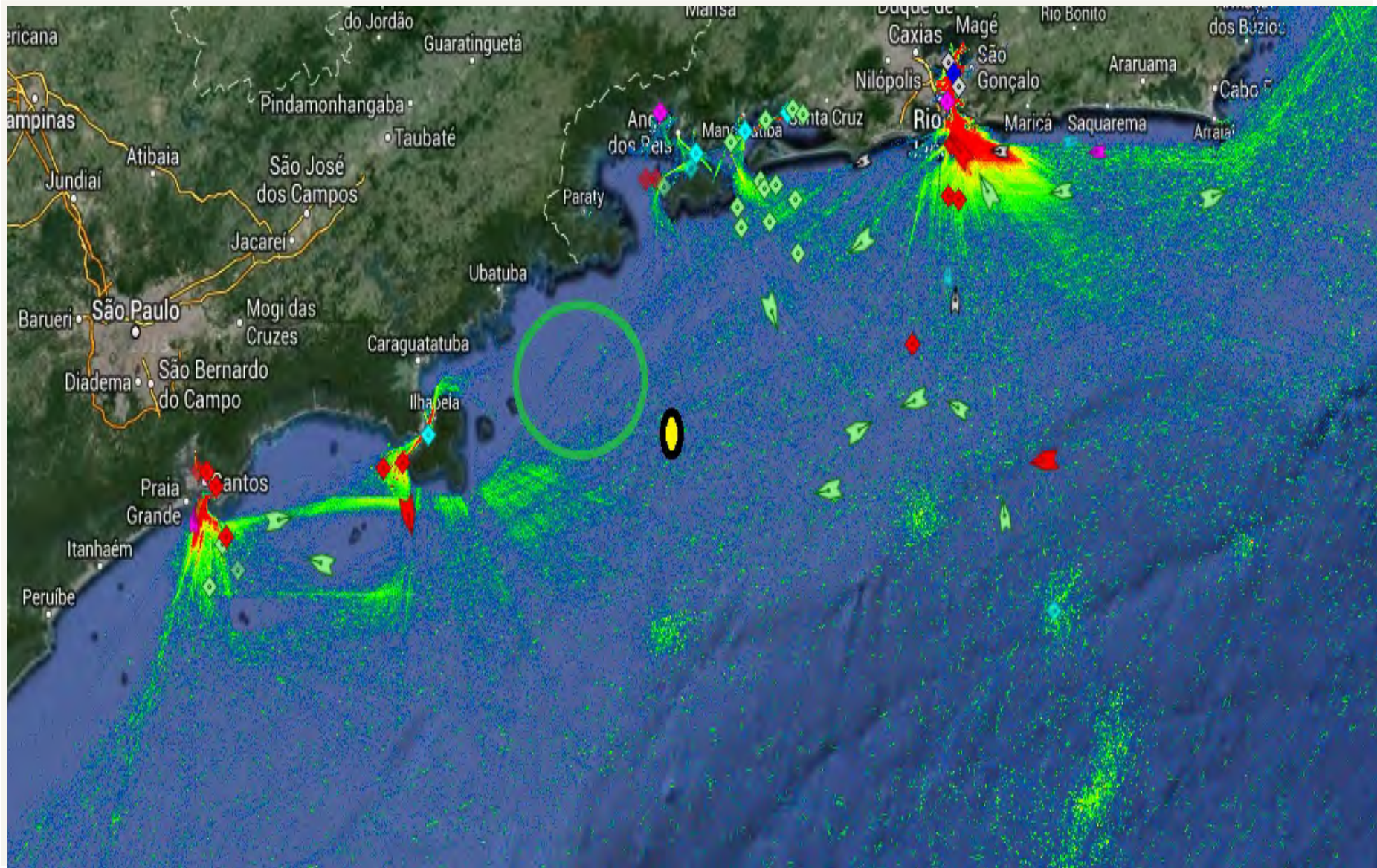
MYOCEAN (800m-1000m) 13, 14 mar 2014

A DEEP **WARM EDDY** >800m, 0.25 m/s

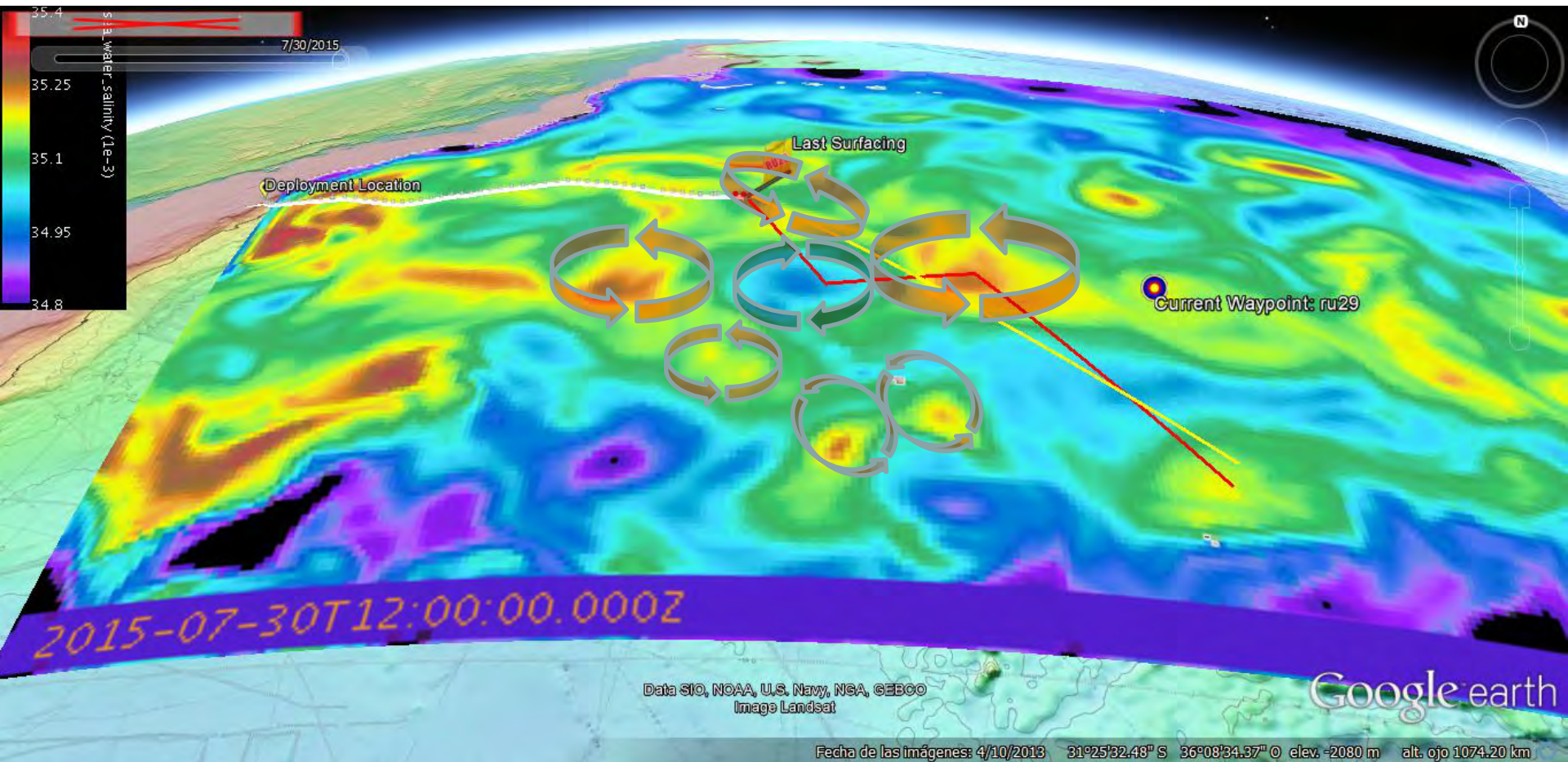


THE NEXT

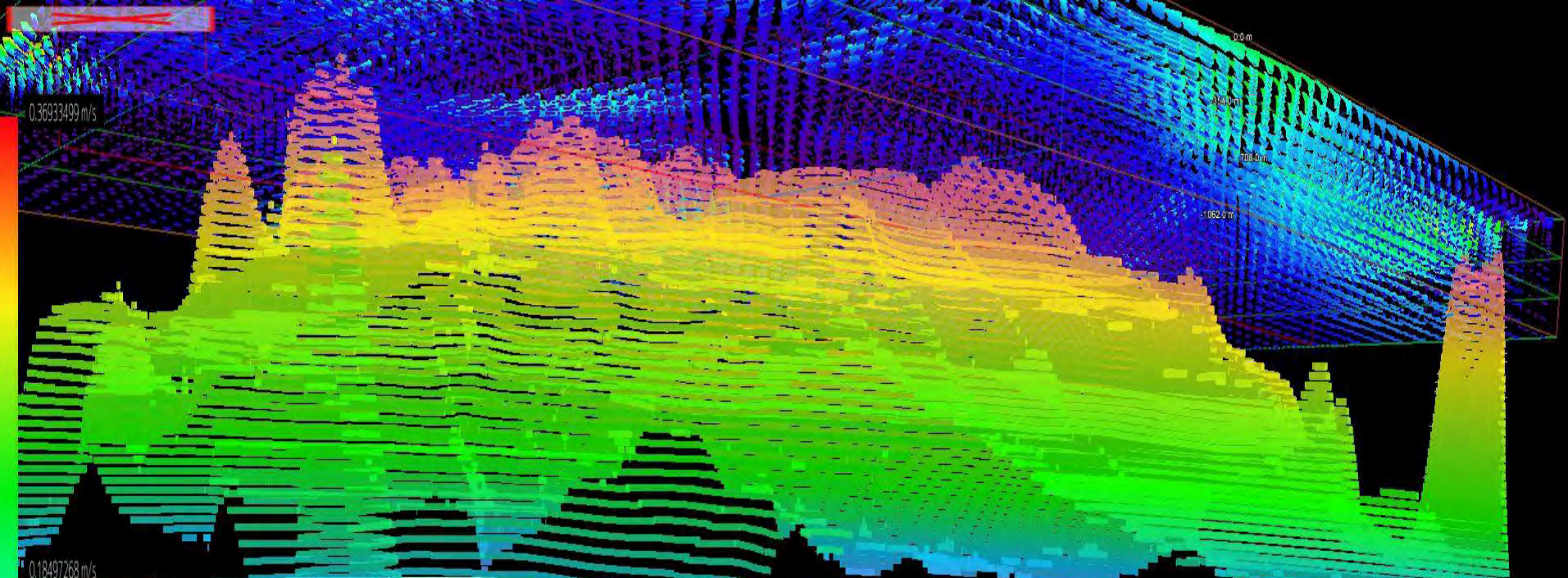




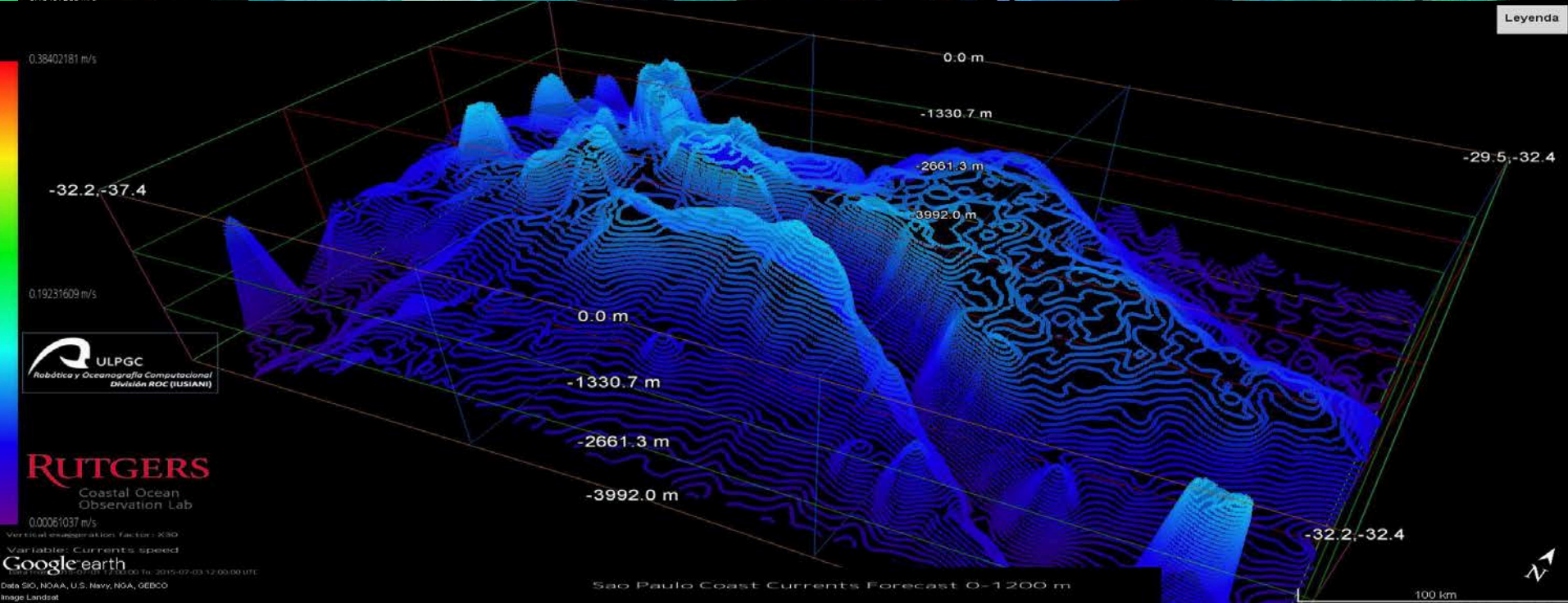
THE LORD OF THE RINGS.....



**SALINITY FIELD (430m. Copernicus/MyOcean, 30july 2015)
Solar System (cold eddy + warm eddies).**



Leyenda



ULPGC
Robótica y Oceanografía Computacional
División ROC (IUSIAN)

RUTGERS
Coastal Ocean
Observation Lab

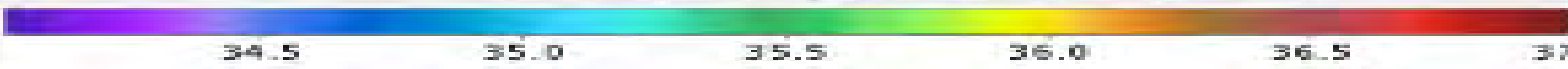
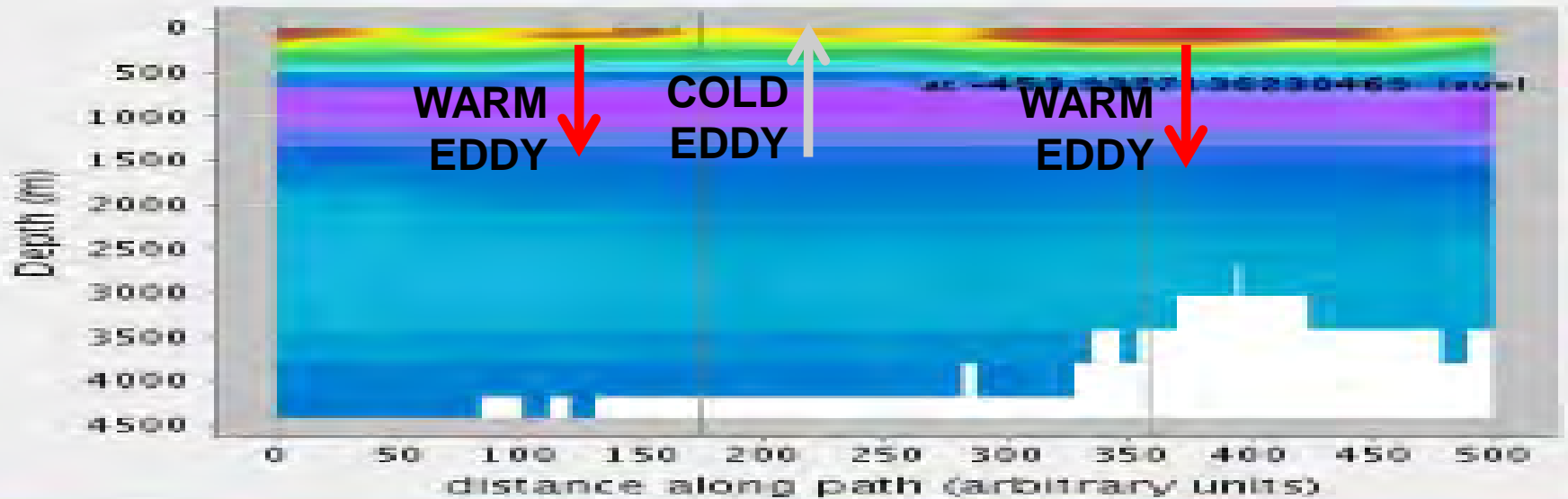
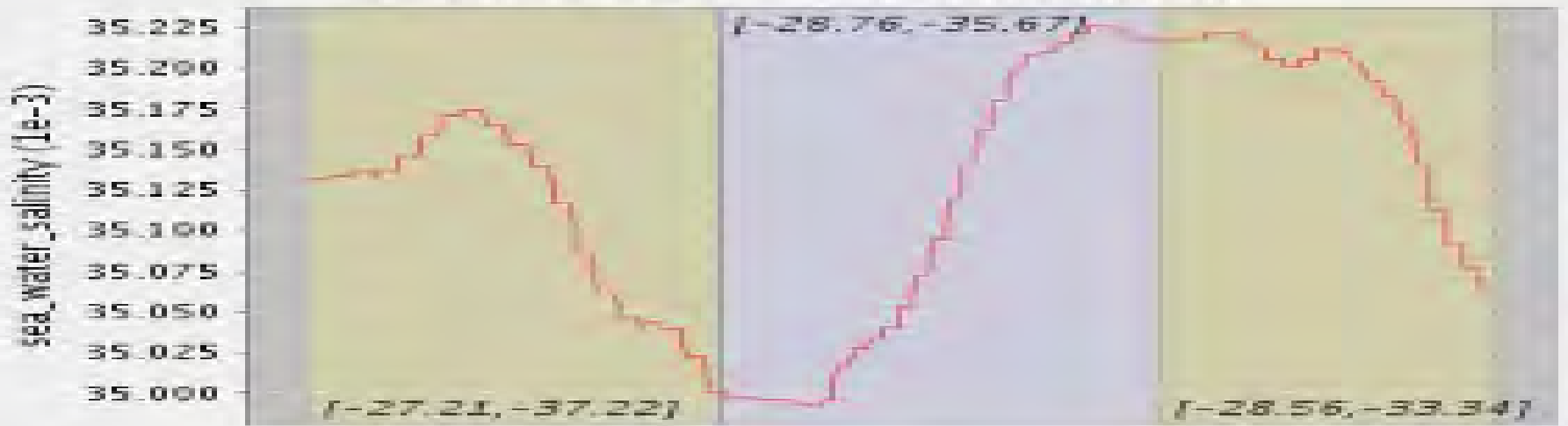
Google earth
Data SIO, NOAA, U.S. Navy, NGA, GEBCO
Image Landsat

Sao Paulo Coast Currents Forecast 0-1200 m

100 km

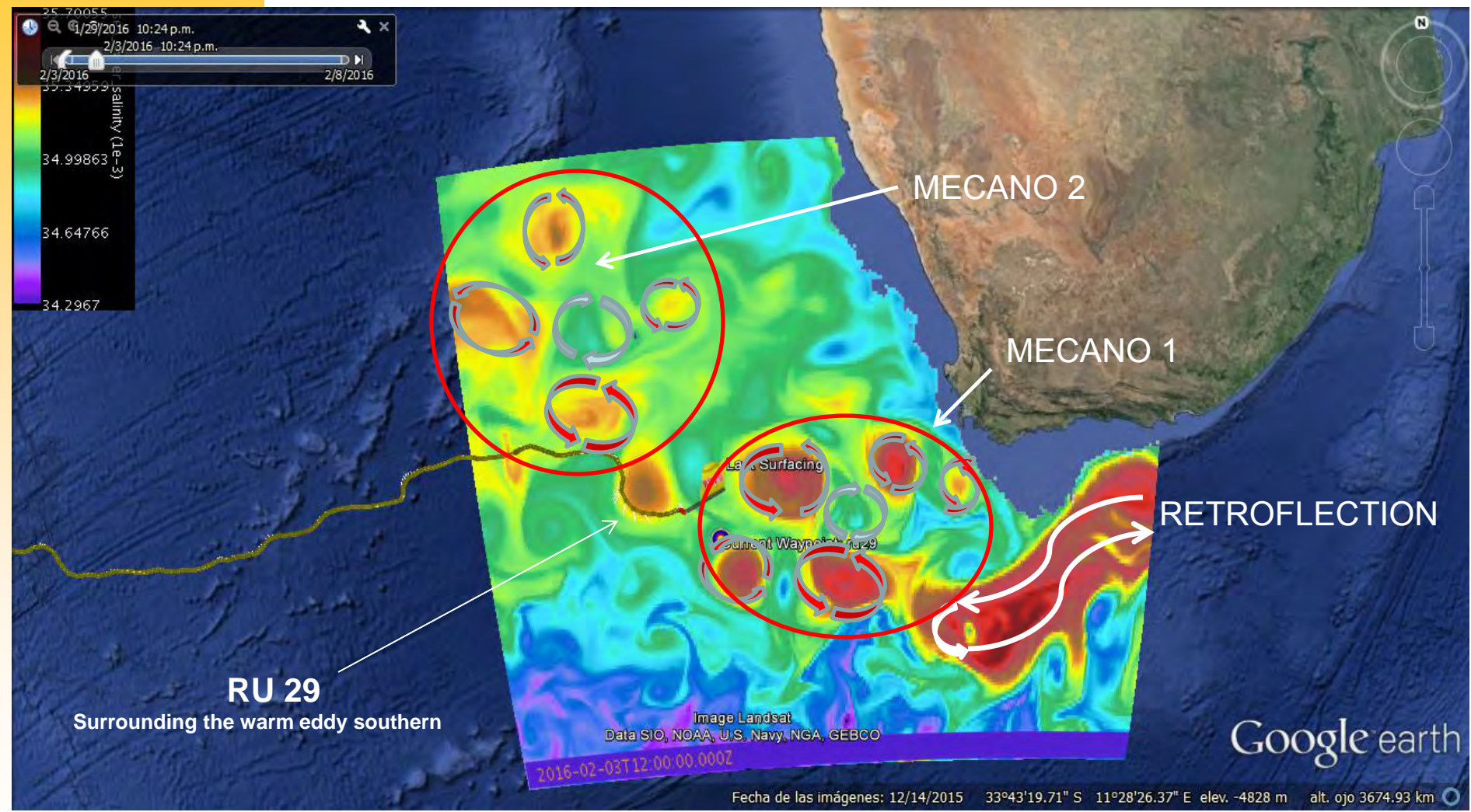


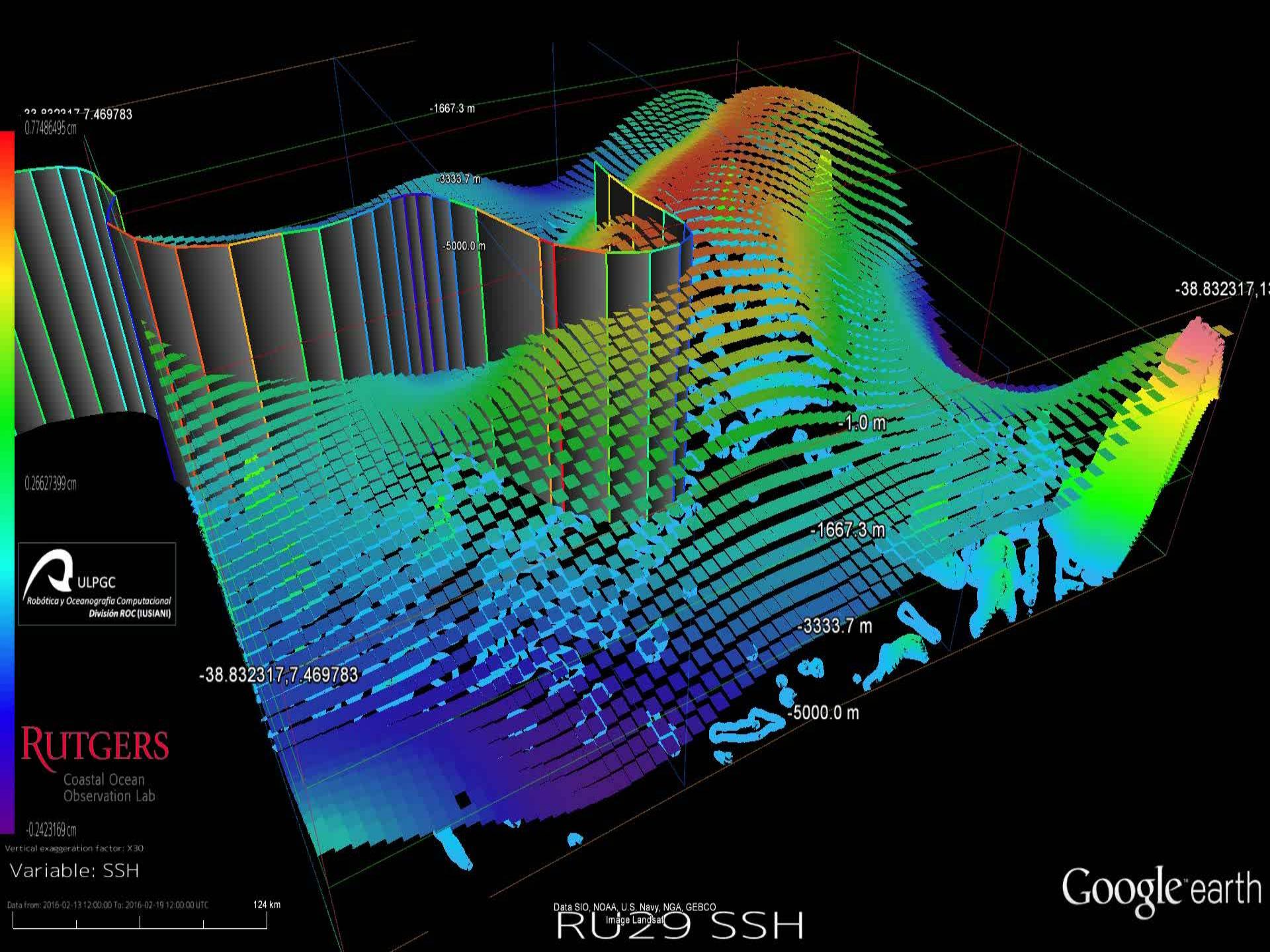
sea_water_salinity (1e-3) at -453.9377136230469m



SALINITY Transect (red path) Copernicus/MyOcean, 30 July 2015)

SALINITY FIELD 260m depth. 8th February 2016





0.77486495 cm

-1667.3 m

-3333.7 m

-5000.0 m

-38.832317, 1

0.26627399 cm

-1.0 m

-1667.3 m

-3333.7 m

-38.832317, 7.469783

-5000.0 m



Vertical exaggeration factor: X30

Variable: SSH

Data from: 2016-02-13 12:00:00 To: 2016-02-19 12:00:00 UTC

124 km

Data SIO, NOAA, U.S. Navy, NGA, GEBCO
Image Landsat

RU29 SSH

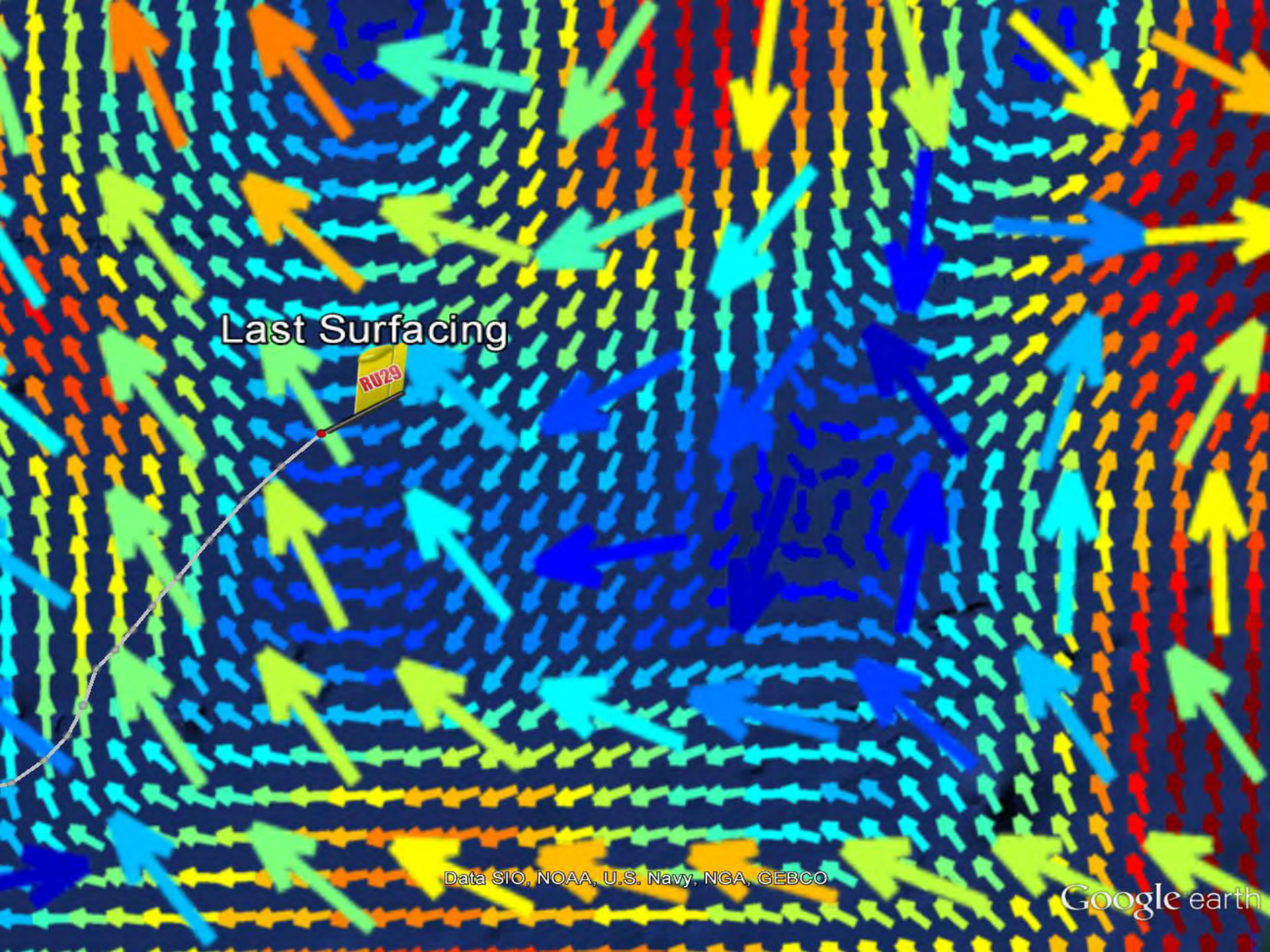


Last Surfacing

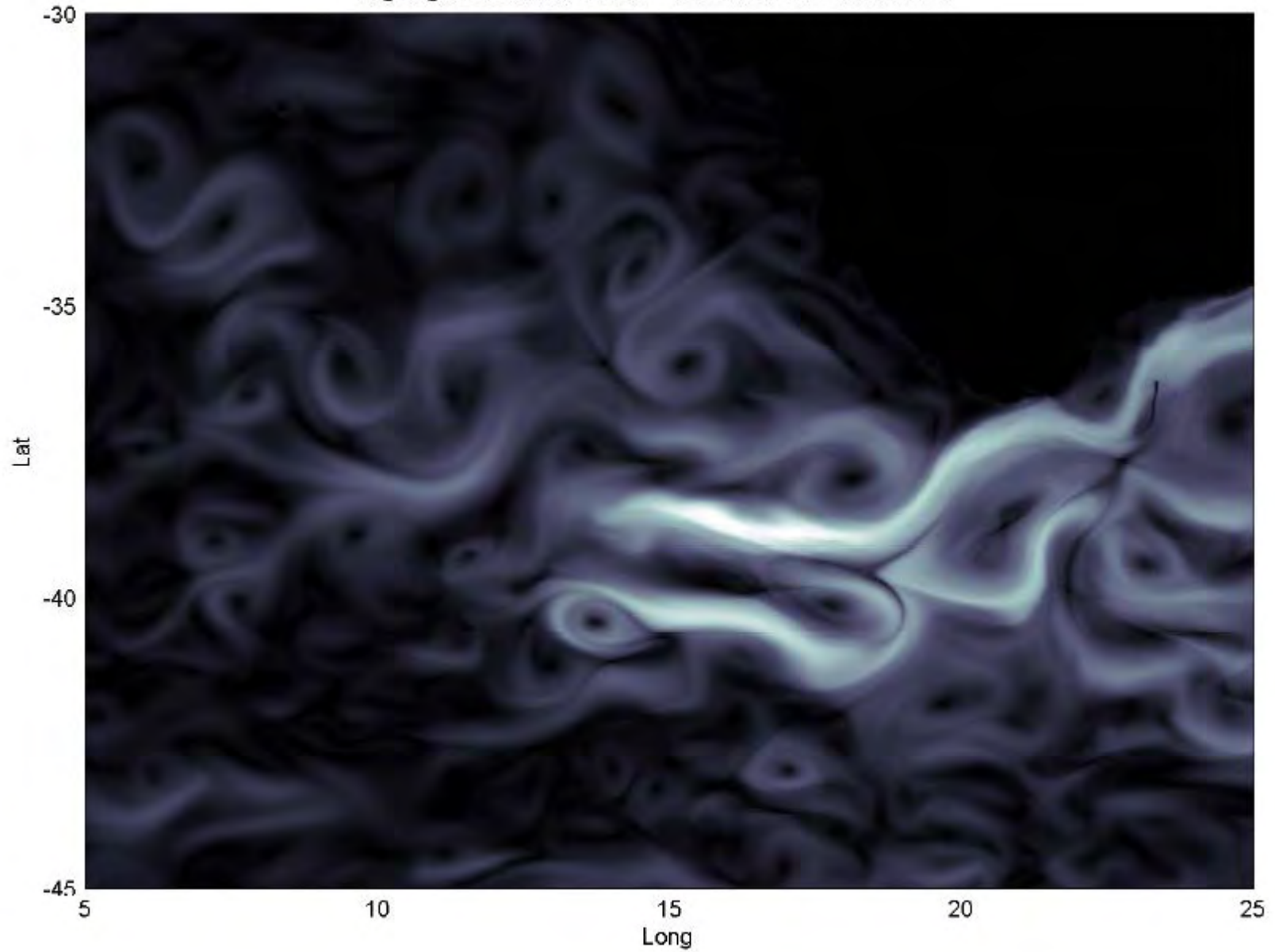
RU29

Data SIO, NOAA, U.S. Navy, NGA, GEBCO

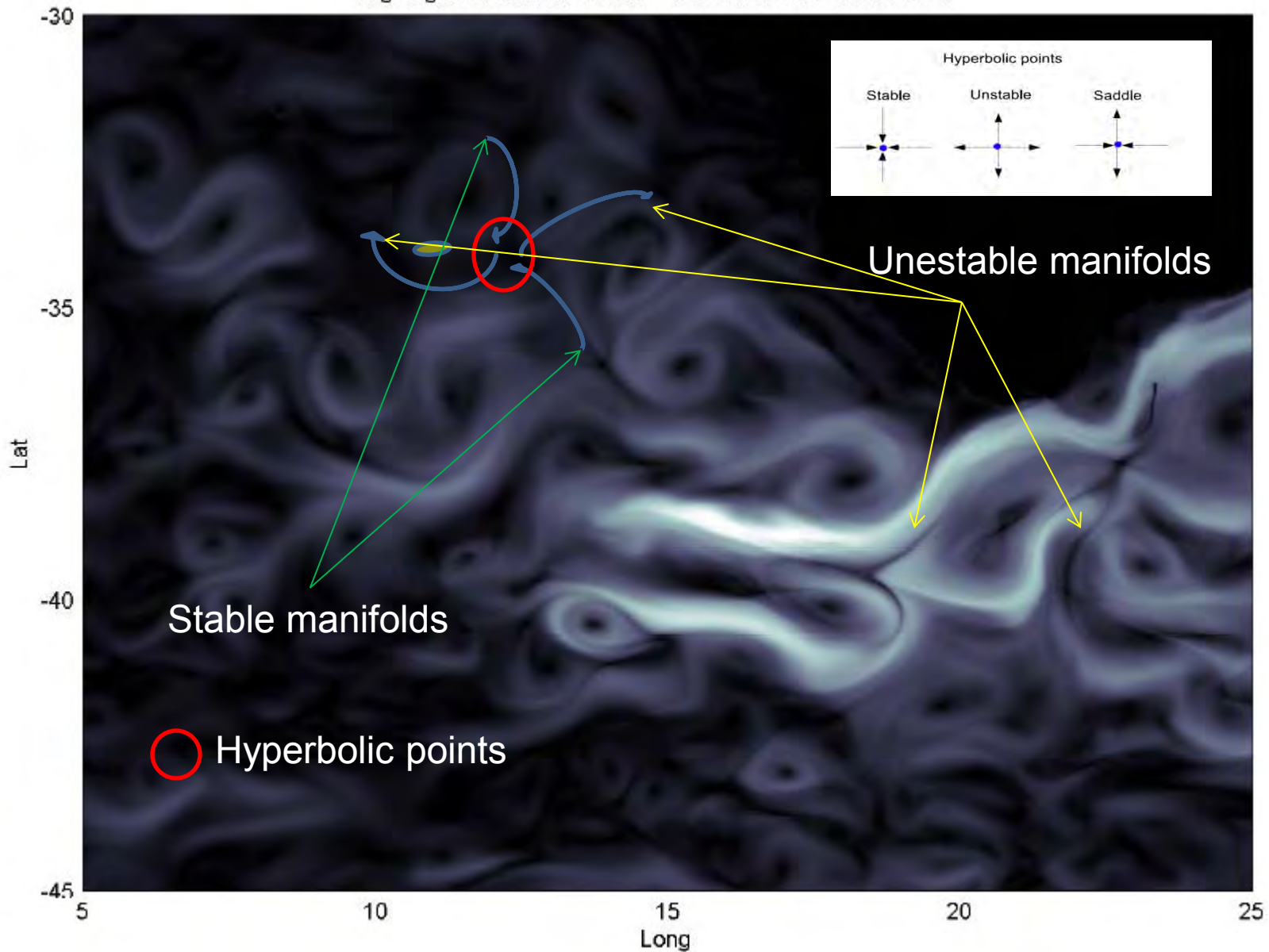
Google earth



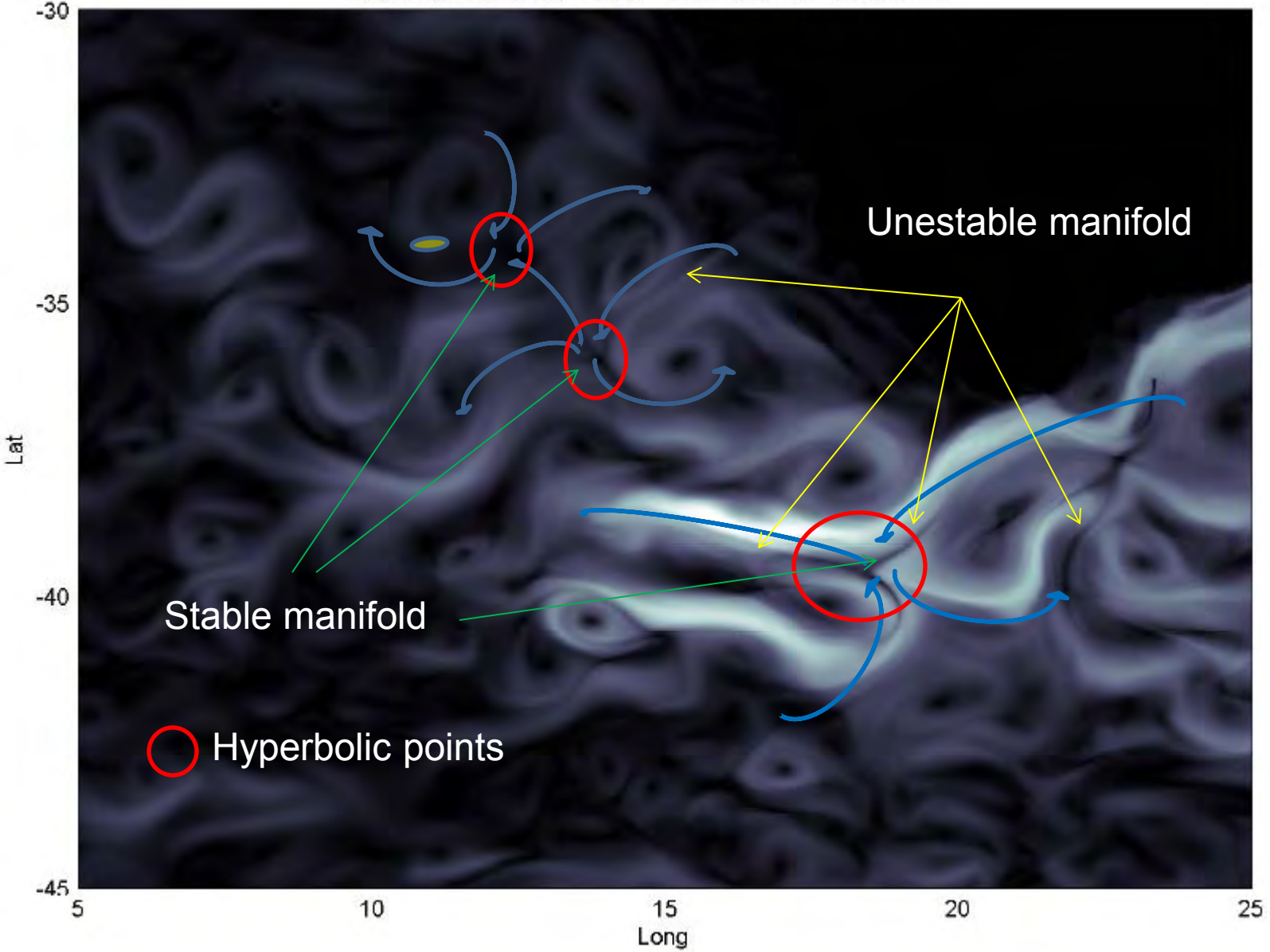
Lagrangian structures for $\tau = 3$ at 5/3/2016 12:00:00 UTC



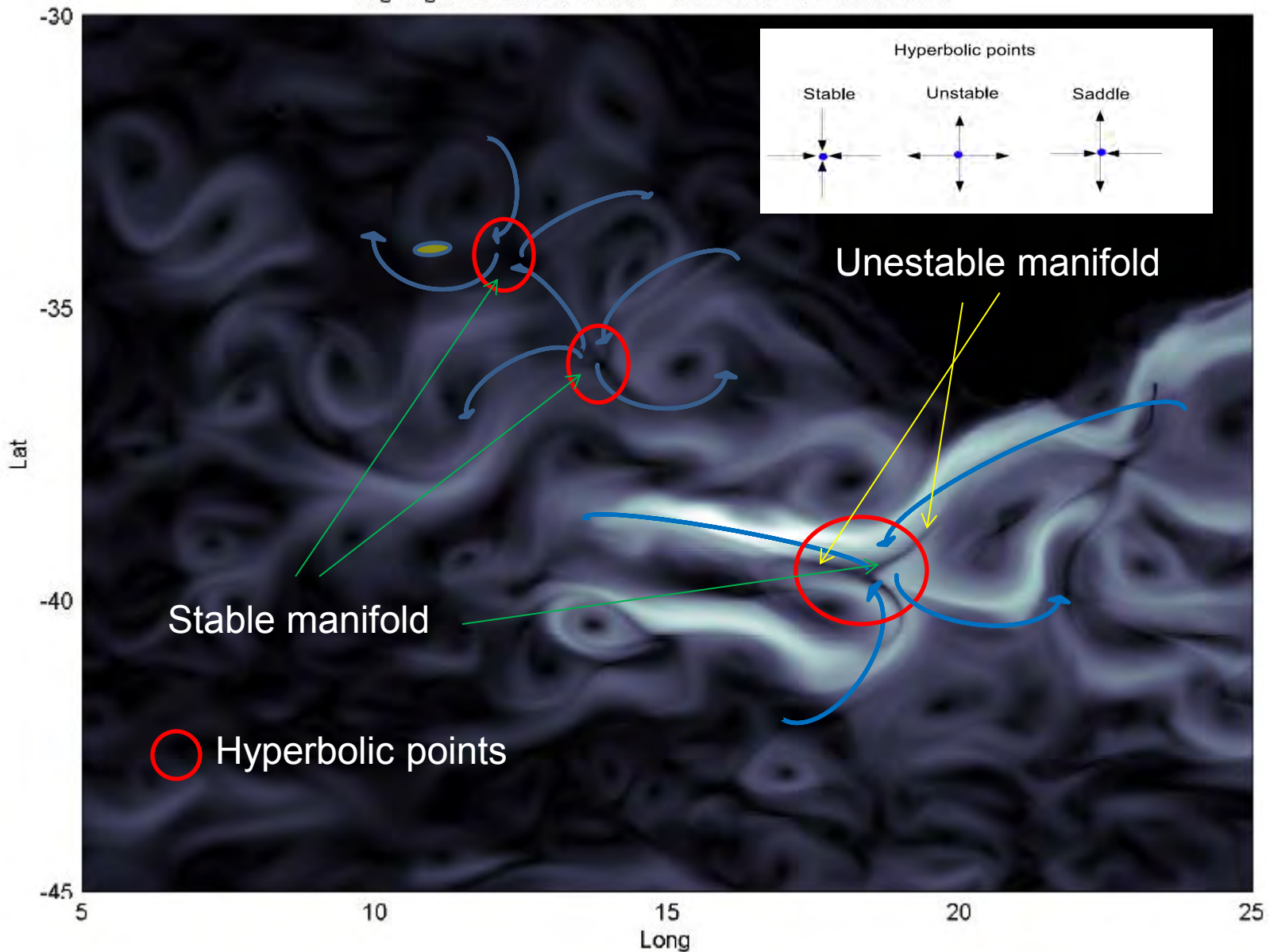
Lagrangian structures for tau = 3 at 5/3/2016 12:00:00 UTC



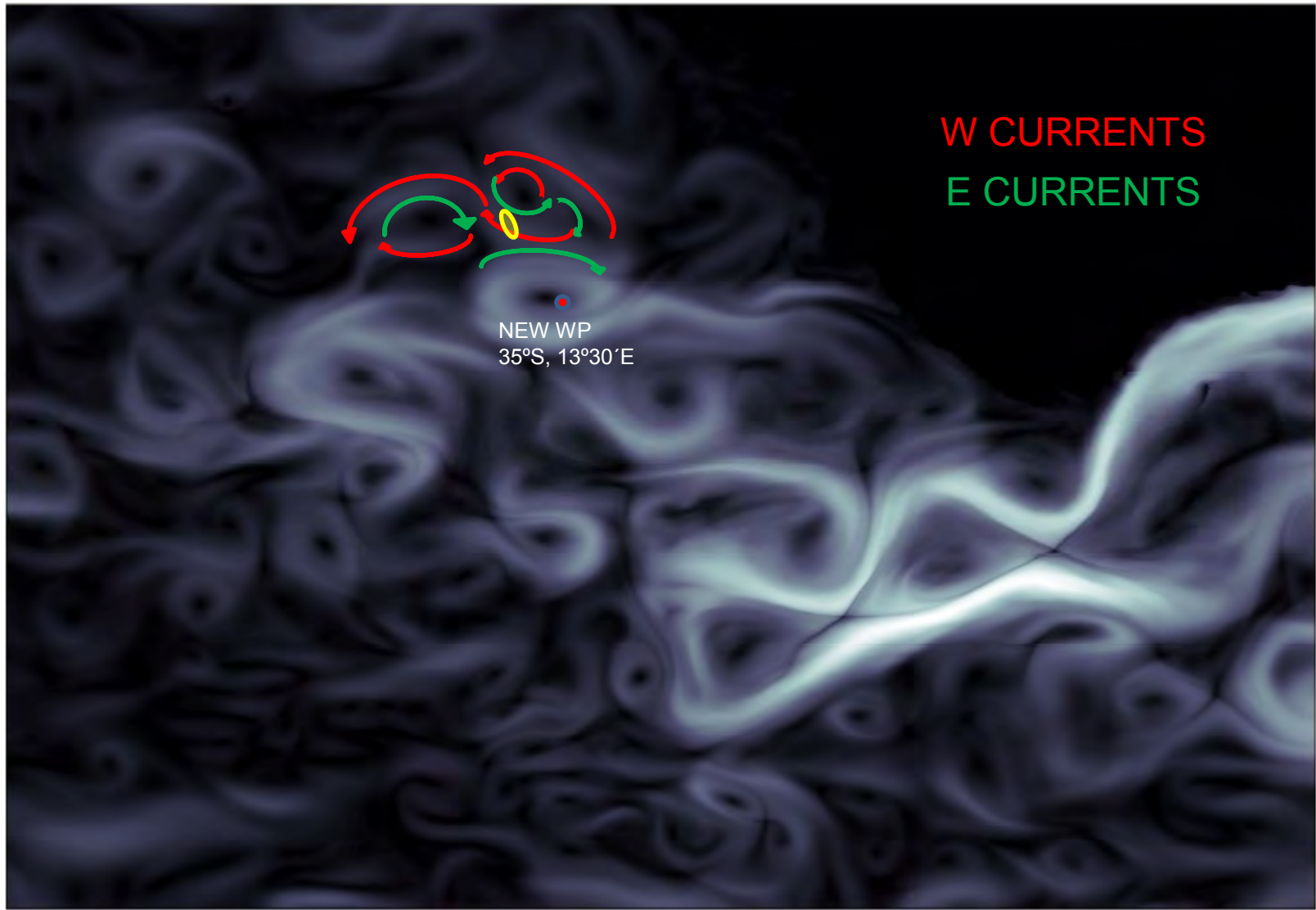
Lagrangian structures for tau = 3 at 5/3/2016 12:00:00 UTC



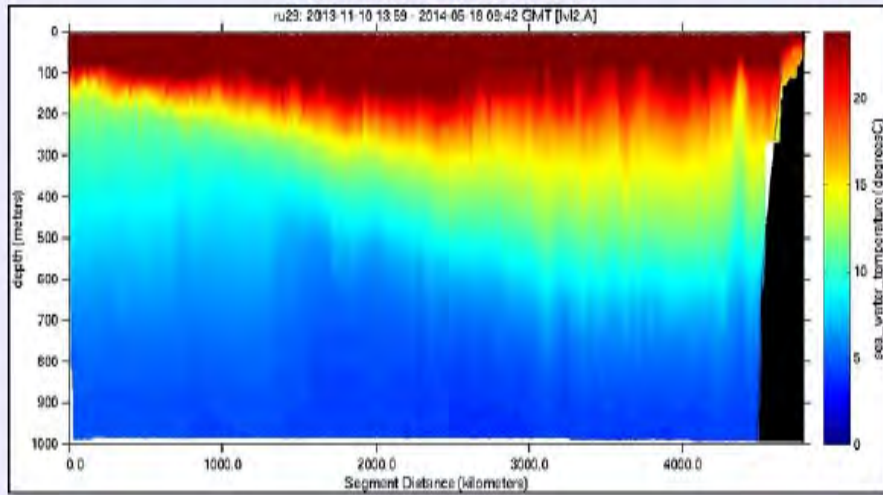
Lagrangian structures for tau = 3 at 5/3/2016 12:00:00 UTC



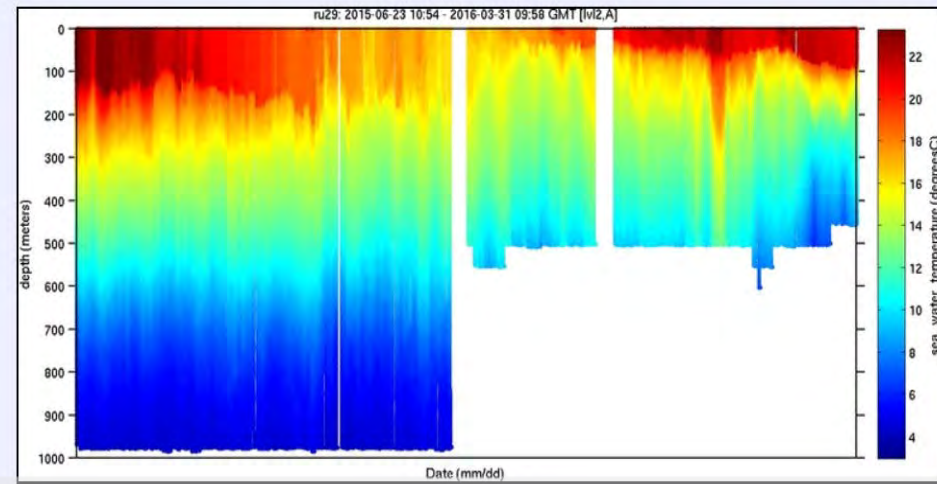
M. LAGRANGIAN FUNCTION 23 MARCH 2016



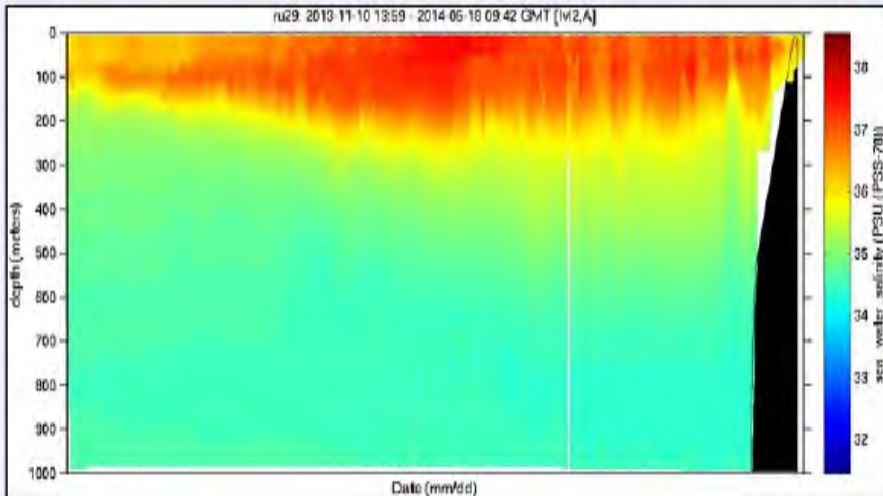
Temperature (°C): 2013-11-10 13:59 - 2014-05-18 09:42 GMT
(Distance Along Track)



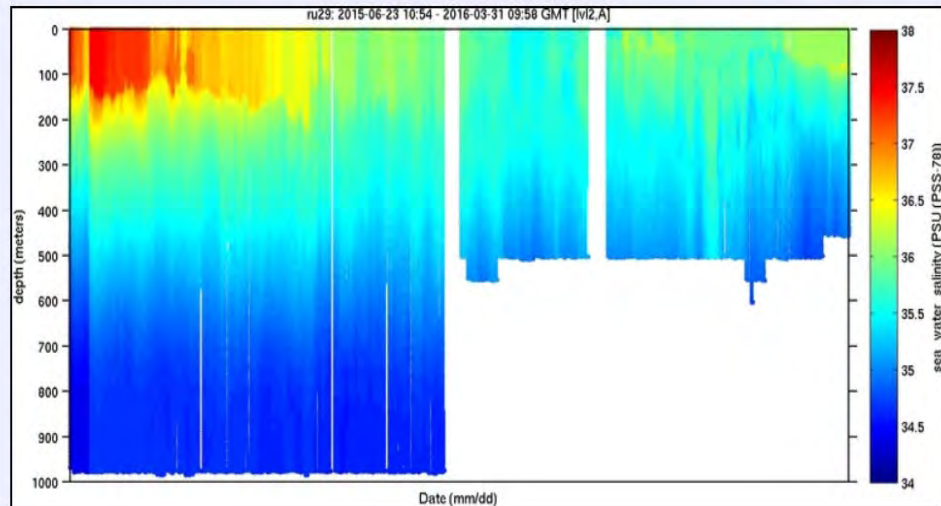
Temperature (°C): 2015-06-23 10:54 - 2016-03-31 09:58 GMT
(Time Series)



Salinity (PSU): 2013-11-10 13:59 - 2014-05-18 09:42 GMT
(Time Series)



Salinity (PSU): 2015-06-23 10:54 - 2016-03-31 09:58 GMT
(Time Series)



TO WEST

TO EAST

>5000 CTD profiles

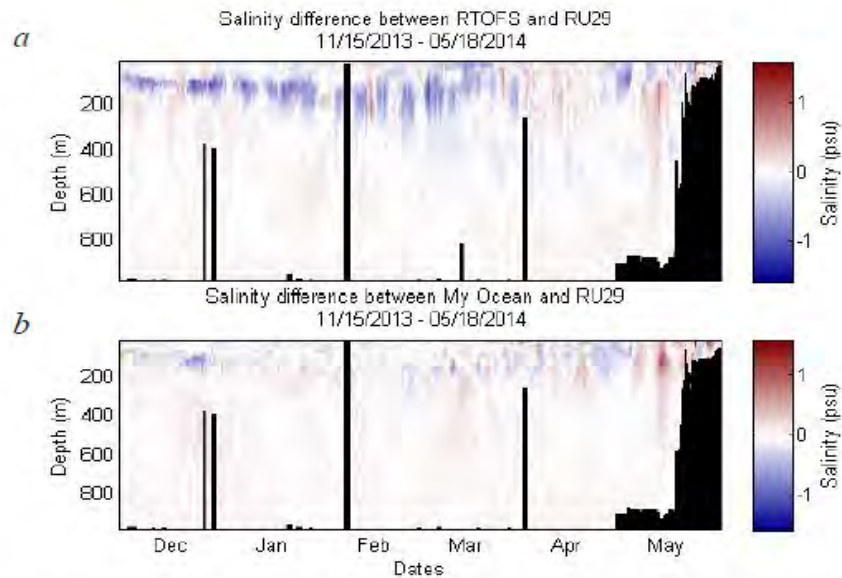


Figure 8: The difference in salinity between the RTOFS model with RU29 (a) and the MyOcean model with RU29 (b).

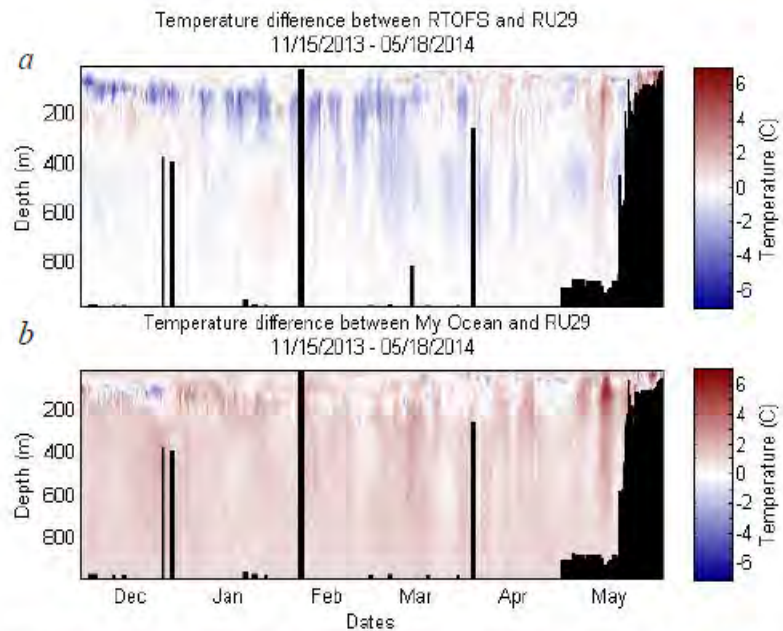


Figure 6: The difference in temperature between the RTOFS model with RU29 (a) and the MyOcean model with RU29 (b).

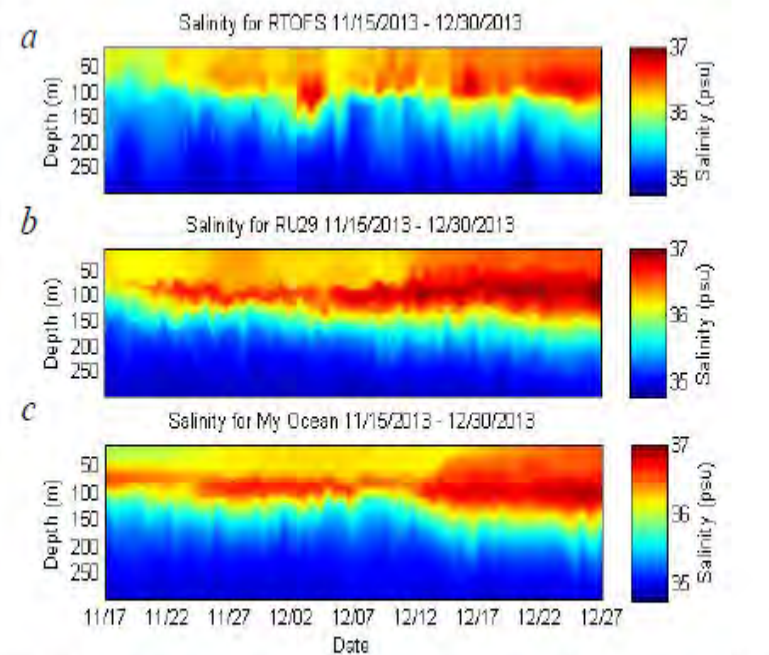
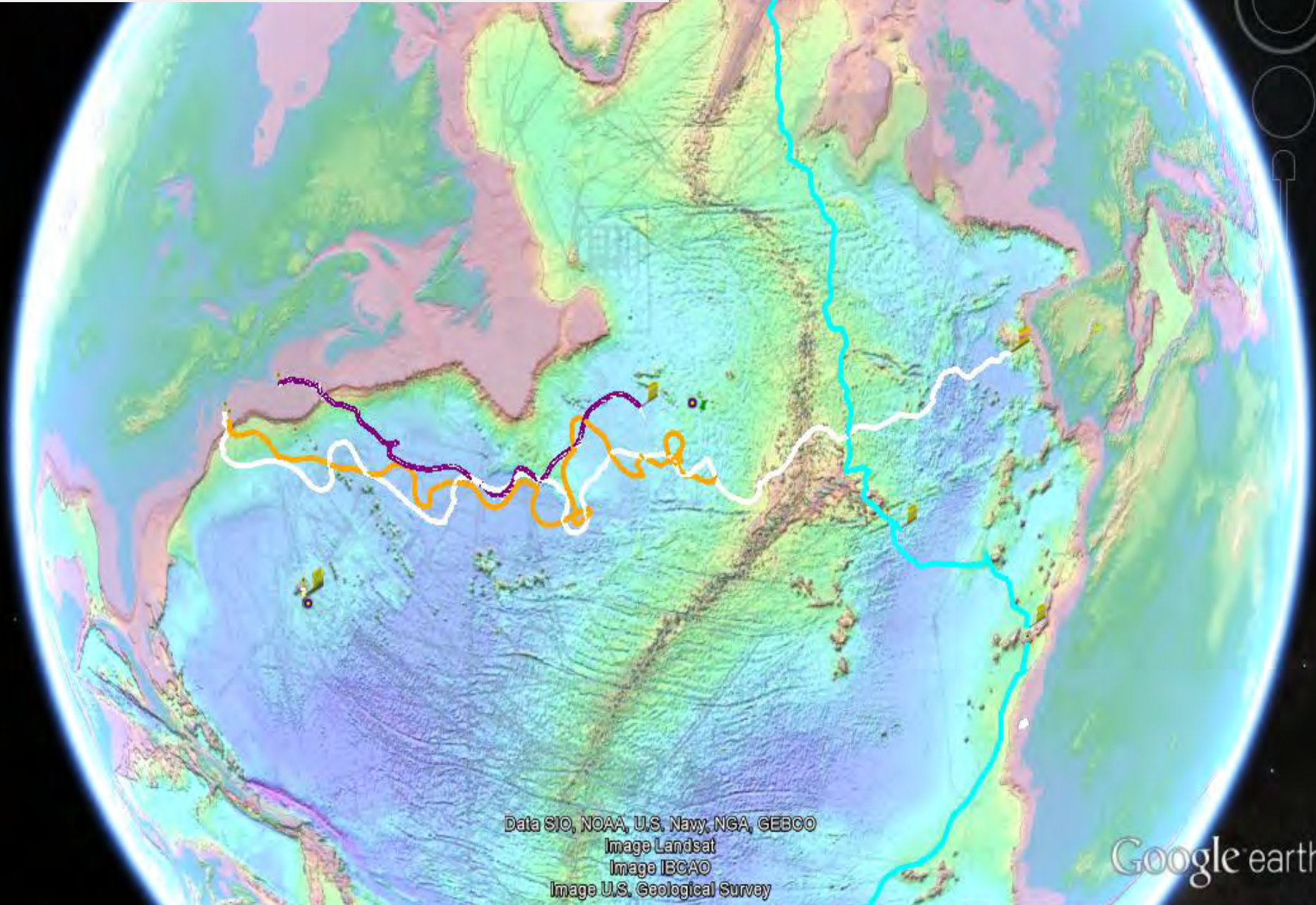


Figure 10: Temperature comparison between RTOFS (a), RU29 (b), and MyOcean (c) for the Turtle Tracks.

SILBO APRIL 2016----

THE NEXT

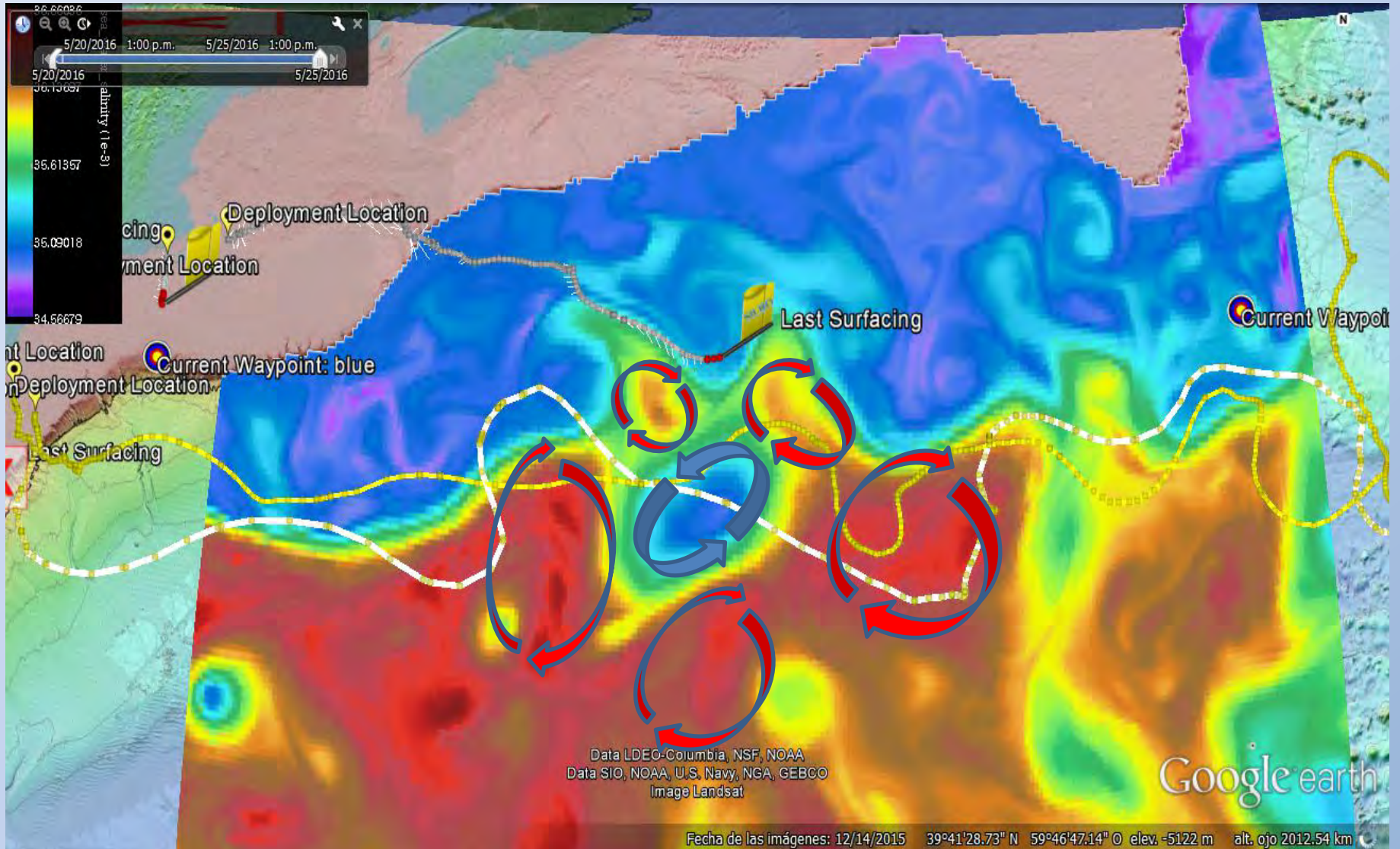


Data SIO, NOAA, U.S. Navy, NGA, GEBCO
Image Landsat
Image IBCAO
Image U.S. Geological Survey

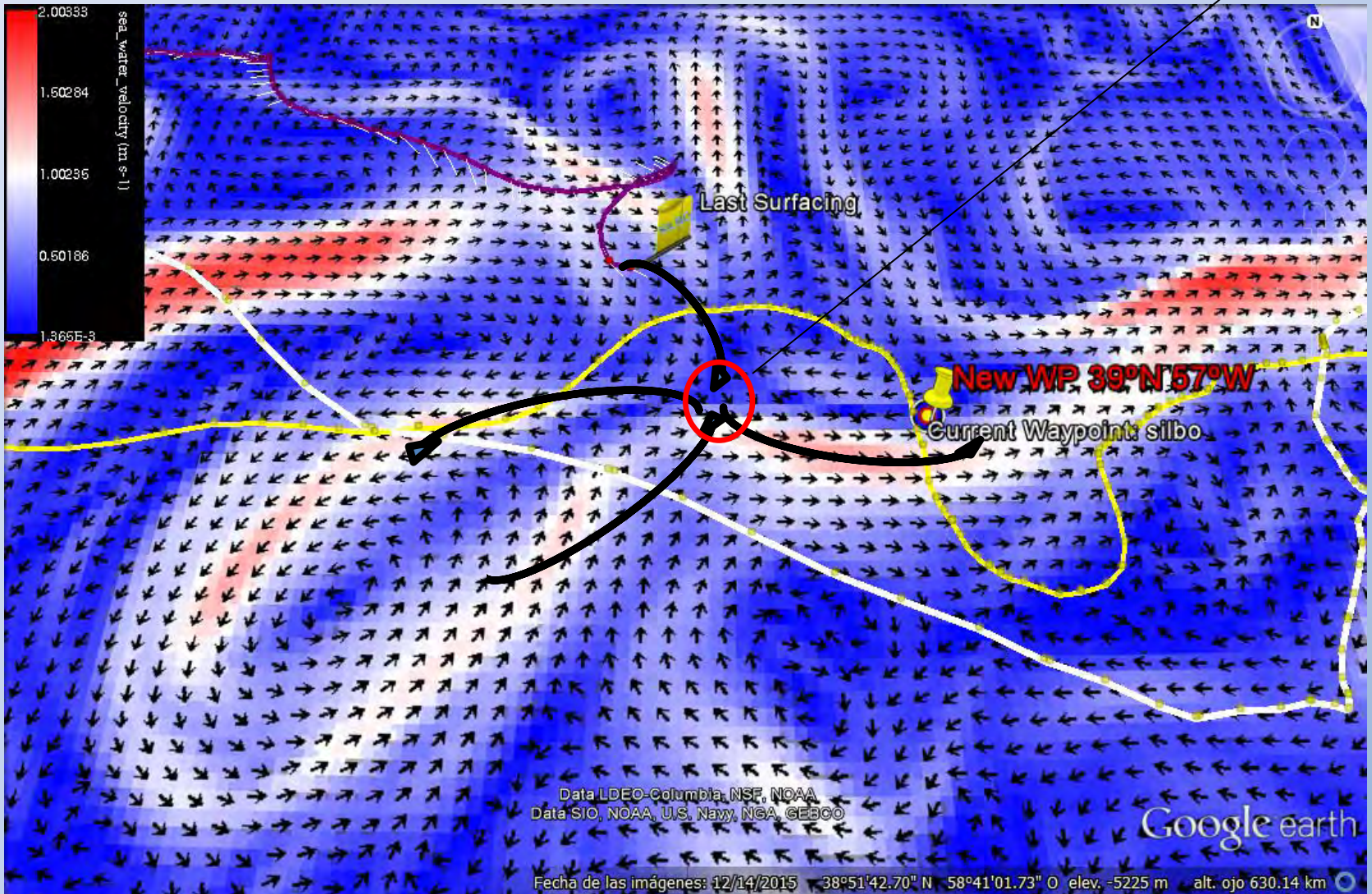
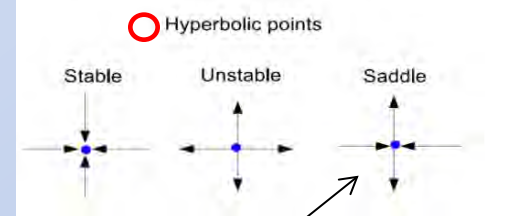
Google earth

Fecha de las imágenes: 12/14/2015 42°13'28.48" N 39°31'51.92" O elev. -4553 m alt. ojo 6937.91 km

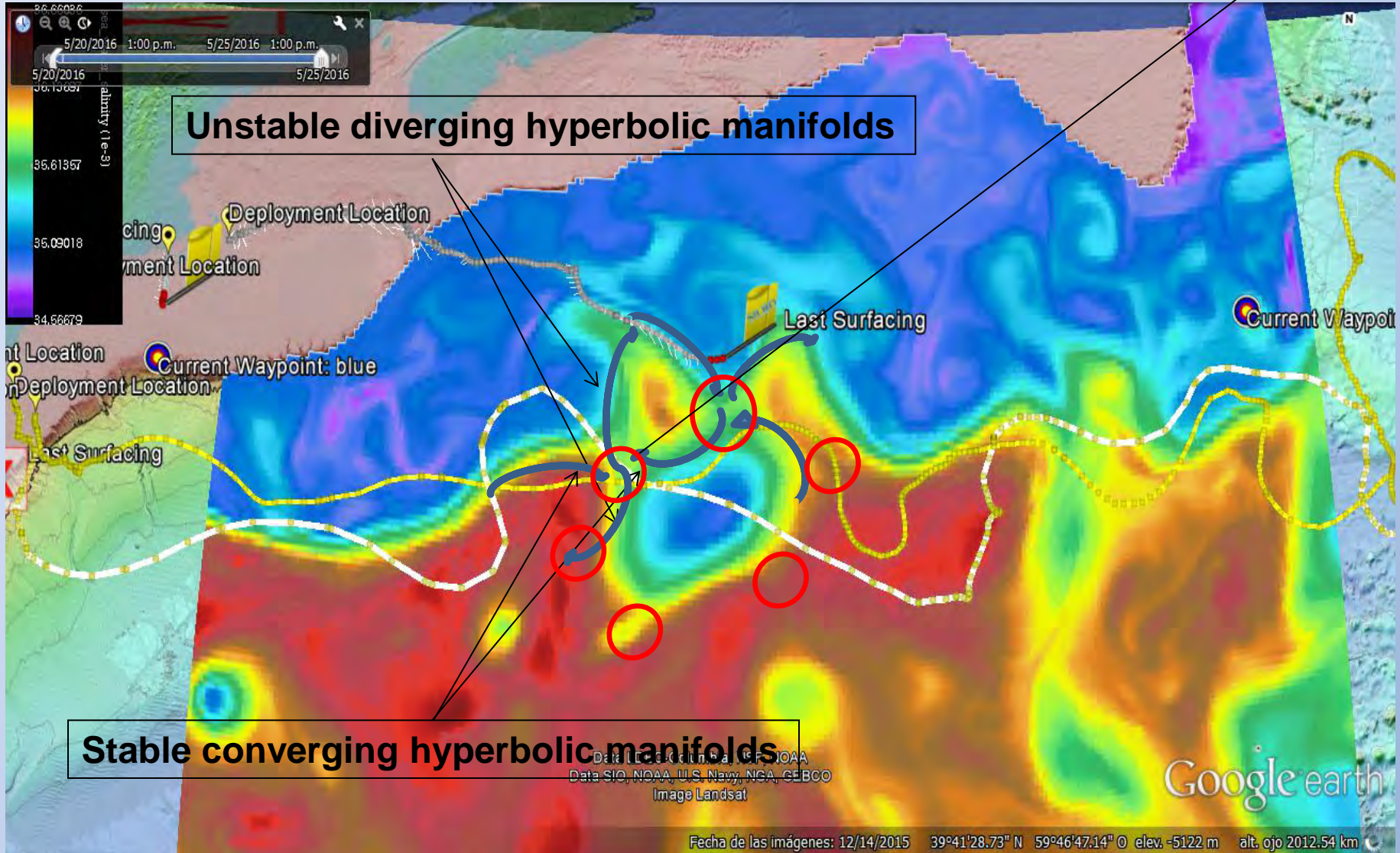
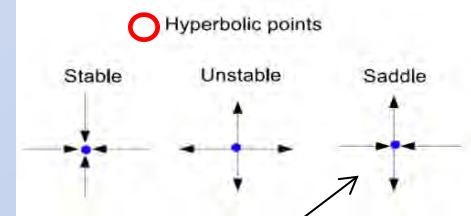
Salinity field COPERNICUS (540m depth). Solar System. 20-25 May 2016.



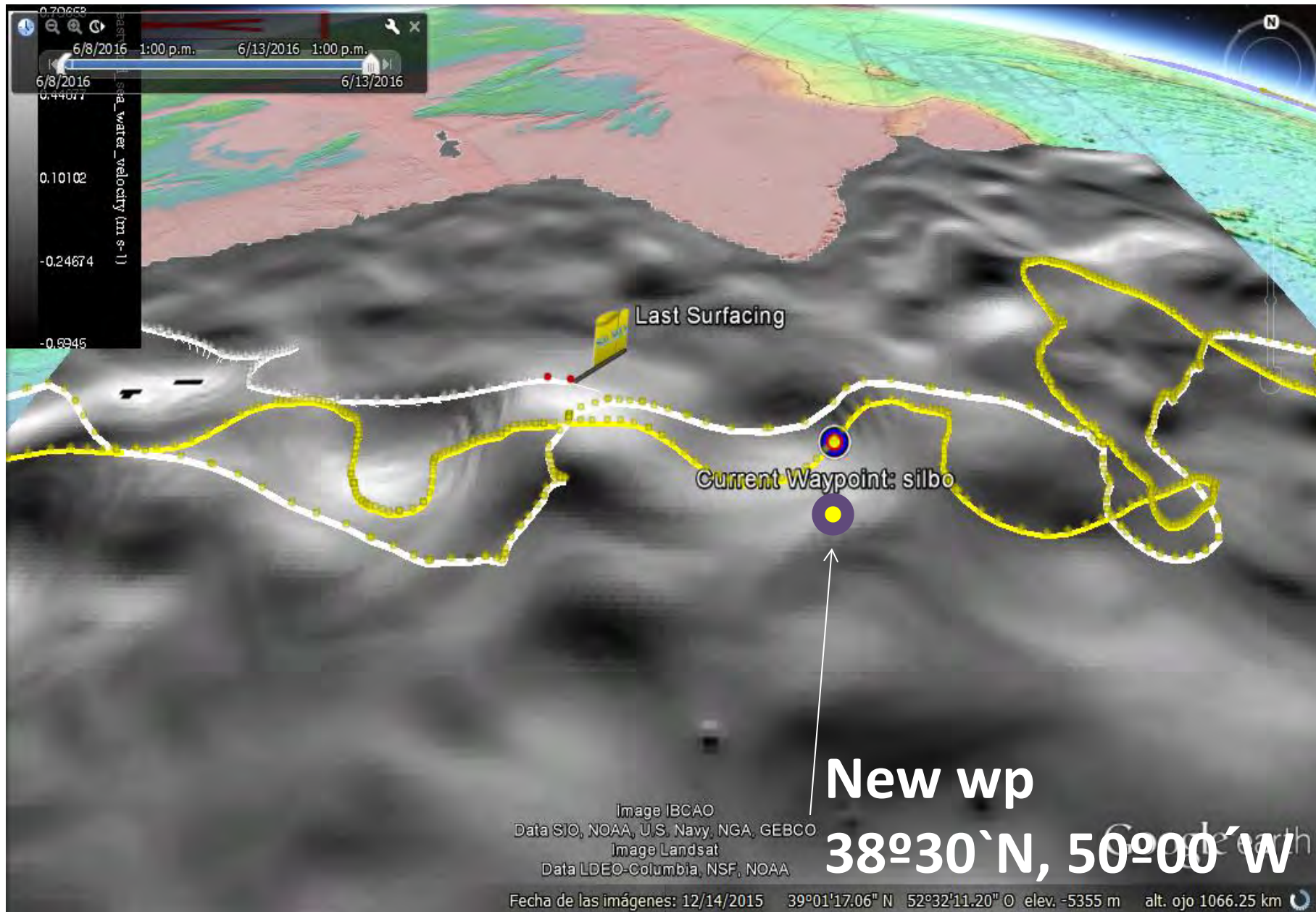
Current field COPERNICUS (0m). Hyperbolic Saddle point. 30 May 2016.



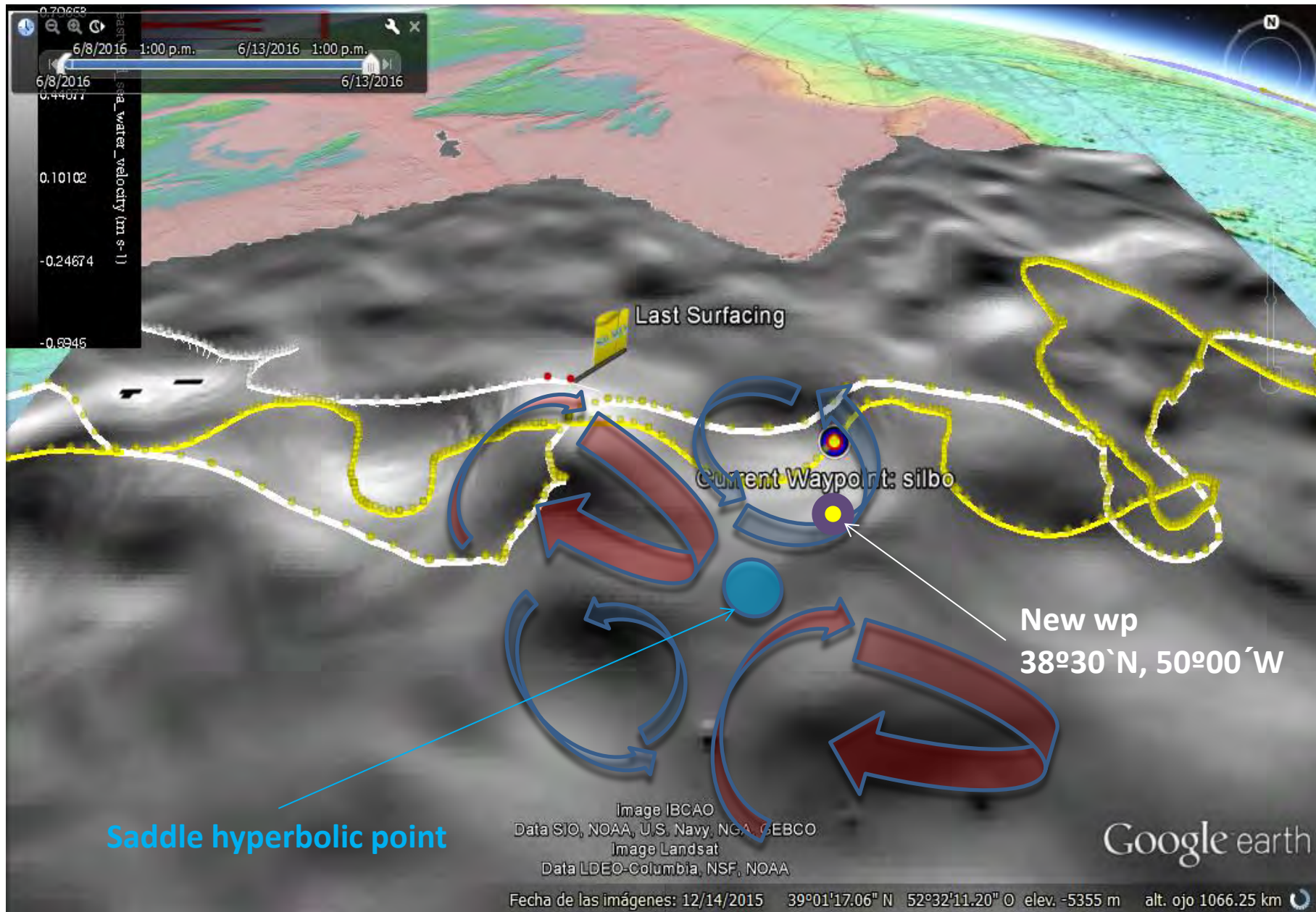
Salinity field COPERNICUS. Hyperbolic points 1-5. 20-25 May 2016.



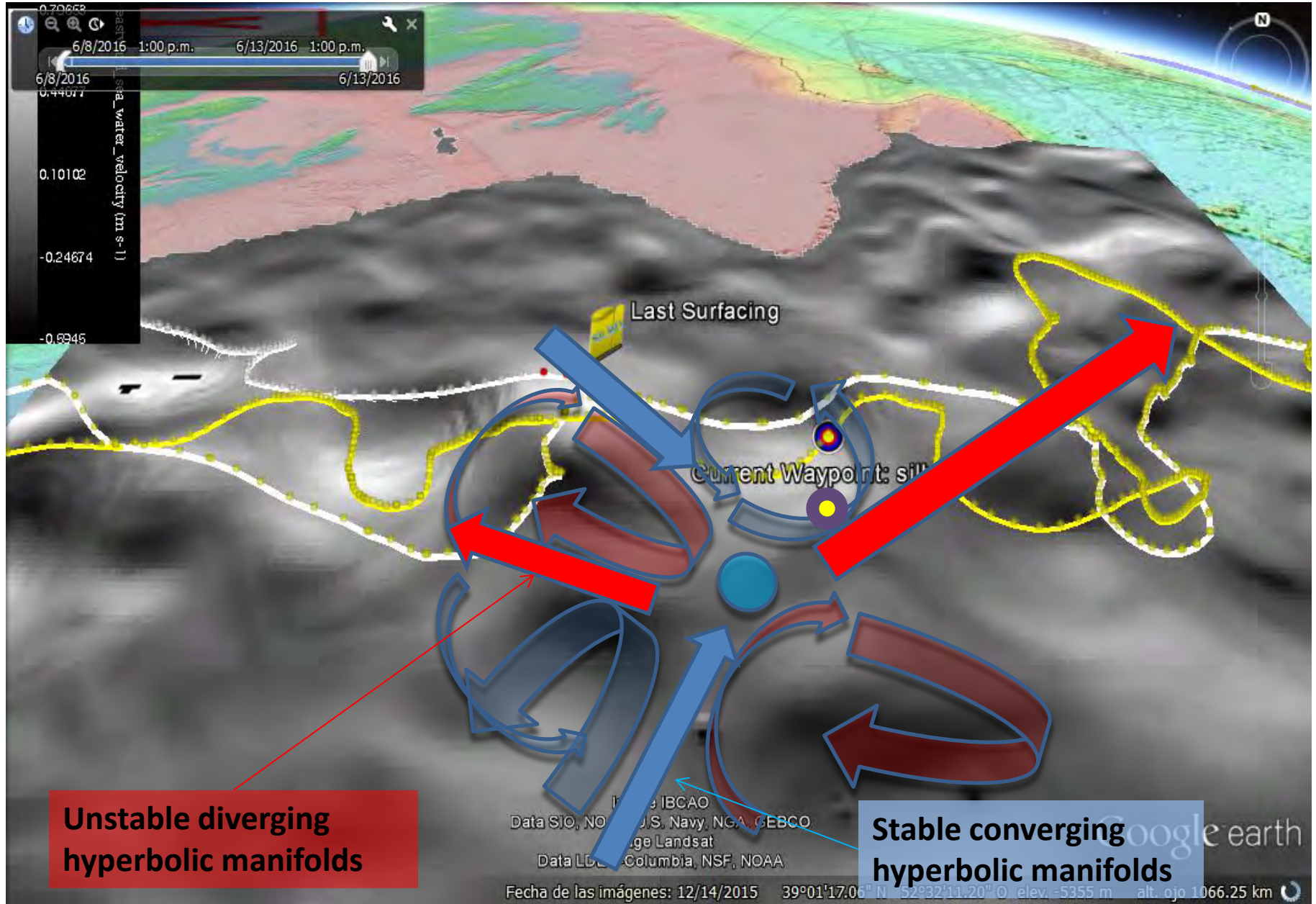
COPERNICUS zonal U current component (z=540m) (8-12 Jun 2016)



COPERNICUS zonal U Current Component (z=540m) (8-12 Jun 2016)



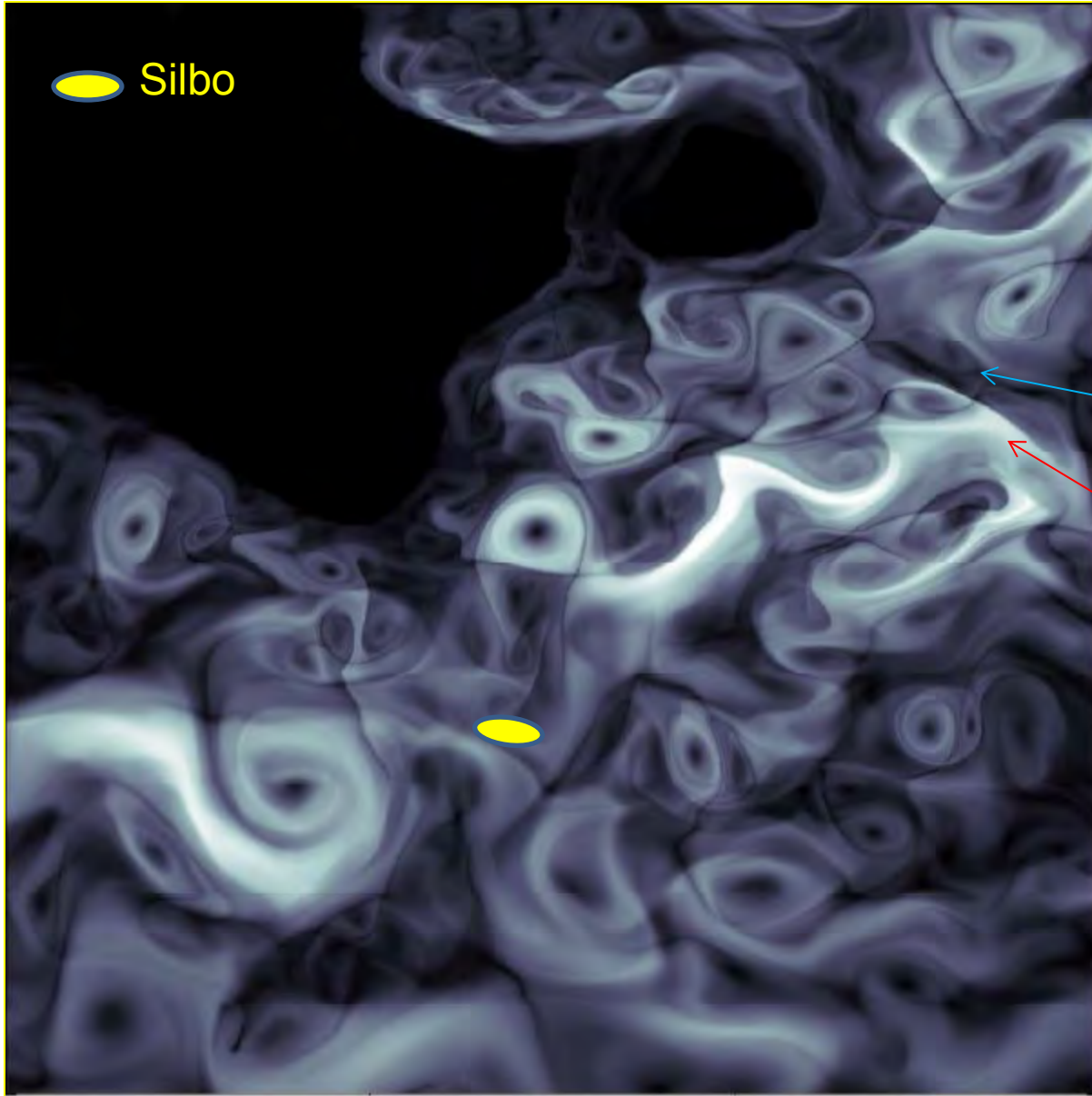
COPERNICUS zonal U Current Component (z=540m) (8-12 Jun 2016)



M Function 450m. Tau 5. 18-22 June 2016.

50N

Silbo



Wall

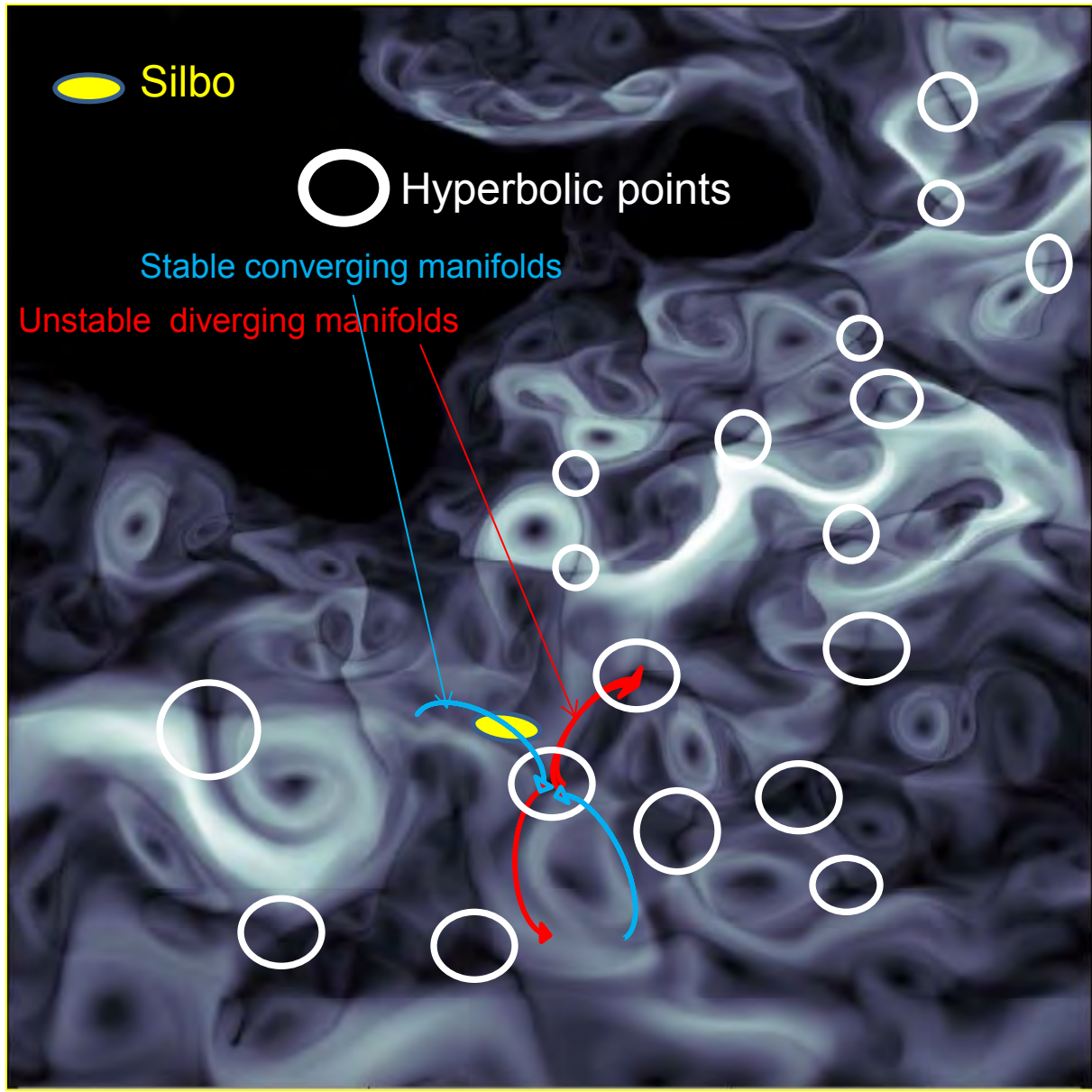
Retroflection

35N

55W

40W

50N



Silbo

Hyperbolic points

Stable converging manifolds

Unstable diverging manifolds

35N

55W

40W



SPEED RECORD : 1 m/s
Usain SIL-BOLT



GPS Acquired	2018-06-14 06:06 GMT
Reason	pitch not commanded
Mission	CCEITM
Filename	silo-2018-107-1-32
0.3 Filename	0038.0032
DSVR Log	silo_network_20180614T060704.log
Segment ENVO	0:07
Mission ENVO	0:21:48
Total FWO	4:20:14.82
Battery	15.222 Volts
Internal Vacuum	3.93 mHg

Dive Time	097.08 minutes
Dive Distance	41.55 km
Total Speed	0.99 m/s @ 34°
Current Speed	0.14 m/s @ 42°
Glide Speed	0.28 m/s @ 12°

Waypoint Location	4222.860N -1311.430W
Range to Waypoint	608.89 km
Bearing to Waypoint	58°

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